

INVESTIGATION AND ANALYSIS OF AN ARBITRARILY
SHAPED DIELECTRIC OBSTACLE IN A RECTANGULAR WAVEGUIDE.

A Thesis

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the Degree of Master of Science in Electrical
Engineering.

by

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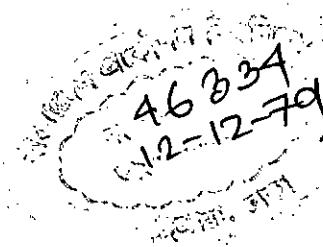
C E R T I F I C A T E

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A B S T R A C T

The development of the dominant mode equivalent circuit parameters for a three-dimensional dielectric obstacle inside a rectangular waveguide requires solution of an integral equation containing a suitable dyadic Green's function. The derivation of the integral equation involves conversion of a two-region scattering problem into two one-region scattering problems by utilizing the linearity property of Maxwell's curl equations. The point matching moment method with a pulse function type subsectional basis vectors has been used for finding the secondary volume current density at the centres of the small rectangularly shaped cells formed by subdividing the dielectric obstacle. Subsequently values of these secondary current density are used in the mathematical formulations for obtaining the dominant mode equivalent circuit parameters. An illustrative example has been solved using a Fortran IV language program. Some modified methods regarding the solution of the problem have been presented.

C O N T E N T S

	<u>Page No</u>
Bibliography ..	1
Chapter-I. Introduction ..	3
Chapter-II. Formulation of the Problem..	6
Art-1 The Integral Equation Involving the Dyadic Green's Function for a 3-dimen- sional arbitrarily shaped dielectric obstacle in a rectangular waveguide..	6
Art-2. Derivation of Electric Type Dyadic Green's Function $\bar{G}_e(r, r')$, ..	11
Art-3. A modified method of deriving \bar{G}_e ..	24
Appendix-I. On Dyads and Dyadic Green's Function and Radiation Condition. ..	29
Appendix-II. On the Mode Completeness relation ..	34
Chapter-III. Moment Method of Solving the Formulated problem.	37
Art-1. Moment Method.	37
Art-2. Solution of the obstacle Problem by the point-matching method of moment..	41
Art-3(a). Evaluation Formulas for Q_{lq}^{pk} elements with $Z_q \neq Z_l$	49
Art-3(b). Evaluation Formulas for Q_{lq}^{pk} elements with $Z_q = Z_l$	56

Contd....

	<u>Page No.</u>
Art-4(a) A suggested Modified Method of Computing $\frac{pk}{Q_{1q}}$ elements with $Z_q \neq Z_1$	64
Art-4(b) A suggested Modified Method of Computing $\frac{pk}{Q_{1q}}$ with $Z_q \neq Z_1$ and $pk = 23, 32, 31, 13$	71
Appendix-III. On the Poisson's Summation Formula ..	79
Art-5: Solution for field quantities inside the dielectric $[u_o, e(r)]$ in volume V ..	81
Art-6: Solution for the Dominant TE ₁₀ Mode T-Equivalent Circuit Parameters for the dielectric obstacle discontinuity.	82
Appendix-IV Radiation from Current Source in a Waveguide ..	87
Chapter-IV. Determination of Equivalent Circuit Parameters for a three-dimensional dielectric obstacle in a rectangular Waveguide. ..	90
Appendix-V. Computer Program ..	107
Chapter-V. A Suggested Modified Moment Method ..	121
Chapter-VI. Conclusion. ..	125

CHAPTER-I

INTRODUCTION

On the analysis of an arbitrarily shaped dielectric obstacle in a rectangular waveguide.

The effects of obstacles and discontinuities on electromagnetic fields in a waveguide have been outstanding problems for a long time. Many of them, essentially two-dimensional, have been solved and were summarized by Marcuvitz (1). The general three-dimensional obstacle-discontinuity problem has remained virtually unsolved inspite of the advent of high speed digital computers and the method of moment, introduced in E.M. Field theory by Harrington (2), which permits dealing with problems not solvable by exact method.

The lack of published research activities on three-dimensional waveguide discontinuities has been mainly due to non-availability of Green's Functions in the waveguide region. A dyadic Green's function for rectangular waveguides based on the use of eigenvector functions M and N was presented by Tai(3) and it was later revised by the same author (4). Collin (5) has discussed the question of incompleteness of the E and H modes in the source region of a waveguide and has shown that an additional term must be added to the classical representation of the E.M. field in order to derive a complete solution that is valid both in the source and source free region. Sami (6) has

recently presented a method of deriving the Dyadic Green's Function for rectangular waveguides and cavities using the theory of distribution and has shown that if one carefully defines the derivatives in the distribution sense and applies the correct completeness property of the modes, it is then possible to construct the complete solution of the entire structure just by employing the scalar eigenfunctions of Helmholtz equation and has pointed out that this procedure may also be used to determine the complete form of the Dyadic Green's Functions for non-rectangular waveguides and cavities.

Recently Wang (7) has presented a method of analyzing a three-dimensional dielectric obstacle in a rectangular waveguide by applying moment method to an integral equation involving Dyadic Green's function and has pointed out that this technique could be extended to ferromagnetic obstacles and for highly conductive obstacles a surface type Green's Function may be more desirable.

The purpose of this Thesis work is to develop a method for finding the dominant mode equivalent circuit parameters for a dielectric obstacle discontinuity inside a rectangular waveguide. The method involves solution of an integral equation involving a dyadic Green's function by moment method for obtaining the secondary current induced in the dielectric obstacle and subsequent use of these induced secondary current values to find the dominant mode equivalent circuit parameters.

The method can be extended for finding the "multimode" equivalent circuit parameter matrix. However, it should be noted that waveguides operate usually in a narrow band near the dominant mode and dominant mode equivalent circuit is the most usual representation for a discontinuity in a waveguide.

In course of this investigation a modified method of deriving the dyadic Green's function for a dielectric obstacle in a rectangular waveguide has been developed. A modified method of summing the double infinite series for evaluating the elements of the matrix resulting from the matrization of the relevant dyadic integral equation by moment method has also been suggested. A modified method of moment for solving the problem has also been presented.

CHAPTER-II.

FORMULATION OF THE PROBLEM.

Art-1: The Integral Equation involving the Dyadic Green's Function for a 3-dimensional arbitrarily shaped dielectric obstacle in a rectangular waveguide.

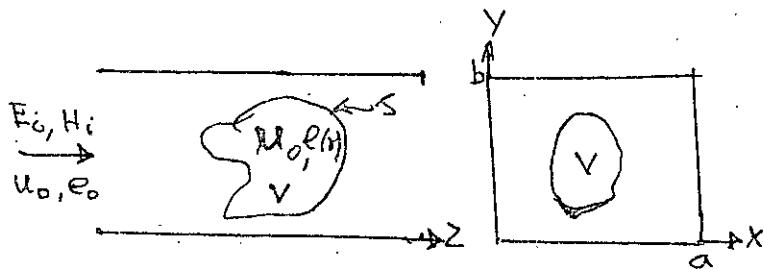


Fig-1. A 3-dimensional arbitrarily shaped dielectric body illuminated with incident field E_i, H_i (with propagation factor e^{jwt} implicit) travelling toward $+z$ direction.

The problem to be considered is depicted in Fig. 1. A three-dimensional arbitrarily shaped heterogeneous body of volume V enclosed by surface S is illuminated with electromagnetic field E_i, H_i incident towards $+z$ direction. At any position vector \mathbf{r} , the obstacle body has permittivity $\epsilon(\mathbf{r})$ and permeability μ_0 . Outside V the medium is homogeneous with permittivity ϵ_0 and permeability μ_0 .

The object occupying the volume V may be regarded as disturbing or scattering the field that would exist if the object were not present, that is, if all the space had the properties: admittivity $Y_0 = j\omega\epsilon_0$, and impedivity $Z_0 = j\omega\mu_0$.

With the scattering object present the total fields E & H satisfy Maxwell's equations in the form:

Outside V

$$\begin{aligned} \nabla \times H &= Y_o E + J_o \\ \nabla \times E &= -Z_o H \end{aligned} \quad | \quad (1)$$

Inside V

$$\begin{aligned} \nabla \times H &= Y_1 E = Y_o E + J \\ \nabla \times E &= Z_o H = -Z_o H \end{aligned} \quad | \quad (2)$$

where J_o is the impressed source outside V, and $J = (Y_1 - Y_o)E$,

wherein $Y_1 = j\omega e(r)$, is the induced source throughout V.

$Y_1 = j\omega e(r)$ and $Z_o = j\omega u_o$ are the admittivity & impedivity, respectively, of the dielectric in V. Since Equations (1) & (2) are of the same form they may be written together, and applied to all space both inside and outside V, as follows:-

$$\nabla \times H = Y_o E + J_o + J \quad | \quad (3)$$

$$\nabla \times E = -Z_o H \quad | \quad \text{by the above given definition}$$

The linearity of Maxwell's equations can be utilized in simplifying solving the scattering problem under consideration. The main consequence of adopting Equation (1), (2) & (3) is that the medium scattering problem has been replaced with a problem involving point sources in homogeneous dielectric media. The total field quantities E and H may be broken into components whose equations are:-

In a medium with μ_i, ϵ_i , we have $\nabla \times H_i = Y_1 E_i - J$

$$\begin{aligned} \nabla \times H_i &= Y_1 E_i + J_o - J \\ \nabla \times E_i &= -Z_o H_i \end{aligned} \quad | \quad (4)$$

$$\nabla \times E_i = -Z_o H_i$$

In a medium with u_o, e_o

$$VXH_s = Y_o E_s + J \quad (5a)$$

$$VXE_s = -Z_o H_s \quad (5b)$$

Combining Eqns(4) & (5),

$$\begin{aligned} VX(H_i + H_s) &= Y_o(E_i + E_s) + J_o \\ VX(E_i + E_s) &= -Z_o(H_i + H_s) \end{aligned} \quad | \quad (8)$$

In a medium with $u_o, e(r)$

$$VXH_s = Y_1 E_s + J \quad (7a)$$

$$VXE_s = -Z_1 H_s \quad (7b)$$

Combining Eqns(6) & (7),

$$\begin{aligned} VX(H_i + H_s) &= Y_1(E_i + E_s) \\ VX(E_i + E_s) &= -Z_1(H_i + H_s) \end{aligned} \quad | \quad (9)$$

Comparing Equation(1) with(8) and Equation(2) with (9)

We find:-

$E = (E_i + E_s)$, $H = (H_i + H_s)$ relations are applicable both inside and outside the dielectric obstacle in V. The advantage of decomposing E and H in this way is that the two-region problem is now tackled by two homogenous-medium problems with E_s and H_s obtainable by solving similar equations whose Green's functions take into account guide boundary and J distribution conditions.

Taking curl of Eqn(5b) and then using Eqn(5a), we have,

$$VXVXE_s - K_o^2 E_s = -jw u_o J \quad (10)$$

$$\text{where } K_o^2 = w u_o e_o$$

Using electric type of Dyadic Green's function(to be derived)

$$\bar{G}_e(r, r') = \bar{G}_{e_o}(r, r') - \frac{\bar{z}\bar{z}d(r-r')}{K_o^2} \dots \quad (11)$$

where $d(r-r')$ is the Dirac delta function.
Solution of Equation(10) is given by using Green's theorem or superposition principle:-

$$E_s(r) = -jw u_o \int \bar{G}_e(r, r') \cdot J(r') dv' \dots \quad (12)$$

where \mathbf{r} is the position vector, \mathbf{r}' and $d\mathbf{v}'$ refer to the region in V .

Using Eqns(11) and (12) in the relation $E_i + E_s = E$ and using the relation $J = jw [e(r) - e_0] E$ we have,

$$-jwu_o \int_V \bar{G}e_o(\mathbf{r}, \mathbf{r}') \cdot J(\mathbf{r}') d\mathbf{v}' - \frac{J(\mathbf{r})}{jw(e(r) - e_0)} - \frac{J_z(r)\bar{z}}{jwe(r)} = -E_i(r) \dots (13).$$

where $J_z = J \cdot \bar{z}$

Taking curl of Equation (7b) and then using (7a) we have,

$$\nabla \times V \times E_s - K^2(r) E_s = -jwu_o J \dots \dots \dots (14).$$

where $K^2(r) = w^2 u_o e(r)$

In an analogous manner the Dyadic Green's function

$$\bar{G}e'(\mathbf{r}, \mathbf{r}') = \bar{G}e_o(\mathbf{r}, \mathbf{r}') - \frac{\bar{z} \bar{z} d(r-r')}{K^2(r)} \dots \dots \dots (15).$$

may be derived.

The solution to Equation (14) is given by using Green's Theorem or Superposition principle :-

$$E_s(r) = -jwu_o \int_V \bar{G}e'(r, r') \cdot J(r') d\mathbf{v}' \dots \dots \dots (16).$$

where \mathbf{r} is the position vector, \mathbf{r}' and $d\mathbf{v}'$ refer to the region in V .

Using Equation(15) and (16) in the relation $E_i + E_s = E$ and using the relation $J = jw [e(r) - e_0] E$ we have,

$$-jwu_o \int_V \bar{G}e_o(\mathbf{r}, \mathbf{r}') \cdot J(\mathbf{r}') d\mathbf{v}' - \frac{J(\mathbf{r})}{jw(e(r) - e_0)} - \frac{J_z(r)\bar{z}}{jwe(r)} = -E_i(r) \dots (17).$$

where $J_z = J \cdot \bar{z}$

Equation (17) is the integral equation to be solved for $J(r)$ by moment method for given $E_i(r)$.

Equation (17) is the integral Equation to be solved for $J(r)$ by moment method for given $\tilde{E}_s(r)$.

In the next article $\tilde{G}_e(r,r')$ for a rectangular waveguide filled homogeneously with medium (ϵ_0 , μ_0) and with current density distribution $J = jw(\epsilon(r)-\epsilon_0)E$ in volume V is derived.

Art-2: Derivation of Electric Type Dyadic Green's Function
=
Ge(r,r'):

In deriving an expression for $\tilde{G}e(r,r')$ we follow the procedure of Sami (6). The geometry of the problem is as shown in Fig.1. The waveguide with its dimensions a and b along x and y axes respectively and aligned along z -axis, is assumed to be of a perfect conductor and is excited by an electric current density distribution J contained in finite volume V .

The Maxwell's curl equations for the scattered field and the relevant boundary conditions are :-

$$\begin{aligned} \nabla \times H_s &= J + j\omega \epsilon_0 E_s && \text{in the} \\ \nabla \times E_s &= -j\omega \mu_0 H_s && \text{waveguide.} \end{aligned} \quad .. \quad (1a)$$

$$\hat{n} \times E_s = 0 \quad \text{On the wall} \quad .. \quad (1b)$$

where \hat{n} is an unit vector normal to the guide walls.

As already outlined this is equivalent to assuming the waveguide filled with a homogeneous isotropic medium with parameters ϵ_0 , μ_0 and representing the scattering effect of the dielectric with $\epsilon(r)$, μ_0 in V by a current density distribution $J = j\omega(\epsilon(r) - \epsilon_0)E$ wherein $E = E_i + E_s$.

In order to obtain the unique solution, the field components must also satisfy the Sommerfeld radiation condition along the \hat{x} z-axis:-

$$\lim_{Z \rightarrow \infty} z \left(\nabla \times \left(\frac{E}{H} \right) \pm jk_0 \hat{z} \left(\frac{E}{H} \right) \right) = 0. \quad (\text{For a matched condition}).$$

for either E (with H absent) or H (with E absent) and $k_0^2 = \omega^2 \mu_0 \epsilon_0$.

Using this and the Green's vector theorem identity we may have, $E_s = -j\omega \mu_0 \int_{V'} \bar{G}_e(r, r') \cdot J(r') dv' ..$ (2).

The Maxwell dot equation yields $\nabla \cdot H = 0$ in the waveguide (3a)

The relevant boundary condition is $\bar{n} \cdot H = 0$ on the wall (3b)

From the Curl equations: $-\nabla \times V X V X E_s - k_o^2 E_s = -j\omega \mu_0 J$ (4a)

The relevant boundary condition is $\bar{n} \times E_s = 0$ (4b)

Also from the curl equation: $-\nabla \times V X V X H_s - k_o^2 H_s = \nabla \times J$ (5a)

The relevant boundary conditions are $\bar{n} \cdot H_s = 0$ | on the
 $\bar{n} \times V X V X H_s = 0$ | wall (5b)

In order to solve Equation (4) we introduce the electric type dyadic Green's function $\bar{G}_e(r, r')$ defined by

$$V X V X \bar{G}_e = -k_o^2 \bar{G}_e = \bar{I} d(r-r') \text{ in the guide} .. (5c)$$

$$\bar{n} \times \bar{G}_e = 0 \text{ on the wall.} .. (5d)$$

where unit dyadic function $\bar{I} = \bar{x}\bar{x} + \bar{y}\bar{y} + \bar{z}\bar{z}$.

$\bar{G}_e(r, r')$ is the response at r due to a concentrated current density $\bar{d}(r-r')$ at r' .

The magnetic dyadic Green's function $\bar{G}_m(r, r')$ corresponding to Eqns (5a) and (5b) is defined by :-

$$V X V X \bar{G}_m = -k_o^2 \bar{G}_m = \nabla \times \bar{I} d(r-r') \text{ in the guide} .. (6a)$$

$$\begin{aligned} \bar{n} \cdot \bar{G}_m &= 0 && \text{on the wall} \\ \bar{n} \times V X V X \bar{G}_m &= 0 \end{aligned} .. (6b)$$

$\bar{G}_m(r, r')$ is the response at r due to a concentrated current density $\bar{d}(r-r')$ at r' .

Eqn(6) may be rewritten as follows:-(Using $V X V = V V \cdot -V^2$)

$$(V^2 + k_o^2) \bar{G}_m = -V X \bar{I} d(r-r') .. (7a)$$

$$\begin{aligned} \bar{n} \cdot \bar{G}_m &= 0 && \text{on the wall} \\ \bar{n} \times V X V X \bar{G}_m &= 0 \end{aligned} .. (7b)$$

To facilitate solving Eqn(7) another Green's function

$\tilde{g}_m(r, r'')$ defined as follows is introduced:

$$(V^2 + k_o^2) \tilde{g}_m = -\tilde{I} d(r-r'') \quad \dots \quad (8a)$$

$$\begin{aligned} \tilde{n} \cdot \tilde{g}_m &= 0 && \text{on the wall} \\ \tilde{n} X V X \tilde{g}_m &= 0 \end{aligned} \quad \dots \quad (8b)$$

Applying Green's vector theorem identity we have,

$$\tilde{G}_m(r, r') = \int \tilde{g}_m(r, r''), V X \tilde{I} d(r''-r'') dv'' \quad \dots \quad (9)$$

where ∇''_X implies cut operation with respect to r'' . [Ref. Page 33]

It is to be noted that from Eqn(1a) we may obtain

the following equation relating \tilde{G}_e and \tilde{G}_m

$$k_o^2 \tilde{G}_e = V X \tilde{G}_m - \tilde{I} d(r-r') \quad \dots \quad (10)$$

Eqn(10) is arrived at as follows:-

$$\text{From (4a) when } J \overset{=}{\Rightarrow} \tilde{I} d(r-r'), \frac{E_s}{jw u_o} \overset{=}{\Rightarrow} \tilde{G}_e$$

$$\text{From (5a) when } J \overset{=}{\Rightarrow} \tilde{I} d(r-r'') \overset{=}{\Rightarrow} G_m$$

Thus putting $J \overset{=}{\Rightarrow} \tilde{I} d(r-r')$, $E_s \overset{=}{\Rightarrow} -jw u_o \tilde{G}_e$ and $G_m \overset{=}{\Rightarrow} \tilde{G}_m$

in Eqn (1a) we have,

$$V X \tilde{G}_m = \tilde{I} d(r-r') + k_o^2 \tilde{G}_e$$

where the symbol \Rightarrow implies "Corresponds to".

Eqn.(8a) may be written as :-

$$(V^2 + k_o^2)(g_m^{xx} \bar{x}\bar{x} + g_m^{yy} \bar{y}\bar{y} + g_m^{zz} \bar{z}\bar{z}) = -(x\bar{x} + y\bar{y} + z\bar{z}) d(r-r'')$$

Hence Eqn(5) may be written componentwise as :-

(With upper sign for $z > z''$ and Lower sign for $z < z''$)
X-Component $(V^2 + K_o^2) g_m^{xx} \bar{x}\bar{x} = -d(r-r')\bar{x}\bar{x} \dots \quad \dots (11a)$

v

$$\bar{n} \cdot g_m^{xx} \bar{x}\bar{x} = 0$$

$$\bar{n}_x \left(\frac{\partial g_m^{xx}}{\partial z} \bar{y} - \frac{\partial g_m^{xx}}{\partial y} \bar{z} \right) \bar{x} = 0$$

on the wall .. (11a')

The corresponding solution is :-

$$g_m^{xx} = \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} A_{nm} \sin \frac{n\pi x}{a} \cos \frac{m\pi y}{b} \exp(\pm i G_{nm} z) \quad \dots (11d)$$

~~With the same procedure as above we can find the corresponding solution for Y-component~~

where $G_{nm}^2 = \left(\left(\frac{n\pi}{a} \right)^2 + \left(\frac{m\pi}{b} \right)^2 - K_o^2 \right)$ and $\bar{n} = \bar{x}$ &/or \bar{y} .

Y-Component

$$(V^2 + K_o^2) g_m^{yy} \bar{y}\bar{y} = -d(r-r')\bar{y}\bar{y} \dots \quad \dots (11b)$$

$$\bar{n} \cdot g_m^{yy} \bar{y}\bar{y} = 0$$

$$\bar{n}_x \left(\frac{\partial g_m^{yy}}{\partial x} \bar{z} - \frac{\partial g_m^{yy}}{\partial z} \bar{x} \right) \bar{y} = 0$$

on the wall .. (11b')

The corresponding solution is :-

$$g_m^{yy} = \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} B_{nm} \cos \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \exp(\mp i G_{nm} z) \dots \quad \dots (11e)$$

Z-Component

$$(V^2 + K_o^2) g_m^{zz} \bar{z}\bar{z} = -d(r-r')\bar{z}\bar{z} \dots \quad \dots (11c)$$

$$\bar{n} \cdot g_m^{zz} \bar{z}\bar{z} = 0$$

$$\bar{n}_x \left(\frac{\partial g_m^{zz}}{\partial y} \bar{x} - \frac{\partial g_m^{zz}}{\partial x} \bar{y} \right) \bar{z} = 0$$

On the wall. (11c')

The corresponding solution is :-

$$g_m^{zz} = \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} C_{nm} \cos \frac{n\pi x}{a} \cos \frac{m\pi y}{b} \exp(\mp i G_{nm} z) \dots \quad \dots (11f)$$

Evaluation of A_{nm}^{\pm} : [8] Pp 199-200.

If Equation (11a) is multiplied by $\sin\left(\frac{n\pi x}{a}\right)\cos\left(\frac{m\pi y}{b}\right)$ and integrated over the guide cross-section we obtain,

$$\left(\frac{d^2}{dz^2} - G_{nm}^2\right) g_m^{xx}(z) = - \sin\left(\frac{n\pi x}{a}\right)\cos\left(\frac{m\pi y}{b}\right) \dots\dots(11g)$$

$$\text{where } g_m^{xx}(z) = \int_0^a \int_0^b g_m^{xx}(x, y') \sin\frac{n\pi x}{a} \cos\frac{m\pi y}{b} dy dx$$

Equation (11g) is arrived at as follows: -

For $n = \bar{x}$ at $x = 0$ and $x = a$

1st B.C. (boundary condition) yields $g_m^{xx}|_{x=0} = 0$ } i.e. $G_m^{xx} \Rightarrow \sin\frac{n\pi x}{a}$

2nd B.C. yields $0 = 0$

For $n = \bar{y}$ at $y = 0$ & $y = b$

1st B.C. yields $0 = 0$

2nd B.C. yields $-\frac{\partial g_m^{xx}}{\partial y}|_{y=b} = 0$

} i.e. $G_m^{xx} \Rightarrow \cos\frac{m\pi y}{b}$

Combining these results for all possible modes:

$$g_m^{xx} = \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} A_{nm}^{\pm} \sin\frac{n\pi x}{a} \cos\frac{m\pi y}{b} \exp(\pm G_{nm} z) \dots(11d)$$

where the upper sign is for $z > z''$ and the lower sign if for $z < z''$

Substituting (11d) in (11a) we have,

$$\left(\frac{d^2}{dz^2} - \left(\frac{n\pi}{a}\right)^2 - \left(\frac{m\pi}{b}\right)^2 + k_o^2\right) g_m^{xx}(r, r'') = -d(r-r'') = -d(x-x'')d(y-y'')d(z-z'')$$

Multiplying this equation by $\sin\frac{n\pi x}{a} \cos\frac{m\pi y}{b}$ and integrating

over guide cross-section we have:-

$$\int_0^a \int_0^b \left(\frac{d^2}{dz^2} - (G_{nm}^2)^{\pm}\right) g_m^{xx} \sin\frac{n\pi x}{a} \cos\frac{m\pi y}{b} dx dy$$

$$= - \int_0^a \int_0^b d(r-r'') \sin\frac{n\pi x}{a} \cos\frac{m\pi y}{b} dx dy$$

$$\text{or } \left(\frac{d^2}{dz^2} - (G_{nm}^2)^{\pm}\right) \int_0^a \int_0^b g_m^{xx} \sin\frac{n\pi x}{a} \cos\frac{m\pi y}{b} dx dy$$

$$= - \sin\frac{n\pi x}{a} \cos\frac{m\pi y}{b} d(z-z'')$$

$$\text{or } \left(-\frac{\partial^2}{\partial z^2} - G_{nm}^2 \right) g_{nm}^{xx}(z) = - \sin \frac{n\pi x''}{a} \cos \frac{m\pi y''}{b} d(z-z'') \quad (11g)$$

$$d(z-z'') \quad \dots \quad \dots \quad \dots \quad \dots \quad (11g)$$

$$\text{where } g_{nm}^{xx}(z) = \int_0^b g_m^{xx} \sin \frac{n\pi x}{a} \cos \frac{m\pi y}{b} dx dy =$$

$$= \begin{cases} A_{nm}^- \frac{ab}{e_{on} e_{om}} e^{-G_{nm} z''} & \dots \quad \text{for } z < z'' \\ A_{nm}^+ \frac{ab}{e_{on} e_{om}} e^{-G_{nm} z''} & \dots \quad \text{for } z > z'' \end{cases}$$

$$\text{N.B. } e_{on} = \begin{cases} 1 & \text{for } n = 0 \\ 2 & \text{otherwise.} \end{cases} \quad \& \quad e_{om}' = \begin{cases} 1 & \text{for } m = 0 \\ 2 & \text{otherwise.} \end{cases}$$

At $Z = Z''$, $g_{nm}^{xx}(z)$ is continuous.

$$\text{Hence } A_{nm}^- \frac{ab}{e_{on} e_{om}} e^{-G_{nm} z''} = A_{nm}^+ \frac{ab}{e_{on} e_{om}} e^{-G_{nm} z''} \dots \quad (11h)$$

Also since $g_{nm}^{xx}(z)$ is continuous at $Z = Z''$, integrating (11g)

from $Z'' - \Delta$ to $Z'' + \Delta$ over Z'' and letting Δ approach zero,

we have,

$$\left[\frac{dg_{nm}^{xx}(z)}{dz} \right]_{Z''_-}^{Z''_+} = - \sin \frac{n\pi x''}{a} \cos \frac{m\pi y''}{b}$$

This implies that $\frac{dg_{nm}^{xx}(z)}{dz}$ is discontinuous at $Z = Z''$.

-17-

$$\text{Thus, } G_{nm} A_{nm} + \frac{ab}{e_{on} e'_{om}} e^{-G_{nm} z''} = G_{nm} A_{nm} - \frac{ab}{e_{on} e'_{om}} e^{G_{nm} z''}$$

$$= - \sin \frac{n\pi x''}{a} \cos \frac{m\pi y''}{b} \dots \quad (11i)$$

$$\text{Solving (11h) and (11i)} \quad A_{nm}^+ e^{-G_{nm} z''} = A_{nm}^- e^{G_{nm} z''}$$

$$= \frac{e_{on} e'_{om}}{G_{nm} 2ab} \sin \frac{n\pi x''}{a} \cos \frac{m\pi y''}{b}$$

$$\text{Thus } g_m^{xx}(r, r'') = \left[\sum_{n=0}^{\infty} \sum_{m=0}^{\infty} \frac{e_{on} e'_{om}}{2ab G_{nm}} e^{-G_{nm}|z-z''|} \right]$$

$$\left. \sin \frac{n\pi x}{a} \sin \frac{n\pi x''}{a} \cos \frac{m\pi y}{b} \cos \frac{m\pi y''}{b} \right]$$

Similarly we can evaluate the coefficients B_{pm}^+ and C_{nm}^+

and obtain expressions for $g_m^{yy}(r, r'')$ and $g_m^{zz}(r, r'')$

Combining $g_m^{xx}(r, r'')$, $g_m^{yy}(r, r'')$ and $g_m^{zz}(r, r'')$ we have

$$g_m(r, r'') = \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} \frac{e_{on} e'_{om}}{2ab G_{nm}} e^{-G_{nm}|z-z''|}$$

$$\left. \begin{array}{l} \bar{x}\bar{x} (\sin \frac{n\pi x}{a} \sin \frac{n\pi x''}{a} \cos \frac{m\pi y}{b} \cos \frac{m\pi y''}{b}) \\ +\bar{y}\bar{y} (\cos \frac{n\pi x}{a} \cos \frac{n\pi x''}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y''}{b}) \\ +\bar{z}\bar{z} (\sin \frac{n\pi x}{a} \sin \frac{n\pi x''}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y''}{b}) \end{array} \right\} \quad \dots (12)$$

Substituting Eqn(12) in Eqn(9) we now perform the integration $\int \int$ to solve \bar{g}_m for \bar{G}_m . The integration can be performed in a simple way by incorporating some elementary theorems of the distribution theory. To this end the following relations of the distribution theory are used to simplify the process of integrating Eqn(9): $\nabla'' x \bar{I} d(r'-r'') = \frac{\partial}{\partial x''} (\bar{x} \bar{I} d(r'-r''))$

$$= (\bar{x} \frac{\partial}{\partial x''} + \bar{y} \frac{\partial}{\partial y''} + \bar{z} \frac{\partial}{\partial z''}) \times (\bar{x}\bar{x} + \bar{y}\bar{y} + \bar{z}\bar{z}) d(r'-r'')$$

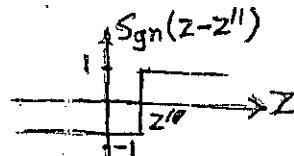
$$= (\frac{\partial d}{\partial z''} \bar{y} - \frac{\partial d}{\partial y''} \bar{z}) \bar{x} + (\frac{\partial d}{\partial x''} \bar{z} - \frac{\partial d}{\partial z''} \bar{x}) \bar{y} + (\frac{\partial d}{\partial y''} \bar{x} - \frac{\partial d}{\partial x''} \bar{y}) \bar{z} \quad (13)$$

(Since $\bar{x}\bar{x} = \bar{y}\bar{y} = \bar{z}\bar{z} = 0$, $\bar{x}\bar{y} = \bar{z}$, $\bar{y}\bar{z} = \bar{x}$, $\bar{z}\bar{x} = \bar{y}$)

$$\frac{\partial}{\partial z''} e^{-G_{nm}|z-z''|} = G_{nm} \operatorname{sgn}(z-z'') e^{-G_{nm}|z-z''|} \quad \begin{matrix} \text{Ref. (3)} \\ \text{P. 48.} \end{matrix} \quad (14)$$

$\operatorname{sgn}(z-z'')$... (14) (Ref. 9).

Where $\operatorname{sgn}(z-z'')$ is representable as :-



$$\int \left(\frac{\partial d}{\partial z''} (z-z'') \right) f dv'' = - \frac{df}{dz''} \quad (15) \quad \text{(Ref. 9).}$$

Applying Eqns (13), (14) & (15) in eqn (9) and performing the differentiation - integration the following result is obtained:-

$$\bar{G}_m(r, r') = \int \bar{g}_m(r, r''), \nabla'' x \bar{I} d(r'-r'') dv''$$

$$= \int \bar{g}_m(r, r'') \left(\frac{\partial}{\partial x''} (\bar{x} \bar{I} d(r'-r'')) - \frac{\partial}{\partial y''} (\bar{y} \bar{I} d(r'-r'')) - \frac{\partial}{\partial z''} (\bar{z} \bar{I} d(r'-r'')) \right) dv''$$

$$\begin{aligned}
 &= \sqrt{\left[-g_m^{xx} \bar{x}\bar{x} \cdot \frac{dd}{dz''} \bar{x}\bar{y} + g_m^{xx} \bar{x}\bar{x} \cdot \frac{dd}{dy''} \bar{x}\bar{x} + g_m^{yy} \bar{y}\bar{y} \cdot \frac{dd}{dz''} \bar{y}\bar{x} \right.} \\
 &\quad \left. - g_m^{yy} \bar{y}\bar{y} \cdot \frac{dd}{dx''} \bar{y}\bar{x} - g_m^{zz} \bar{z}\bar{z} \cdot \frac{dd}{dy''} \bar{z}\bar{x} + g_m^{zz} \bar{z}\bar{z} \cdot \frac{dd}{dx''} \bar{z}\bar{y} \right] dy''} \\
 &= \left[\frac{dg_m^{xx}}{dz''} \bar{x}\bar{y} - \frac{dg_m^{xx}}{dy''} \bar{x}\bar{x} \right. \\
 &\quad \left. + \frac{dg_m^{yy}}{dz''} \bar{y}\bar{x} + \frac{dg_m^{yy}}{dx''} \bar{y}\bar{y} \right. \\
 &\quad \left. + \frac{dg_m^{zz}}{dy''} \bar{z}\bar{x} - \frac{dg_m^{zz}}{dx''} \bar{z}\bar{z} \right] \\
 &= \left[G_m^{xy} \bar{x}\bar{y} + G_m^{xz} \bar{x}\bar{z} + G_m^{yx} \bar{y}\bar{x} + G_m^{yz} \bar{y}\bar{z} + G_m^{zy} \bar{z}\bar{x} \right. \\
 &\quad \left. + G_m^{zy} \bar{z}\bar{y} \right]
 \end{aligned}$$

$$\begin{aligned}
 x'' &= x' \\
 y'' &= y' \\
 z'' &= z'
 \end{aligned}$$

$$\sum_{n=0}^{\infty} \sum_{m=0}^{\infty} \frac{e_{on} e'_{om}}{2ab G_{nm}} \left[\bar{x}\bar{y} G_{nm} \operatorname{Sgn}(z-z') \right]_{\text{limits}}$$

$$\sin \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \cos \frac{m\pi y}{b} \cos \frac{m\pi y'}{b}$$

$$+ \bar{x}\bar{z} \left(\frac{m\pi}{b} \right) \sin \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \cos \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} \bar{y}\bar{x} G_{nm} \operatorname{Sgn}(z-z'),$$

$$\cos \frac{n\pi x}{a} \cos \frac{n\pi x'}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} - \bar{y}\bar{z} \left(\frac{n\pi}{a} \right) \cos \frac{n\pi x}{a}$$

$$\sin \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} - \bar{x}\bar{z} \left(\frac{m\pi}{b} \right) \cos \frac{n\pi x}{a}$$

$$\frac{\cos \frac{n\pi x}{a}}{a} \cos \frac{n\pi y}{b} \sin \frac{n\pi y}{b} + \bar{z}\bar{y} \left(\frac{n\pi}{a} \right) \cos \frac{n\pi x}{a}$$

$$\sin \frac{n\pi x}{a} \cos \frac{n\pi y}{b} \cos \frac{n\pi y}{b} \Big]$$

Substituting this value of \tilde{G}_m in Eqn(10) we obtain

\tilde{G}_e as follows:

$$\begin{aligned} \tilde{G}_e &= \frac{1}{2} \frac{Vx \tilde{G}_m}{K_o} - \tilde{I} d(r-r') = \left[Vx \left(G_m^{xx} \bar{x} + G_m^{yx} \bar{y} + G_m^{zx} \bar{z} \right) \bar{x} \right. \\ &\quad \left. + Vx \left(G_m^{xy} \bar{x} + G_m^{yy} \bar{y} + G_m^{zy} \bar{z} \right) \bar{y} + Vx \left(G_m^{xz} \bar{x} + G_m^{yz} \bar{y} \right. \right. \\ &\quad \left. \left. + G_m^{zz} \bar{z} \right) \bar{z} \right] - \left[\bar{x}\bar{x} d(r-r') + \bar{y}\bar{y} d(r-r') + \bar{z}\bar{z} d(r-r') \right] \\ &= \left[\left(\frac{\partial G_m^{yx}}{\partial x} \bar{z}\bar{x} - \frac{\partial G_m^{yx}}{\partial z} \bar{x}\bar{x} \right) + \left(\frac{\partial G_m^{zx}}{\partial y} \bar{x}\bar{x} - \frac{\partial G_m^{zx}}{\partial x} \bar{y}\bar{x} \right) \right. \\ &\quad + \left(\frac{\partial G_m^{xy}}{\partial z} \bar{y}\bar{y} - \frac{\partial G_m^{xy}}{\partial y} \bar{y}\bar{x} \right) + \left(\frac{\partial G_m^{zy}}{\partial y} \bar{x}\bar{y} - \frac{\partial G_m^{zy}}{\partial x} \bar{y}\bar{y} \right) \\ &\quad \left. + \left(\frac{\partial G_m^{xz}}{\partial z} \bar{y}\bar{z} - \frac{\partial G_m^{xz}}{\partial y} \bar{z}\bar{x} \right) + \left(\frac{\partial G_m^{yz}}{\partial x} \bar{z}\bar{z} - \frac{\partial G_m^{yz}}{\partial z} \bar{x}\bar{z} \right) \right] \\ &- \tilde{I} d(r-r') = \left[\bar{x}\bar{x} \left(- \frac{\partial G_m^{yx}}{\partial z} + \frac{\partial G_m^{zx}}{\partial y} - \frac{d(r-r')}{K_o^2} \right) + \bar{y}\bar{y} \right. \\ &\quad \left(\frac{\partial G_m^{xy}}{\partial z} - \frac{\partial G_m^{zy}}{\partial x} - \frac{d(r-r')}{K_o^2} \right) + \bar{z}\bar{z} \left(- \frac{\partial G_m^{xz}}{\partial y} + \frac{\partial G_m^{yz}}{\partial x} \right) \\ &\quad + \bar{x}\bar{y} \left(- \frac{\partial G_m^{zy}}{\partial y} \right) + \bar{y}\bar{x} \left(- \frac{\partial G_m^{zx}}{\partial x} \right) + \bar{x}\bar{z} \bar{y} \left(\frac{\partial G_m^{xz}}{\partial z} \right) \\ &\quad \left. + \bar{z}\bar{y} \left(- \frac{\partial G_m^{xy}}{\partial y} \right) + \bar{x}\bar{x} \left(\frac{\partial G_m^{yz}}{\partial x} \right) + \bar{x}\bar{z} \bar{z} \left(- \frac{\partial G_m^{yz}}{\partial z} \right) \right] \\ &- \bar{z}\bar{z} \frac{1}{2} \frac{d(r-r')}{K_o} \end{aligned}$$

For simplifying we use the following :-

$$\begin{aligned} \frac{d}{dz} \left[e^{-G_{nm}|z-z'|} \right] &= -G_{nm} \operatorname{Sgn}(z-z') e^{-G_{nm}|z-z'|} \\ -\frac{d}{dz} \left(\operatorname{Sgn}(z-z') e^{-G_{nm}|z-z'|} \right) &= \left(-G_{nm} + 2d(z-z') \right) e^{-G_{nm}|z-z'|} \end{aligned} \quad \dots (17)$$

and the completeness relations:- $d(x-x') d(y-y')$

$$\begin{aligned} 1 &= \left[\sum_{n=0}^{\infty} \sum_{m=0}^{\infty} \frac{e_{on} e'_{om}}{ab} \sin \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \cos \frac{m\pi y}{b} \cos \frac{m\pi y'}{b} \right] \\ &\stackrel{x \rightarrow \infty}{\rightarrow} \left[\sum_{n=0}^{\infty} \sum_{m=0}^{\infty} \frac{e_{on} e'_{om}}{ab} \cos \frac{n\pi x}{a} \cos \frac{n\pi x'}{a} \cos \frac{m\pi y}{b} \cos \frac{m\pi y'}{b} \right. \\ &\quad \left. \sin \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} \right] \quad \dots \quad \dots (18) \end{aligned}$$

Equation (18) is the mode completeness relation for cylindrical waveguides with normal mode functions separable into a transverse part and an axial part & constant coordinate curves coinciding with boundary of the waveguides (8). Using these relations we obtain the following

result:-

$$\begin{aligned} G_e &= \frac{1}{K^2} \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} \frac{e_{on} e'_{om}}{2ab G_{nm}} e^{-G_{nm}|z-z'|} \left[\bar{xx} \left(\left(\frac{m\pi}{b} \right)^2 - G_{nm}^2 \right) \right. \\ &\quad \left. + \bar{yy} \left(\left(\frac{n\pi}{a} \right)^2 - G_{nm}^2 \right) \right. \\ &\quad \left. + \bar{zz} \left(\left(\frac{m\pi}{b} \right)^2 + \left(\frac{n\pi}{a} \right)^2 \right) \right] \end{aligned}$$

$$\begin{aligned}
 & \left(\sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \right) \left(\sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \right) + \bar{x}\bar{y} \left(-\left(\frac{m\pi}{b} \right) \left(\frac{n\pi}{a} \right) \right), \\
 & \left(\cos \frac{n\pi x}{a} \sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \cos \frac{m\pi y}{b} \right) + \bar{x}\bar{y} \\
 & + \bar{y}\bar{x} \left(-\left(\frac{m\pi}{b} \right) \left(\frac{n\pi}{a} \right) \right) \cdot \left(\sin \frac{n\pi x}{a} \cos \frac{n\pi x}{a} \cos \frac{m\pi y}{b} \sin \frac{m\pi y}{b} \right) \\
 & \left(\sin \frac{n\pi x}{a} \sin \frac{n\pi x}{a} \right) + \bar{y}\bar{z} \left(-\left(\frac{m\pi}{b} \right) \right) G_{nm} \operatorname{sgn}(z-z') \cdot \left(\sin \frac{n\pi x}{a} \sin \frac{n\pi x}{a} \right) \\
 & \cos \frac{m\pi y}{b} \cos \frac{m\pi y}{b} \right) + \bar{z}\bar{x} \left(+\left(\frac{m\pi}{b} \right) \right) G_{nm} \operatorname{sgn}(z-z') \left(\cos \frac{n\pi x}{a} \sin \frac{n\pi x}{a} \right) \\
 & \left(\sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \cos \frac{m\pi y}{b} \right) + \bar{z}\bar{x} \left(+\left(\frac{n\pi}{a} \right) \right) G_{nm} \operatorname{sgn}(z-z') \\
 & \left(\sin \frac{n\pi x}{a} \cos \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y}{b} \right) + \bar{x}\bar{z} \left(-\left(\frac{n\pi}{a} \right) \right) \\
 & G_{nm} \operatorname{sgn}(z-z') \left(\cos \frac{n\pi x}{a} \sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y}{b} \right)
 \end{aligned}$$

$$-\frac{1}{K_o^2} \bar{z}\bar{z} d(r-r') = \bar{G}_{eo}(r, r') - \frac{1}{K_o^2} \bar{z}\bar{z} d(r-r') \quad \dots \quad \dots \quad (19)$$

Putting $G_{nm} = jK_{nm}$ where $K_{nm}^2 = G_{nm}^2 = K_p^2 - k_o^2$

$$\text{and } K_p^2 = \left[\left(\frac{n\pi}{a} \right)^2 + \left(\frac{m\pi}{b} \right)^2 \right] \& jK_{nm} = G_{nm} = \sqrt{(K_p^2 - k_o^2)} \quad \dots$$

we have the following form for \bar{G}_{eo}

$$\bar{G}_{eo}(r, r') = -\frac{j}{2abk_o^2} \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} \frac{e_{on} e'_{om}}{K_{nm}} e^{-j K_{nm}(z-z')}.$$

$$\left[\bar{x}\bar{x} \left(K_o^2 - \left(\frac{n\pi}{a} \right)^2 \right) \cos \frac{n\pi x}{a} \cos \frac{n\pi x'}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} \right]$$

$$\begin{aligned}
 & +\bar{y}\bar{y} \left(k_o^2 - \left(\frac{m_{II}}{b}\right)^2 \right) \sin \frac{n_{II}x}{a} \sin \frac{n_{II}x'}{a} \cos \frac{m_{II}y}{b} \cos \frac{m_{II}y'}{b} \\
 & +\bar{z}\bar{z} \left(\left(\frac{n_{II}}{a}\right)^2 + \left(\frac{m_{II}}{b}\right)^2 \right) \sin \frac{n_{II}x}{a} \sin \frac{n_{II}x'}{a} \sin \frac{m_{II}y}{b} \sin \frac{m_{II}y'}{b} \\
 & +\bar{x}\bar{y} \left(\pm \left(\frac{n_{II}}{a}\right) \left(\frac{m_{II}}{b}\right) \right) (\cos \frac{n_{II}x}{a} \sin \frac{n_{II}x'}{a} \sin \frac{m_{II}y}{b} \cos \frac{m_{II}y'}{b} \\
 & +\bar{y}\bar{x} \left(-\left(\frac{n_{II}}{a}\right) \left(\frac{m_{II}}{b}\right) \right) \sin \frac{n_{II}x}{a} \cos \frac{n_{II}x'}{a} \cos \frac{m_{II}y}{b} \sin \frac{m_{II}y'}{b} \\
 & +\bar{y}\bar{z} \left(\mp jK_{nm} \left(\frac{m_{II}}{b}\right) \right) \sin \frac{n_{II}x}{a} \sin \frac{n_{II}x'}{a} \cos \frac{m_{II}y}{b} \sin \frac{m_{II}y'}{b} \\
 & +\bar{z}\bar{y} \left(\pm jK_{nm} \left(\frac{m_{II}}{b}\right) \right) \sin \frac{n_{II}x}{a} \sin \frac{n_{II}x'}{a} \sin \frac{m_{II}y}{b} \cos \frac{m_{II}y'}{b} \\
 & +\bar{z}\bar{x} \left(\pm jK_{nm} \left(\frac{n_{II}}{a}\right) \right) \sin \frac{n_{II}x}{a} \cos \frac{n_{II}x'}{a} \sin \frac{m_{II}y}{b} \sin \frac{m_{II}y'}{b} \\
 & +\bar{x}\bar{z} \left(\mp jK_{nm} \left(\frac{n_{II}}{a}\right) \right) \cos \frac{n_{II}x}{a} \sin \frac{n_{II}x'}{a} \sin \frac{m_{II}y}{b} \sin \frac{m_{II}y'}{b}
 \end{aligned}$$

for $z \gtrless z'$ (20).

Art-3:-

A modified method of deriving \tilde{G}_e :

Following the suggestion of Collin ((8) pp 222-223) and a procedure very similar to that of Art-2, a modified procedure of deriving the electric type dyadic Green's function \tilde{G}_e is presented as follows:-

Defining vector potential A_s by $\mathbf{H}_s = \nabla \times \mathbf{A}_s$

and defining scalar potential ψ_s by $E_s = -j\omega A_s - \nabla \psi_s$

and using them in Maxwell's ~~Coulomb~~ equation $\nabla \times \mathbf{H}_s = j\omega \epsilon_0 E_s + J$

and using the Lorentz condition $\nabla \cdot \mathbf{A}_s = -j\omega \mu_0 \epsilon_0 \nabla \psi_s$ we have

$$\nabla \times \nabla \times \mathbf{A}_s = \mu_0 J + k_o^2 A_s = j\omega \mu_0 \epsilon_0 \nabla \psi_s$$

$$\text{or } -\nabla^2 A_s + \nabla \cdot A_s = \mu_0 J + k_o^2 A_s - j\omega \mu_0 \epsilon_0 \nabla \psi_s$$

$$\therefore \nabla^2 \left(\frac{A_s}{\mu_0} \right) + k_o^2 \left(\frac{A_s}{\mu_0} \right) = -J$$

$$\text{and } \frac{E_s}{-j\omega \mu_0} = \left(1 + \frac{1}{k_o^2} \nabla \cdot \nabla \right) \left(\frac{A_s}{\mu_0} \right) \quad (\text{Using Lorentz condition})$$

in ψ_s defining equation)

$$\text{For } J \Rightarrow \bar{I} d(r-r') \quad \frac{A_s}{\mu_0} \Rightarrow \bar{G}_a \quad \text{and} \quad \frac{E_s}{-j\omega \mu_0} \Rightarrow \bar{G}_e$$

we have

$$\nabla^2 \bar{G}_a + k_o^2 \bar{G}_a = -\bar{I} d(r-r') \quad \text{and} \quad \bar{G}_e = \left(1 + \frac{1}{k_o^2} \nabla \cdot \nabla \right) \bar{G}_a$$

Thus due to a current distribution $J(r, r')$, throughout volume element

$$E_s(r) = -j\omega \mu_0 \int \bar{G}_e(r, r') dV' \quad (\text{Eqn(2) of Art -2.})$$

To Solve for \tilde{G}_a we set

$$V^2 \tilde{G}_a + k_0^2 \tilde{G}_a = -\tilde{I} d(r-r') \text{ in the waveguide}$$

$$\nabla \cdot \tilde{G}_a = 0 \quad \left[\text{from } V_s E_s = -\frac{P_s}{q} = V_s (-jw u_0 (1 + \frac{1}{k_0^2} VV_s) A) \right] \text{ on the wall.}$$

$$\tilde{n} \cdot \nabla \times \tilde{G}_a = 0 \quad \left[\text{from } \tilde{n} \cdot \tilde{H}_s = \tilde{n} \cdot \nabla \times \tilde{A}_s = 0. \right]$$

Component wise:-

$$(V^2 + k_0^2) G_a^{xx} \hat{x}\hat{x} = -d(r-r') \hat{x}\hat{x}$$

$$\frac{\partial G_a^{xx}}{\partial \hat{x}} \hat{x} = 0$$

$$\tilde{n} \cdot \left(\frac{\partial G_a^{xx}}{\partial z} \hat{y} - \frac{\partial G_a^{xx}}{\partial y} \hat{z} \right) \hat{x} = 0 \quad \left\{ \text{on the wall.} \right.$$

$$(V^2 + k_0^2) G_a^{yy} \hat{y}\hat{y} = -d(r-r') \hat{y}\hat{y}$$

$$\frac{\partial G_a^{yy}}{\partial \hat{y}} \hat{y} = 0$$

$$\tilde{n} \cdot \left(\frac{\partial G_a^{yy}}{\partial x} \hat{z} - \frac{\partial G_a^{yy}}{\partial z} \hat{x} \right) \hat{y} = 0 \quad \left\{ \text{on the wall.} \right.$$

$$(V^2 + k_0^2) G_a^{zz} \hat{z}\hat{z} = -d(r-r') \hat{z}\hat{z}$$

$$\frac{\partial G_a^{zz}}{\partial \hat{z}} \hat{z} = 0$$

$$\tilde{n} \cdot \left(\frac{\partial G_a^{zz}}{\partial y} \hat{x} - \frac{\partial G_a^{zz}}{\partial x} \hat{y} \right) \hat{z} = 0 \quad \left\{ \text{on the wall.} \right.$$

$$\therefore G_a^{xx} = \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} A_{nm}^+ \cos \frac{n\pi x}{a} \sin \frac{m\pi y}{b} e^{\pm G_{nm} z}$$

$$G_a^{yy} = \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} B_{nm}^+ \sin \frac{n\pi x}{a} \cos \frac{m\pi y}{b} e^{\pm G_{nm} z}$$

$$G_a^{zz} = \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} C_{nm}^+ \sin \frac{n\pi x}{a} \sin \frac{m\pi y}{b} e^{\pm G_{nm} z}$$

These solutions are obtained by the method of separation of variables with assumed propagations factor $e^{\pm G_{nm} z}$.

where $G_{nm}^2 = \left[\left(\frac{n\pi}{a} \right)^2 + \left(\frac{m\pi}{b} \right)^2 - k_0^2 \right]$ & using

boundary conditions.

In G_a^{xx} , G_a^{yy} , G_a^{zz} expressions, the upper sign is for $z > z'$

and the lower sign is for $z < z'$..

Proceeding as in Art:-2 the coefficients A_{nm}^+ , B_{nm}^+ ,

C_{nm}^+ may

be evaluated. When so evaluated we obtain \bar{G}_a as

follows :-

$$\bar{G}_a = G_a^{xx} \bar{xx} + G_a^{yy} \bar{yy} + G_a^{zz} \bar{zz} = \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} G_{nm}^{\pm} e^{\pm G_{nm} z - z'} \cdot \frac{e_{on} e_{om}'}{2ab G_{nm}^2}$$

$$\left[\bar{xx} \cos \frac{n\pi x}{a} \cos \frac{n\pi x'}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} \right]$$

$$+ \bar{yy} \sin \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \cos \frac{m\pi y}{b} \cos \frac{m\pi y'}{b}$$

$$+ \bar{z}\bar{z} \sin \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y'}{b}]$$

Using this expression of \bar{G}_a , \bar{G}_e is obtained as follows:-

$$\bar{G}_e = \left(1 + \frac{1}{k_o^2} VV \cdot \bar{G}_a \right) + \left\{ \frac{1}{k_o^2} V \left(\bar{x} \frac{\partial}{\partial x} + \bar{y} \frac{\partial}{\partial y} + \bar{z} \frac{\partial}{\partial z} \right) \right.$$

$$(\bar{x}\bar{x}G_a^{xx} + \bar{y}\bar{y}G_a^{yy} + \bar{z}\bar{z}G_a^{zz}) \left. \right\}$$

$$= \left[\bar{G}_a + \frac{1}{k_o^2} \left(\bar{x} \frac{\partial}{\partial x} + \bar{y} \frac{\partial}{\partial y} + \bar{z} \frac{\partial}{\partial z} \right) \left(\bar{x} \frac{\partial G_a^{xx}}{\partial x} + \bar{y} \frac{\partial G_a^{yy}}{\partial y} + \bar{z} \frac{\partial G_a^{zz}}{\partial z} \right) \right]$$

$$= (\bar{x}\bar{x}G_a^{xx} + \bar{y}\bar{y}G_a^{yy} + \bar{z}\bar{z}G_a^{zz}) - \frac{1}{2}$$

$$+ \frac{1}{k_o^2} \left[\begin{aligned} & \bar{x}\bar{x} \frac{\partial^2 G_a^{xx}}{\partial x^2} + \bar{y}\bar{y} \frac{\partial^2 G_a^{yy}}{\partial y^2} + \bar{z}\bar{z} \frac{\partial^2 G_a^{zz}}{\partial z^2} \\ & + \bar{y}\bar{x} \frac{\partial^2 G_a^{xx}}{\partial y \partial x} + \bar{y}\bar{y} \frac{\partial^2 G_a^{yy}}{\partial y \partial y} + \bar{y}\bar{z} \frac{\partial^2 G_a^{zz}}{\partial y \partial z} \\ & + \bar{z}\bar{x} \frac{\partial^2 G_a^{xx}}{\partial z \partial x} + \bar{z}\bar{y} \frac{\partial^2 G_a^{yy}}{\partial z \partial y} + \bar{z}\bar{z} \frac{\partial^2 G_a^{zz}}{\partial z \partial z} \end{aligned} \right]$$

$$= \left[\bar{x}\bar{x} \left(G_a^{xx} + \frac{\partial^2 G_a^{xx}}{k_o^2 \partial x^2} \right) + \bar{y}\bar{y} \left(G_a^{yy} + \frac{\partial^2 G_a^{yy}}{k_o^2 \partial y^2} \right) + \bar{z}\bar{z} \left(G_a^{zz} + \frac{\partial^2 G_a^{zz}}{k_o^2 \partial z^2} \right) + \right.$$

$$- \frac{1}{k_o^2} d(r-r') \left(\bar{x}\bar{y} \frac{\partial^2 G_a^{yy}}{\partial x \partial y} + \bar{y}\bar{z} \frac{\partial^2 G_a^{zz}}{\partial y \partial z} + \bar{z}\bar{x} \frac{\partial^2 G_a^{xx}}{\partial z \partial x} \right)$$

$$+ \bar{z}\bar{y} \left(\frac{\partial^2 G_a^{yy}}{k_o^2 \partial z \partial y} \right) + \bar{z}\bar{x} \left(\frac{\partial^2 G_a^{xx}}{k_o^2 \partial z \partial x} \right) + \bar{x}\bar{z} \left(\frac{\partial^2 G_a^{zz}}{k_o^2 \partial x \partial z} \right) \left. \right] - \frac{1}{k_o^2} d(r-r')$$

Using the relation $\frac{d}{dz} e^{-\zeta_{nm}|z-z'|} = -\zeta_{nm} \text{Sgn}(z-z') e^{-\zeta_{nm}|z-z'|}$

$$\frac{d}{dz} \left(\text{Sgn}(z-z') e^{-\zeta_{nm}|z-z'|} \right) = \left(-\zeta_{nm} + 2d(z-z') \right) e^{-\zeta_{nm}|z-z'|}$$

and the mode completeness relation:- $d(x-x')d(y-y')$

$$\sum_{n=0}^{\infty} \sum_{m=0}^{\infty}$$

$$\left[\frac{e_{on}}{ab} \sin \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} \right]$$

We obtain the following expression for \bar{G}_e :-

$$\begin{aligned} \bar{G}_e = & \frac{1}{k^2} \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} \frac{e_{on} \zeta_{nm}}{2ab \zeta_{nm}} e^{-\zeta_{nm}|z-z'|} \left[\dots \left(\left(\frac{m\pi}{b} \right)^2 - \zeta_{nm}^2 \right) \right. \\ & \cos \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} \\ & + \bar{yy} \left(\left(\frac{m\pi}{b} \right)^2 - \zeta_{nm}^2 \right) \sin \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \cos \frac{m\pi y}{b} \cos \frac{m\pi y'}{b} \\ & + \bar{zz} \left(\left(\frac{m\pi}{b} \right)^2 + \left(\frac{n\pi}{a} \right)^2 \right) \sin \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} \\ & + \bar{xy} \left(-\left(\frac{m\pi}{b} \right) \left(\frac{n\pi}{a} \right) \right) \cos \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} \\ & + \bar{yx} \left(-\left(\frac{m\pi}{b} \right) \left(\frac{n\pi}{a} \right) \right) \sin \frac{n\pi x}{a} \cos \frac{n\pi x'}{a} \cos \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} \\ & + \bar{yz} \left(-\left(\frac{m\pi}{b} \right) \zeta_{nm} \text{Sgn}(z-z') \right) \sin \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \cos \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} \\ & + \bar{zy} \left(+\left(\frac{m\pi}{b} \right) \zeta_{nm} \text{Sgn}(z-z') \right) \sin \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \sin \frac{m\pi y}{b} \cos \frac{m\pi y'}{b} \\ & + \bar{zx} \left(+\left(\frac{n\pi}{a} \right) \zeta_{nm} \text{Sgn}(z-z') \right) \sin \frac{n\pi x}{a} \cos \frac{n\pi x'}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} \\ & + \bar{xz} \left(-\left(\frac{n\pi}{a} \right) \zeta_{nm} \text{Sgn}(z-z') \right) \cos \frac{n\pi x}{a} \sin \frac{n\pi x'}{a} \sin \frac{m\pi y}{b} \sin \frac{m\pi y'}{b} \\ & - \bar{zz} \frac{1}{k^2} d(r-r'). \end{aligned}$$

Appendix-I: ON DYADS and DYADIC Green's Function(4)
and Radiation Condition [4]

A dyad or a dyadic function \bar{D} is defined by :-

$\bar{D} = \bar{A} \bar{B}$, where the vector function \bar{A} is the anterior element
and the vector function \bar{B} is the posterior element.

A dyad plays the role very similar to that of a matrix.

Scalar Product between \bar{D} and \bar{C} :

Anterior scalar product : $\bar{C} \cdot \bar{D} = (\bar{C} \cdot \bar{A}) \bar{B} = \bar{B} (\bar{C} \cdot \bar{A}) = \bar{B} (\bar{A} \cdot \bar{C})$

Posterior scalar product: $\bar{D} \cdot \bar{C} = \bar{A} (\bar{B} \cdot \bar{C}) = ((\bar{B} \cdot \bar{C}) \bar{A} + (\bar{C} \cdot \bar{B}) \bar{A})$

The above two identities suggests $\bar{D}^t = \bar{B} \bar{A}$
where superscript t implies "transpose".

Thus $\bar{D} \cdot \bar{C} = \bar{C} \cdot \bar{D}^t$

The resultant of the scalar product between \bar{D} and \bar{C} is a vector
function.

Vector Product between \bar{D} and \bar{C} :-

Anterior vector product $\bar{C} \times \bar{D} = (\bar{C} \times \bar{A}) \bar{B}$

Posterior vector product $\bar{D} \times \bar{C} = \bar{A} (\bar{B} \times \bar{C})$

The resultant of the vector product between \bar{D} and \bar{C} is a
dyadic function.

e.g. In rectangular coordinate system

$$\bar{D} = \bar{D}(x) \bar{x} + \bar{D}(y) \bar{y} + \bar{D}(z) \bar{z}$$

$$= \left[\begin{array}{l} A_x B_x \bar{x}\bar{x} + A_x B_y \bar{x}\bar{y} + A_x B_z \bar{x}\bar{z} \\ + A_y B_x \bar{y}\bar{x} + A_y B_y \bar{y}\bar{y} + A_y B_z \bar{y}\bar{z} \\ + A_z B_x \bar{z}\bar{x} + A_z B_y \bar{z}\bar{y} + A_z B_z \bar{z}\bar{z} \end{array} \right]$$

where $\bar{D}^{(x)} = B_x \bar{A} = A_x B_x \bar{x} + A_y B_x \bar{y} + A_z B_x \bar{z}$
 $\bar{D}^{(y)} = B_y \bar{A} = A_x B_y \bar{x} + A_y B_y \bar{y} + A_z B_y \bar{z}$
 $\bar{D}^{(z)} = B_z \bar{A} = A_x B_z \bar{x} + A_y B_z \bar{y} + A_z B_z \bar{z}$

The above form of writing \bar{D} is most usual. An alternative form (not used usually) is :-

$$\bar{D} = \bar{x}^{(x)} \bar{D} + \bar{y}^{(y)} \bar{D} + \bar{z}^{(z)} \bar{D} \text{ where } \bar{x}^{(x)} \bar{D} = \bar{x} \cdot \bar{D}, \bar{y}^{(y)} \bar{D} = \bar{y} \cdot \bar{D}, \bar{z}^{(z)} \bar{D} = \bar{z} \cdot \bar{D}$$

Such expanded representation of \bar{D} illustrates the concept that a dyadic function is a composite of three vectors functions. Divergence of \bar{D} : v , $\bar{D} = (v \cdot \bar{D}) \bar{x} + (v \cdot \bar{D}) \bar{y} + (v \cdot \bar{D}) \bar{z}$ thus $(v \cdot \bar{D}) \bar{z} / v \cdot \bar{D}$ is a vector function.

$$\text{Curl of } \bar{D} : v \times \bar{D} = (v \times \bar{D}) \bar{x} + (v \times \bar{D}) \bar{y} + (v \times \bar{D}) \bar{z}$$

$v \times \bar{D}$ is a dyadic function.

$$\text{Unit Dyad } \bar{I} : \bar{I} = \bar{x}\bar{x} + \bar{y}\bar{y} + \bar{z}\bar{z}$$

The following identities manifest the properties of \bar{I} .

$$\bar{A} \cdot \bar{I} = \bar{I} \cdot \bar{A} = \bar{A} \quad \& \quad v \cdot (\bar{I} \Psi) = v\Psi \text{ where } \Psi \text{ is a scalar function.}$$

Green's vector Theorem and its application:-

$$\text{With } \bar{A} = \bar{Q} \times \bar{V} \times \bar{P} - \bar{P} \times \bar{V} \times \bar{Q}$$

Using the vector identity $v \cdot (\bar{C} \times \bar{D}) = \bar{D} \cdot \bar{V} \times \bar{C} - \bar{C} \cdot \bar{V} \times \bar{D}$, by assuming $\bar{C} = \bar{Q}$, $\bar{D} = \nabla \times \bar{P}$ in 1st term of \bar{A} and then

by assuming $\bar{C}' = \bar{P}$, $\bar{D}' = V X \bar{Q}$ in 2nd term of \bar{A} , we have

$$V \cdot \bar{A} = \bar{P} \cdot V X V \bar{Q} - \bar{Q} \cdot V X V \bar{P}$$

Applying Gauss theorem to this equation,

$$\nabla \cdot \int_V V \cdot \bar{A} dv = \oint_S \bar{A} \cdot \bar{D} ds$$

$$\text{or } \int_V (\bar{P} \cdot V X V \bar{Q} - \bar{Q} \cdot V X V \bar{P}) dv = \oint_S (\bar{Q} X V \bar{X} \bar{P} - \bar{P} X V \bar{X} \bar{Q}) ds$$

This is Green's vector theorem.

Now we let $\bar{P} = \bar{E}_s(r)$, $\bar{Q} = [\bar{G}_e(r, r') \cdot \bar{a}]$ where \bar{a} denotes

a constant, arbitrary vector.

Putting these values in Green's vector theorem, we have

$$\begin{aligned} & \int_V \left[\bar{E}_s(r) \cdot (V X V \bar{G}_e^*(r, r') \cdot \bar{a}) - \langle \bar{G}_e(r, r') \cdot \bar{a} \rangle \cdot (V X V \bar{E}_s(r)) \right] dv \\ &= \oint_S \left[\langle \bar{G}_e(r, r') \cdot \bar{a} \rangle \times (V X \bar{E}_s(r)) - \bar{E}_s(r) \times (V X \bar{G}_e(r, r') \cdot \bar{a}) \right] d\bar{s} \\ &= \oint_S \left[(V X \bar{E}_s(r)) \times (\bar{G}_e(r, r') \cdot \bar{a}) + (\bar{E}_s(r)) \times (V X \bar{G}_e(r, r') \cdot \bar{a}) \right] d\bar{s} \\ &= \oint_S \left[(\bar{n} X V \bar{E}_s(r)) \cdot (\bar{G}_e(r, r') \cdot \bar{a}) + (\bar{n} X \bar{E}_s(r)) \cdot (V X \bar{G}_e(r, r') \cdot \bar{a}) \right] ds \end{aligned}$$

where we have used $d\bar{s} = \bar{n} ds$

and the relation $(\bar{a}) \times (\bar{b}) \cdot \bar{c} = (\bar{c} \times \bar{a}) \cdot \bar{b}$

*N.B.
 \bar{n} denotes an outward normal*

In the volume integral part of this equation we put,

$$V X V \bar{G}_e^*(r, r') = K_o^2 \bar{G}_e(r, r') + \bar{I} d(r-r') \quad [\text{from eqn. 5(G) Ch.II.}]$$

$$V X V \bar{E}_s(r) = K_o^2 \bar{E}_s - j w u_o J(r) \quad [\text{from eqn 4(a) Ch.II.}]$$

and use the relation $\int_V \bar{E}_s(r) \cdot \bar{I} d(r-r') = \bar{E}_s(r')$

and rearranging terms we have [with $K_o^2 \bar{E}_s(r) \cdot \bar{G}_e(r, r')$ term cancelled].

$$\bar{E}_s(r') \cdot \bar{a} = -j w u_o \int_V \bar{J}(r) \cdot \bar{G}_e(r, r') \cdot \bar{a} dv$$

$$-\oint \left[(\bar{n} \times \nabla \bar{X} \bar{E}_s(r)) \cdot \bar{\hat{G}}_e(r, r') \cdot \bar{a} + (\bar{n} \bar{x} \bar{E}_s(r)) \cdot \nabla \bar{X} \bar{G}_e(r, r') \cdot \bar{a} \right] ds$$

Replacing $\nabla \bar{X} \bar{E}_s$ by $-jw\mu_0 \bar{H}_s$, interchanging the primed and the unprimed variables and deleting $(\cdot \bar{a})$ from the above equation, since \bar{a} is a constant vector, we have

$$\begin{aligned} \bar{E}_s(r) &= -jw\mu_0 \int \bar{J}(r') \cdot \bar{\hat{G}}_e(r', r) dv' \\ &- \oint_S \left[(-jw\mu_0 (\bar{n} \bar{X} \bar{H}_s(r') \bar{\hat{G}}_e(r', r)) + (\bar{n} \bar{x} \bar{E}_s(r')) \cdot \nabla \bar{X} \bar{G}_e(r', r)) \right] ds' \end{aligned}$$

where $(\nabla \bar{X})$ means that the \bar{x} curl operation has to be performed in the primed coordinate system.

With $jw\mu_0 = jk\mu_0$ and $\bar{H}_s = \frac{1}{\mu_0} \bar{r} \times \bar{E}_s$ (As far field radiation

approximation and considering the waveguide to be of infinite value i.e. input and output matched, surface S recedes to infinity then as a result of radiation condition the surface integral of the above equation becomes zero i.e.

$$\oint_S (\bar{n} \bar{x} \bar{E}_s(r')) \cdot (\nabla \bar{X} \bar{G}_e(r', r) - jk\bar{n} \bar{x} \bar{G}_e(r', r)) ds' = 0$$

N.B. Radiation condition : $\lim_{z \rightarrow \infty} [\nabla' \bar{x} \cdot \bar{G}_o(r', r) - jk_o \bar{z} \bar{x} \bar{G}_o(r', r)] = 0$

$$\text{Hence } \bar{E}_s(r) = -jw u_0 \int_V \bar{J}(r') \cdot \bar{G}_e^t(r', r) dv' \\ = -jw u_0 \int_V \bar{G}_e^t(r', r) \cdot \bar{J}(r') dv' = -jw u_0 \int_V \bar{G}_e(r, r') \cdot \bar{J}(r') dv'$$

The last expression results from the identity that

$$\bar{G}_e^t(r', r) = \bar{G}_e(r, r')$$

This is the effect either of the radiation condition or of the specific boundary condition. To clarify further this point we define two vector functions \bar{P} and \bar{Q} using a Green's function \bar{G} of the same boundary conditions but with two different source locations r_a and r_b such that

$$\bar{P} = \bar{G}(r, r_a) \cdot \bar{a} \text{ and } \bar{Q} = \bar{G}(r, r_b) \cdot \bar{b}$$

where \bar{a} and \bar{b} denote two different constant arbitrary vectors. Applying the vector Green's theorem to these two functions we obtain,

$$\bar{a}, \bar{G}(r_a, r_b) \cdot \bar{b} = \bar{b}, \bar{G}(r_b, r_a) \cdot \bar{a}$$

The surface integral vanishes either because of the radiation condition or because of the specific boundary conditions which \bar{G} must satisfy. Thus this equation

implies $\bar{G}^t(r_a, r_b) = \bar{G}(r_b, r_a)$. Thus Eqn.(2) of Ch.II is proved.
This equation may also be written as: - $\bar{E}_s(r) = -jw u_0 \int_V \bar{G}_e(r, r') \cdot \bar{J}(r') dv'$ (*)
With this Eqn(2) of Ch.II may be proved in an analogous way, implying "componentwise correspondence" & implying "correspondence as a whole".

we can prove Eqn (9) of Ch.II with $\bar{E}_s(r) \Rightarrow \bar{G}_m(r, r')$, $\bar{J}(r') \Rightarrow \nabla'' \times \bar{I}d(r-r')$ and $\bar{G}_e(r, r') \Rightarrow \bar{g}_m(r, r')$ in Eqn (*).

It is to be noted that radiation condition stated above is the modified waveguide version of the free space radiation condition and rests on the condition that at the large distance from the source $V' \times \bar{G}_e(r', r) \approx jk \bar{Z} X \bar{G}_e(r', r)$
N.B. In above correspondence relations $E_s(r)$, $\bar{G}_e(r, r')$, $J(r')$ are with respect to coordinate origin and $G_m(r, r')$, $\bar{g}_m(r, r')$, $\nabla'' \times \bar{I}d(r-r')$ are with respect to r' as origin of the relevant coordinate system.

Appendix-II.

On the mode completeness relation (18) of Ch.-II. [8]
 With normal mode function separable into a transverse part E_n and an axial
 part E_{2n} & constant coordinate curves coinciding with waveguide boundary,
 Let E_t be an arbitrary transverse electric field in a given

guide. The normal mode functions e_n form a complete set,

provided the integrated mean square error in representing

or approximating E_t by a finite series of N normal mode

functions tends to zero as N tends to infinity. If we

approximate E_t by $E_a = \sum_{n=1}^N c_n e_n$ where c_n is given by

$$c_n = \langle E_t, e_n \rangle = \int S E_t, e_n ds , \text{ we have}$$

$$\langle E_t - E_a, E_t - E_a \rangle = \int S (E_t - E_a) \cdot (E_t - E_a) ds \geq 0$$

$$\text{or } \langle E_t, E_t \rangle - 2 \langle E_a, E_t \rangle + \langle E_a, E_a \rangle \geq 0$$

Assuming that the functions e_n form an orthonormal set

such that $\langle e_n, e_m \rangle = \int S e_n, e_m ds = \delta_{mn} = \begin{cases} 0 & \text{for } n \neq m \\ 1 & \text{for } n = m \end{cases}$

$$\langle E_t, E_t \rangle - 2 \left\langle \sum_{n=1}^N c_n e_n, E_t \right\rangle + \left\langle \sum_{n=1}^N c_n e_n, \sum_{n=1}^N c_n e_n \right\rangle \geq 0$$

$$\text{or } \langle E_t, E_t \rangle - 2 \sum_{n=1}^N c_n \langle e_n, E_t \rangle + \sum_{n=1}^N c_n^2 \geq 0$$

$$\text{or } \langle E_t, E_t \rangle - 2 \sum_{n=1}^N c_n^2 + \sum_{n=1}^N c_n^2 \geq 0$$

$$\text{or } \langle E_t, E_t \rangle - \sum_{n=1}^N c_n^2 \geq 0$$

If, when N tends to infinity

$$\langle E_t, E_t \rangle = \sum_{n=1}^{N \rightarrow \infty} c_n^2 = 0$$

then we say that the mode set e_n is complete. This is also called the closure property of the set e_n . E_t must be at least piecewise continuous, if the above equality equation is to be valid. Physical fields are, of course, sufficiently well behaved to satisfy these requirements.

An equivalent statement of the completeness property is the following relation:-

$$\sum_n e_n(x', y') e_n(x, y) = (\bar{x}\bar{x} + \bar{y}\bar{y}) d(x-x') d(y-y') = I_2 \delta(x-x') \delta(y-y')$$

~~at x=x' and y=y'~~ where I_2 is the 2-dimensional unit dyadic.

This equation is seen to be the expansion of the unit.

~~source~~ of this comes on the right hand side. The validity of this relation involving delta function may be checked by scalar-post-multiplying both sides by $e_m(x, y)$ and integrating over the guide cross-section.

$$\text{Thus LHS} = \sum_n e_n(x', y') \int_S e_n(x, y) \cdot e_m(x, y) ds = \sum_n e_n(x', y') \delta_{mn}$$

$$= e_m(x', y') \quad \left[\text{By orthogonal property of } e_n \right] \text{ and}$$

$$\text{RHS} = \int_S I_2 \cdot e_m(x, y) d(x-x') d(y-y') ds = e_m(x', y')$$

$$\left[\text{By the property of delta function} \right]$$

Using the above mode completeness relation the expansion for an arbitrary field E_t follows by superposition i.e.

$$\begin{aligned}
 E_t(x, y) &= \int_S E_t(x', y') \cdot \bar{e}_n(x-x') d(y-y') dx' dy' \\
 &= \sum_n \int_S E_t(x', y') e_n(x', y') e_n(x, y) dx' dy' \\
 &\quad \cancel{\int_S \left(E_t(x', y') e_n(x', y') e_n(x, y) \right) dx' dy'} \\
 &= \sum_n c_n \Theta_n(x, y)
 \end{aligned}$$

It is to be noted that apart from its use in the representation of an arbitrary field E_t relation like the completeness relation having an infinite sine and cosine function series on one side & scalar $d(x-x') d(y-y')$ function on the other may be considered to be the purely mathematical expansion function representing $d(x-x') d(y-y')$ whose validity is proved by multiplying by a testing function on both sides and integrated over an infinite ~~xy~~-plane. In waveguide cases, the testing function reduces to an eigenfunction, and the infinite ~~xy~~ plane reduces to the waveguide cross-section.

This set of equations can be written in matrix form as

$$(l_{mn}) (\mathbf{f}_n) = (g_m) \quad \dots \quad \dots \quad \dots \quad (5).$$

where $(l_{mn}) = \begin{pmatrix} \langle w_2, Lf_2 \rangle & \langle w_1, Lf_2 \rangle & \dots & \dots & \dots \\ \langle w_2, Lf_1 \rangle & \langle w_2, Lf_2 \rangle & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \end{pmatrix}$

$$(\mathbf{f}_n) = \begin{pmatrix} f_1 \\ f_2 \\ \vdots \end{pmatrix}; \quad (g_m) = \begin{pmatrix} \langle w_1, g \rangle \\ \langle w_2, g \rangle \\ \vdots \end{pmatrix}$$

If the matrix (l_{mn}) is nonsingular its inverse $(l_{mn})^{-1}$ exists,

$$\text{In that case } (\mathbf{f}_n) = (l_{mn})^{-1} (g_m) \quad \dots \quad \dots \quad (6)$$

$$\text{and } f = \overbrace{(\mathbf{f}_n)}^{\checkmark} (\mathbf{f}_n) = \overbrace{(\mathbf{f}_n)}^{\checkmark} (l_{mn})^{-1} (g_m) \quad \dots \quad \dots \quad (7).$$

$$\text{where matrix } (\mathbf{f}_n) = (f_1, f_2, f_3 \dots \dots)$$

The solution may be exact or approximate, depending on the choice of f_n and w_m . If the matrix (l_{mn}) is of infinite order, it can be inverted only in special cases, for example, if it is diagonal. The classical eigenfunction method leads to a diagonal matrix and can be thought of as a special case of method of moments. If the sets f_n and w_m are finite, the matrix is of finite order, and can be inverted by known methods. The main task in the matrization of the functional equation by the moment method is the choice of f_n and w_m . The f_n should be linearly independent and chosen so that some sorts of superposition like that in Eqn(2) can approximate f reasonably well. The w_m should also be linearly independent and chosen so that the scalar products $\langle w_m, g \rangle$ depend on relatively independent properties of g . Some additional factors which affect the choice

Thus for $N=1$, $I_{11} = \frac{1}{3}$, $g_1 = \frac{11}{30}$ and $L_1 = \frac{11}{20}$ from Eqn(5)

For $N=2$,

$$\begin{pmatrix} \frac{1}{3} & \frac{1}{2} \\ \frac{1}{2} & \frac{4}{5} \end{pmatrix} \begin{pmatrix} L_1 \\ L_2 \end{pmatrix} = \begin{pmatrix} \frac{11}{30} \\ \frac{7}{12} \end{pmatrix} \Rightarrow \begin{pmatrix} L_1 \\ L_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{10} \\ \frac{2}{3} \end{pmatrix}$$

For $N=3$,

$$\begin{pmatrix} \frac{1}{3} & \frac{1}{2} & \frac{3}{5} \\ \frac{1}{2} & \frac{4}{5} & 1 \\ \frac{3}{5} & 1 & \frac{9}{7} \end{pmatrix} \begin{pmatrix} L_1 \\ L_2 \\ L_3 \end{pmatrix} \neq \begin{pmatrix} 11/30 \\ 7/12 \\ 51/70 \end{pmatrix} \Rightarrow \begin{pmatrix} L_1 \\ L_2 \\ L_3 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ 0 \\ \frac{1}{3} \end{pmatrix}$$

For $N=3$ we obtain the exact solution $f = \sum_{n=1}^{N=3} f_n L_n$

For $N \geq 3$ we obtain the same exact solution.

Solution by Point matching method with entire domain basis

With $f_n = x - x_m^{n+1}$. Let $x_m = \frac{m}{N+1}$, $m = 1, 2, 3, \dots, N$ be the

equipaced points in the interval $0 \leq x \leq 1$ at which the

equation is to be satisfied exactly. For this we let

$w_m = d(x - x_m)$ and we have $I_{mn} = n(n+1) \left(\frac{m}{N+1}\right)^{n-1}$,

$$g_m = 1 + 4 \left(\frac{m}{N+1}\right)^2$$

Thus for $N=1, N=2$ we again have an approximate. Solution and for $N \geq 3$, we have the exact solution.

Solution by Subsectional bases:

With $x_m = \frac{m}{N+1}$, $m = 1, 2, 3, \dots, N$ as the equispaced points in the interval $0 \leq x \leq 1$, let $f_n = P(x - x_m)$ or

$$f_n = \prod_{m=1}^N (x - x_m)$$

- : 41 :-

where pulse function $P(x) = \begin{cases} 1 & |x| < \frac{1}{2(N+1)} \\ 0 & |x| > \frac{1}{2(N+1)} \end{cases}$ and triangle

function $T(x) = 1 - |x|/(N+1)$

for $|x| < \frac{1}{N+1}$

$T(x) = 0$ for $|x| > \frac{1}{N+1}$

Since L [P(x)] functions are not in the range of L. We

take $f_n = T(x-x_n)$, $L T(x-x_n) = (N+1) \left[-d(x-x_{n-1}) + 2d(x-x_n) - d(x-x_{n+1}) \right]$

Choosing $w_m = P(x-x_m)$, $I_{mn} = \begin{cases} 2(N+1) & m=n \\ -(N+1) & |m-n|=1 \\ 0 & |m-n|>1 \end{cases}$

$g_m = \frac{1}{N+1} \left[1 + \frac{4m^2 + \frac{1}{3}}{(N+1)^2} \right]$; N = 5 yields discrete values of f, coinciding with exact f(x).

Art-2: Solution of the obstacle problem by the point-matching method of moment:

Although there exists numerical methods by which the integral operator obstacle equation could be solved numerically, the complexity of three-dimensional and the dyadic green's function involved indicates that further computational complication in the scalar multiplication process of matrizing the functional equation must be avoided as far as possible. This naturally implies that point-matching method of moment may be adopted for the obstacle problem. Even in the relatively simple case of plane wave incidence on obstacles in un-bounded free space, only point-matching method together with rectangularly sided cells has been attempted for the volume type

of integral equations(10). Fortunately, this process has been found to be capable of producing good numerical results(7). Thus point-matching method with rectangularly sided cells is employed in the present analysis.

The volume V occupied by the dielectric is first divided into L equal rectangular-sided cells ΔV_i , $i = 1, 2, \dots, L$, each of which has constant dimensions $\Delta X, \Delta Y$ and ΔZ . The incident electric field, assumed to be uniform inside the i th cell is designated $E_i(r_i)$, where r_i represents the centre of the i th cell.

The corresponding current in the dielectric may be expressed as $J(r) = \sum_{l=1}^L \sum_{k=1}^3 \bar{u}_k j_k^l P_l^k(r) \dots \quad \dots (1)$

where \bar{u}_k denotes a unit vector and $P_l^k(r) = \begin{cases} 1 & \text{for } r \text{ in } \Delta V_i \\ 0 & \text{otherwise} \end{cases}$
and $\bar{u}_1 = \bar{x}, \bar{u}_2 = \bar{y}, \bar{u}_3 = \bar{z}$,

The equation to be solved is :- [Eqn(17) Ch-II Art-I].

$$-jw\mu_0 \int \bar{G}_{eo}(r, r') \cdot J(r') dv' - \frac{J(r)}{jw[e(r) - e_0]} - \frac{(Z \cdot J(r) \bar{z})}{jw\epsilon(r)} = -E_i(r) \quad \dots \quad \dots (2)$$

$$\bar{G}_{eo}(r) = \dots \quad \dots \quad \dots \quad \dots (2)$$

In the point matching method we generate a set of linear equations by first substituting Eqn(1) into Eqn(2) and then performing a scalar product on the resulting equation with the testing function $w_p^q(r) = d(r-r_q) \bar{u}_p$ for $p=1,2,3$ and $q=1,2, \dots, L$.

where \bar{u}_p is a unit vector.

The scalar product between vectors f and g is defined as

$$\langle f, g \rangle = \int_V f \cdot g dv$$

$$\text{Thus } \langle w_q^p(r), e_i(r) \rangle = - \int_V d(r-r_q) \bar{U}_p \cdot E_i(r) dv'$$

$$= - \int_V d(r-r_q) E_i^p(r) dv' = -E_i^p(r_q) = C_{qV}^{p,q} \text{ for } p = 1, 2, 3$$

q = 1, 2, ..., L.

$$\left\langle w_q^p(r), \frac{[\bar{e}_j(r)] \bar{z}}{jw e(r)} \right\rangle = \left\langle w_q^p(r), \underbrace{\left[\bar{U}_3 \cdot \sum_{l=1}^L \sum_{k=1}^3 \bar{U}_k J_k^l P^l(r) \right] \bar{U}_3}_{jw e(r)} \right\rangle$$

$$= \int_V \frac{d(r-r_q)}{jw e(r)} \left[\bar{U}_3 \cdot \sum_{l=1}^L \sum_{k=1}^3 \bar{U}_k J_k^l P^l(r) \right] \bar{U}_3 dv'$$

$$= \int_V \sum_{k=1}^3 \sum_{l=1}^L \frac{J_k^l}{jw e(r)} \left[\frac{d_p}{d_3}, \frac{d_k}{d_3} \right] P^l(r) d(r-r_q) dv'$$

$$= \sum_{k=1}^3 \sum_{l=1}^L \frac{J_k^l d_q^l}{jw e(r)} \left[\frac{d_p}{d_3}, \frac{d_k}{d_3} \right] \text{ for } p=1, 2, 3 \text{ and } q=1, 2, \dots, L.$$

$$\left\langle w_q^p(r), \frac{J(r)}{jw [e(r) - e_o]} \right\rangle = \int_V d(r-r_q) \bar{U}_p \cdot \frac{\sum_{k=1}^L \sum_{l=1}^3 \bar{U}_k J_k^l P^l(r)}{jw [e(r) - e_o]} dv'$$

$$= \int_V \sum_{k=1}^3 \sum_{l=1}^L \frac{J_k^l d_k^l P^l(r)}{jw [e(r) - e_o]} d(r-r_q) dv' = \frac{\sum_{k=1}^3 \sum_{l=1}^L J_k^l d_k^l}{jw [e(r) - e_o]}$$

$$= \sum_{k=1}^3 \sum_{l=1}^L \frac{d_q^l d_k^l}{jw [e(r_q) - e_o]} \text{ for } l=1, 2, 3 \text{ & } q = 1, 2, \dots, L.$$

$$\text{N.B. } \int_V P^l(r) d(r-r_q) dv' = P^l(r_q) = d_q^l$$

$$\text{Rewriting } \int_V \bar{G}_{eo}^{pk}(r, r') J(r') dv' = \int_V \left[\sum_{k=1}^3 \bar{U}_k \sum_{l=1}^3 \bar{U}_k G_{eo}^{pk}(r, r') \right]$$

$$\left\{ \sum_{k=1}^3 \bar{u}_k \left[\sum_{l=1}^L J_1^k P^1(r') \right] dv' \right\} = \left\{ \sum_{p=1}^3 \bar{u}_p \sum_{k=1}^3 \int_{\Delta V_k} G_{eo}^{pk}(r, r') dv' \right\}$$

$$\left\{ \sum_{l=1}^L J_1^k P^1(r') dv' \right\} = \cancel{\sum_{p=1}^3 \bar{u}_p} \left\{ \sum_{p=1}^3 \bar{u}_p \sum_{k=1}^3 \frac{1}{L} \sum_{l=1}^L J_1^k \int_{\Delta V_k} G_{eo}^{pk}(r, r') dv' \right\}$$

For a fixed p and q in the scalar multiplication $\left[\begin{smallmatrix} p \\ q \end{smallmatrix} \right]$,

$$\begin{aligned} & j w u_o \int_{\Delta V_k} G_{eo}^{pk}(r, r') \cdot J(r') dv' \cancel{\left[\begin{smallmatrix} p \\ q \end{smallmatrix} \right]} \cancel{\int_{\Delta V_k} G_{eo}^{pq}(r, r') \cdot J(r') dv'} \\ & = j w u_o \int_{\Delta V_k} \left[d(r - r_q) \bar{u}_p \right] \left[\bar{u}_p \sum_{k=1}^3 \sum_{l=1}^L J_1^k \int_{\Delta V_k} G_{eo}^{pk}(r, r') dv' \right] dv' \\ & = j w u_o \sum_{k=1}^3 \sum_{l=1}^L J_1^k \int_{\Delta V_k} G_{eo}^{pk}(r_q, r') dv' \quad \text{for } p=1, 2, 3 \text{ and } q=1, 2, \dots, L. \end{aligned}$$

Hence this point-matching moment method yields the following set of linear equations:-

$$\sum_{k=1}^3 \sum_{l=1}^L J_1^k A_{1q}^{pk} = -C_q^p \quad (3) \text{ where } C_q^p = +E_i^p(r_q) \dots (3a)$$

$$\text{and } A_{1q}^{pk} = -j w u_o \cdot Q_{1q}^{pk} - \frac{d_q^1}{j w} \left[\frac{d_k^p}{e(r_q) - e_0} + \frac{d_k^p d_3^p}{e(r_q) - e_0} \right] \dots (3b).$$

$$\text{wherein } Q_{1q}^{pk} = \frac{1}{\Delta V_k} \int_{\Delta V_k} G_{eo}^{pk}(r_q, r') dv'$$

When expanded and put in matrix form Eqn 3(a) appears as:-

$Q_{11}^{11}, Q_{11}^{12}, Q_{11}^{13}$	$Q_{21}^{11}, Q_{21}^{12}, Q_{21}^{13}$	$Q_{L1}^{11}, Q_{L1}^{12}, Q_{L1}^{13}$	J_1^1
$Q_{11}^{21}, Q_{11}^{22}, Q_{11}^{23}$	$Q_{21}^{21}, Q_{21}^{22}, Q_{21}^{23}$	$Q_{L1}^{21}, Q_{L1}^{22}, Q_{L1}^{23}$	J_2^2
$Q_{11}^{31}, Q_{11}^{32}, Q_{11}^{33}$	$Q_{21}^{31}, Q_{21}^{32}, Q_{21}^{33}$	$Q_{L1}^{31}, Q_{L1}^{32}, Q_{L1}^{33}$	J_3^3
$Q_{12}^{11}, Q_{12}^{12}, Q_{12}^{13}$	$Q_{22}^{11}, Q_{22}^{12}, Q_{22}^{13}$	$Q_{L2}^{11}, Q_{L2}^{12}, Q_{L2}^{13}$	J_2^1
$Q_{12}^{21}, Q_{12}^{22}, Q_{12}^{23}$	$Q_{22}^{21}, Q_{22}^{22}, Q_{22}^{23}$	$Q_{L2}^{21}, Q_{L2}^{22}, Q_{L2}^{23}$	J_2^2
$Q_{12}^{31}, Q_{12}^{32}, Q_{12}^{33}$	$Q_{22}^{31}, Q_{22}^{32}, Q_{22}^{33}$	$Q_{L2}^{31}, Q_{L2}^{32}, Q_{L2}^{33}$	J_2^3
$Q_{1L}^{11}, Q_{1L}^{12}, Q_{1L}^{13}$	$Q_{2L}^{11}, Q_{2L}^{12}, Q_{2L}^{13}$	$Q_{LL}^{11}, Q_{LL}^{12}, Q_{LL}^{13}$	J_1^1
$Q_{1L}^{21}, Q_{1L}^{22}, Q_{1L}^{23}$	$Q_{2L}^{21}, Q_{2L}^{22}, Q_{2L}^{23}$	$Q_{LL}^{21}, Q_{LL}^{22}, Q_{LL}^{23}$	J_1^2
$Q_{1L}^{31}, Q_{1L}^{32}, Q_{1L}^{33}$	$Q_{2L}^{31}, Q_{2L}^{32}, Q_{2L}^{33}$	$Q_{LL}^{31}, Q_{LL}^{32}, Q_{LL}^{33}$	J_1^3

where the primed diagonal elements corresponding to Eqn(17)

of Ch.II for $\mu_0, e(r)$ medium are :-

$$Q_{11}^{11} = Q_{11}^{11} - \left[\frac{1}{k_1^2 (r_1) - k_o^2} \right], \quad Q_{11}^{22} = Q_{11}^{22} - \left[\frac{1}{k_1^2 (r_1) - k_o^2} \right].$$

$$Q_{11}^{33} = Q_{11}^{33} - \left[\frac{1}{K_1^2(r)} + \frac{1}{K_0^2(r)} \right]) \quad .. \quad (4)$$

$$Q'_{22} = Q_{22} - \left[\frac{1}{k_1^2(r_2) - k_o^2} \right], \quad Q'_{22} = \left[\frac{1}{k_1^2(r_2) - k_o^2} \right],$$

$$Q'_{22} = Q_{22} - \left[\frac{1}{k_1^2(r_2) - k_o^2} + \frac{1}{k_1^2(r_2)} \right]$$

$$Q'_{44} = Q_{44} - \left[\frac{1}{k_1^2(r_L) - k_o^2} \right], \quad Q'_{LL} = Q_{LL} - \left[\frac{1}{k_1^2(r_L) - k_o^2} \right],$$

$$Q'_{LL} = Q_{LL} - \left[\frac{1}{k_1^2(r_L) - k_o^2} + \frac{1}{k_1^2(r_L)} \right]$$

and where the primed diagonal elements corresponding to Eqn (13) of Ch.II, for μ_o , ϵ_o medium are :-

$$Q'_{11} = Q_{11} - \left[\frac{1}{\frac{2}{k_1^2(r_1) - k_o^2}} \right], \quad Q'_{11} = Q_{11} - \left[\frac{1}{k_1^2(r_1) - k_o^2} \right],$$

$$Q'_{11} = Q_{11} - \left[\frac{1}{k_1^2(r_1) - k_o^2} + \frac{1}{k_o^2} \right],$$

$$Q'_{22} = Q_{22} - \left[\frac{1}{k_1^2(r_2) - k_o^2} \right], \quad Q'_{22} = Q_{22} - \left[\frac{1}{k_1^2(r_2) - k_o^2} \right],$$

$$Q'_{22} = Q_{22} - \left[\frac{1}{k_1^2(r_2) - k_o^2} + \frac{1}{k_o^2} \right]$$

$$Q'_{LL} = Q_{LL} - \left[\frac{1}{k_1^2(r_L) - k_o^2} \right], \quad Q'_{LL} = Q_{LL} - \left[\frac{1}{k_1^2(r_L) - k_o^2} \right],$$

$$Q'_{LL} = Q_{LL} - \left[\frac{1}{k_1^2(r_L) - k_o^2} + \frac{1}{k_o^2} \right]$$

It is to be noted that in Equation(4) subscript indices q &/or l refer to the position vector and the superscript indices p & /or k refer to the unit vectors \hat{x} , \hat{y} , \hat{z} .

For finding the integral $Q_{1q}^{pk} = \int_{\Delta V_q} G_{eo}^{pk}(r_q, r') dv'$ we use the following relations:-

$$\begin{aligned} \int_{x_1 - \frac{\Delta x_k}{2}}^{x_1 + \frac{\Delta x_k}{2}} \sin \frac{n\pi x'}{a} dx' &= \sin \frac{n\pi x_1}{a} \left[\frac{\sin(n\pi \Delta x_k/2a)}{(n\pi/2a)} \right]; \quad \int_{x_1 - \frac{\Delta x_k}{2}}^{x_1 + \frac{\Delta x_k}{2}} \cos \frac{n\pi x'}{a} dx' \\ &= \cos \frac{n\pi x_1}{a} \left[\frac{\sin(n\pi \Delta x_k/2a)}{(n\pi/2a)} \right]; \\ \int_{y_1 - \frac{\Delta y_l}{2}}^{y_1 + \frac{\Delta y_l}{2}} \sin \frac{m\pi y'}{b} dy' &= \sin \frac{m\pi y_1}{b} \left[\frac{\sin(m\pi \Delta y_l/2b)}{(m\pi/2b)} \right] \\ \int_{y_1 - \frac{\Delta y_l}{2}}^{y_1 + \frac{\Delta y_l}{2}} \cos \frac{m\pi y'}{b} dy' &= \cos \frac{m\pi y_1}{b} \left[\frac{\sin(m\pi \Delta y_l/2b)}{(m\pi/2b)} \right] \end{aligned}$$

For $z_q \neq z_1$ cases

$$\begin{aligned} I = I_1 &= \int_{z_1 - \frac{\Delta z_l}{2}}^{z_1 + \frac{\Delta z_l}{2}} e^{-jk_{nm}|z_q - z'|} dz' \text{ for } z_q > z' \quad \left[z_1 - \frac{\Delta z_l}{2} \leq z' \leq z_1 + \frac{\Delta z_l}{2} \right] \\ &= \begin{cases} \int_{z_1 - \frac{\Delta z_l}{2}}^{z_1 + \frac{\Delta z_l}{2}} e^{-jk_{nm}(z_q - z')} dz' \text{ for } z_q > z' \\ \int_{z_q - \frac{\Delta z_l}{2}}^{z_q + \frac{\Delta z_l}{2}} e^{-jk_{nm}(z_q - z')} dz' \text{ for } z_q < z' \\ \frac{2}{K_{nm}} e^{-jk_{nm}(z_q - z_1)} \sin K_{nm} \frac{\Delta z_l}{2} \text{ for } z_q > z' \end{cases} \\ &= \begin{cases} \frac{2}{K_{nm}} e^{jk_{nm}(z_q - z_1)} \sin K_{nm} \frac{\Delta z_l}{2} \text{ for } z_q < z' \\ \frac{2}{K_{nm}} e^{-jk_{nm}|z_q - z_1|} \sin K_{nm} \frac{\Delta z_l}{2} \text{ for } z_q > z_1. \end{cases} \end{aligned}$$

For $Z_q = Z_1$ cases with $p_k = 11, 22, 33, 12, 21$

$$I = I_2 = \int_{Z_1 - \frac{\Delta Z_1}{2}}^{Z_1} e^{-jKnm(Z_q - Z')} dz' \quad (\text{for } Z_q > Z') + \int_{Z_1}^{Z_1 + \frac{\Delta Z_1}{2}} e^{jKnm(Z_q - Z')} dz \quad (\text{if } Z_q < Z')$$

$$(\text{for } Z_q = Z_1) = \left\{ e^{-jKnm \frac{\Delta Z_1}{2}} - 1 \right\} \frac{2 \cos Knm(Z_q - Z_1)}{jKnm}$$

$$= \frac{2}{jKnm} \left(e^{-jKnm \frac{\Delta Z_1}{2}} \right) \text{ for } Z_q = Z_1$$

For $Z_q = Z_1$ cases : with $p_k = 32, 23, 31, 13$.

$$I = I_3 = \pm \left\{ \int_{Z_1 - \frac{\Delta Z_1}{2}}^{Z_1} e^{-jKnm(Z_q - Z')} dz' \quad (\text{for } Z_q > Z') \right.$$

$$\left. - \int_{Z_1}^{Z_1 + \frac{\Delta Z_1}{2}} e^{jKnm(Z_q - Z)} dz' \quad (\text{for } Z_q < Z) \right\} = \pm \left\{ \frac{jKnm \frac{\Delta Z_1}{2}}{2} - 1 \right\} \frac{2 \sin Knm(Z_q - Z_1)}{Knm}$$

$$= 0 \text{ for } Z_q = Z_1$$

With these integrations carried out Q_{1q}^{pk} takes the following

$$\text{form : - } Q_{1q}^{pk} = \frac{j}{2abK_n^2} \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} \frac{Q_{on} \Psi_{om}'}{K_{nm}} I_{Qk}^{pk} \quad (5)$$

$$\text{where } I = \begin{cases} I_1 & \text{for } Z_q \neq Z_1 \text{ & for all } p_k \text{ values} \\ I_2 & \text{for } Z_q \neq Z_1 \text{ & for } p_k = 11, 22, 33, 12, 21 \\ I_3 = 0 & \text{for } Z_q = Z_1 \text{ & for } p_k = 32, 33, 31, 13 \end{cases}$$

$$Q = \left[\frac{\sin(n\pi \Delta x_1/2a)}{(n\pi/2a)} \right] \left[\frac{\sin(m\pi \Delta y_1/2b)}{(m\pi/2b)} \right]$$

$$F_{nm}^{pk} = \left[\text{the } (n,m) \text{th term of } G_{eo}^{pk} (r_q, r_l) \right] \cdot e^{j k n m |z_q - z_l|}$$

N.B., For $pk = 23, 32, 31, 15$ F_{nm}^{pk} includes the \pm sign depending

on $z_q > z_l$ or $z_q < z_l$. $pk = 23$ implies $p = 2$ and $k = 3$;
 $pk = 32$ implies $p = 3$ and $k = 2$ & so on.

Art-3: (a) Evaluation Formulas for Q_{lq}^{pk} elements with $z_q \neq z_l$

$z_q \neq z_l$. With $z_q \neq z_l$, the Q_{lq}^{pk} elements have the exponential

factor $e^{-jk_{nm}|z_q - z_l|} = e^{-G_{nm}|z_q - z_l|}$. Except for the

few terms with first few terms with first few values of n and

m all the remaining terms of a Q_{lq}^{pk} element are real. If G_{nm}

$$\text{is real i.e. } \left[\left(\frac{n\pi}{a} \right)^2 + \left(\frac{m\pi}{b} \right)^2 \right] > k_o^2$$

then the double infinite series terms of Q_{lq}^{pk} decrease rapidly

with increasing n and m . Therefore a Q_{lq}^{pk} element terms with

real G_{nm} can be computed with a finite series truncated

according to a precision criterion established by the value

of $G_{nm} |z_q - z_l|$. Depending on the value of $|z_q - z_l|$ approxima-

tely 16x8 upto 21x12 terms were used for n and m in the

typical examples reported in a paper by J.J.H.Wang(7)

To this value of the truncated series we add the few terms

(usually 2 or so) with imaginary G_{nm} to obtain the value of

a Q_{lq}^{pk} element.

In order to develop working formulas and expressions for summing the double infinite series we proceed as follows:-

Rewriting Q_{1q}^{pk} as follows

$$Q_{1q}^{pk} = C \sum_{n=0}^{\infty} e_{on} Q_{1q}^{pk}(n) \sum_{m=0}^{\infty} e'_{om} b_{1q}^{pk}(n,m)$$

$$\text{where } C = \frac{1}{2abk_0^2}$$

$a_{1q}^{pk}(n)$ is the part of Q_{1q}^{pk} comprising sine and cosine functions involving n only and the factor $\frac{1}{n}$ (if any)

$b_{1q}^{pk}(n,m)$ is the part of Q_{1q}^{pk} comprising sine and cosine functions involving m only and a factor involving m , $E_{nm} = jK_{nm}$,

jK_{nm} , and $\frac{-G_{nm}[Z_{q1}] \sinh G_{nm} \Delta z_l}{2}$

Expanding Q_{1q}^{pk} we have :-

$$Q_{1q}^{pk} = C \left[a_{1q}^{pk}(0) \sum_{m=0}^{\infty} e'_{om} b_{1q}^{pk}(0,m) \right] + C \left[a_{1q}^{pk}(1) \sum_{m=0}^{\infty} e'_{om} b_{1q}^{pk}(1,m) \right] + \dots$$

$$+ C \left[2a_{1q}^{pk}(NT) \sum_{m=0}^{\infty} e'_{om} b_{1q}^{pk}(NT,m) \right] + \dots$$

Now $a_{1q}^{pk}(0) b_{1q}^{pk}(0,0) = 0$ for all pk

$a_{1q}^{pk}(0) = 0$ for all pk except $pk = 11$

$b_{1q}^{pk}(NT,0) = 0$ for all pk except $pk = 22, NT = 1, 2, 3 \dots$
 [chosen for a particular function]

Thus we have (expanding upto $n=NT$ & $m = MT$)

$$\left. \begin{aligned}
 Q_{1q}^{11} &= 2C a_{1q}^{11}(0) \sum_{m=1}^{MT} b_{1q}^{11}(0, m) + 4C \sum_{n=1}^{NT} a_{1q}^{11}(n) \sum_{m=1}^{MT} b_{1q}^{11}(n, m) \\
 Q_{1q}^{22} &= 2C \sum_{n=1}^{NT} a_{1q}^{22}(n) b_{1q}^{22}(n, 0) \\
 + 4C \sum_{n=1}^{NT} a_{1q}^{22}(n) \sum_{m=1}^{MT} b_{1q}^{22}(n, m) \\
 Q_{1q}^{pk} &= 4C \sum_{n=1}^{NT} a_{1q}^{pk}(n) \sum_{m=1}^{MT} b_{1q}^{pk}(n, m) \text{ for other pk values}
 \end{aligned} \right\} \quad \boxed{1}$$

Similarly we may rewrite Q_{1q}^{pk} as follows :-

$$Q_{1q}^{pk} = C \sum_{m=0}^{\infty} e_{om}^r b_{1q}^{pk}(m) + \sum_{n=0}^{\infty} e_{on} a_{1q}^{pk}(n, m)$$

$$\text{Where } C = \frac{1}{2abk_0^2}$$

$b_{1q}^{pk}(m)$ is the part of Q_{1q}^{pk} Comprising Sine and Cosine

functions involving m only and the factor $\frac{1}{m}$ (if any)

$Q_{1q}^{pk}(n, m)$ is the part of Q_{1q}^{pk} Comprising Sine and Cosine

functions involving n only and a factor involving $n, m, G_{nm} = j K_{nm}$

$$\text{and } Q = G_{nm} |z_q|^2 z_1 \\ \cdot \sinh G_{nm} \frac{z_1}{2} \quad \begin{array}{l} \text{when } z_1 \neq 0 \\ \text{for } q \neq 1 \\ (z_q \neq z_1) \text{ for } q \neq 1 \end{array}$$

Expanding Q_{1q}^{pk} we have :-

$$Q_{1q}^{pk} = C \left[b_{1q}^{pk} (0) \sum_{n=0}^{\infty} e_{en} a_{1q}^{pk} (n, 0) \right] + C \left[2b_{1q}^{pk} (1) \sum_{n=0}^{\infty} e_{en} a_{1q}^{pk} (n, 1) \right] \\ + \dots + C \left[2b_{1q}^{pk} (MT) \sum_{n=0}^{\infty} e_{en} a_{1q}^{pk} (n, MT) \right] + \dots \\ = C \left[b_{1q}^{pk} (0) a_{1q}^{pk} (0, 0) + 2b_{1q}^{pk} (0) \sum_{n=1}^{\infty} a_{1q}^{pk} (n, 0) \right] + \dots \\ + C \left[2b_{1q}^{pk} (1) a_{1q}^{pk} (0, 1) + 4b_{1q}^{pk} (1) \sum_{n=1}^{\infty} a_{1q}^{pk} (n, 1) \right] \dots \dots \\ + C \left[2b_{1q}^{pk} (MT) a_{1q}^{pk} (0, MT) + 4b_{1q}^{pk} (MT) \sum_{n=1}^{\infty} a_{1q}^{pk} (n, MT) \right] + \dots$$

$$\text{Now } b_{1q}^{pk} (0) a_{1q}^{pk} (0, 0) = 0 \text{ for all } pk$$

$b \frac{pk}{lq} (0) = 0$ for all pk except $pk = 22$

$a \frac{pk}{lq} (0, MT) = 0$ for all pk except $pk = 11$, $MT = 1, 2, 3, \dots$
 [chosen for a particular truncation]

Thus we have (expanding up to $n = NT$ & $m = MT$)

$$Q \frac{11}{lq} = 2C \sum_{m=1}^{MT} b \frac{11}{lq} (m) a \frac{11}{lq} (0, m) + 4C \sum_{m=1}^{MT} b \frac{11}{lq} (m) \sum_{n=1}^{NT} Q \frac{pk}{lq} (n, m)$$

$$Q \frac{22}{lq} = 2C b \frac{22}{lq} (0) \sum_{n=1}^{NT} a \frac{22}{lq} (n, 0) + \dots \quad \text{II}$$

$$\pm 4C \sum_{m=1}^{MT} b \frac{22}{lq} (m) \sum_{n=1}^{NT} a \frac{22}{lq} (n, m)$$

$$Q \frac{pk}{lq} = 4C \sum_{m=1}^{MT} b \frac{pk}{lq} (m) \sum_{n=1}^{NT} a \frac{pk}{lq} (n, m) \text{ for other } pk \text{ values}$$

Either of the Equation I or Equation II may be used for evaluation

of the double series of $Q \frac{pk}{lq}$ elements according to convenience.

The explicit expressions for $Q \frac{pk}{lq}$ elements for various pk

are as follows :- [for a specific problem the few imaginary G_{nm} terms
 of a $Q \frac{pk}{lq}$ element can easily be picked up]

Using Equation I

$$Q_{1q}^{11} = \left\{ 2C \left(\frac{4b}{\pi} \Delta x_1 \right) \sum_{n=1}^{NT} \frac{k_o^2 - G_{nm} |z_q - z_1|}{n G_{nm}^2} \cdot \sin h G_{nm} \frac{\Delta z_1}{2} \sin \frac{n\pi y_q}{b} \right. \\ \left. \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b} \right\} \\ + \left\{ 4C \left(\frac{8ab}{\pi^2} \right) \sum_{n=1}^{NT} \frac{1}{n} \cos \frac{n\pi x_q}{a} \cos \frac{n\pi x_1}{a} \sin \frac{m\pi y_q}{b} \sin \frac{m\pi \Delta y_1}{2b} \right. \\ \left. - G_{nm} |z_q - z_1| Q \sin h G_{nm} \frac{\Delta z_1}{2} \sin \frac{m\pi y_q}{b} \sin \frac{m\pi \Delta y_1}{2b} \right\} \quad (21.1)$$

Using Equation II

$$Q_{1q}^{22} = \left\{ 2C \left(\frac{4a}{\pi} y_1 \right) \sum_{n=1}^{NT} \frac{k_o^2 - G_{no} |z_q - z_1|}{n G_{no}^2} \cdot \sin h G_{no} \frac{\Delta z_1}{2} \sin \frac{n\pi x_q}{a} \right. \\ \left. \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} \right\} + \left\{ 4C \left(\frac{8ab}{\pi^2} \right) \sum_{n=1}^{MT} \frac{1}{n} \cos \frac{n\pi y_q}{b} \cos \frac{m\pi y_1}{b} \right. \\ \left. \sin \frac{m\pi \Delta y_1}{2b} \sum_{n=1}^{NT} \frac{k_o^2 - (\frac{m\pi}{b})^2}{n G_{nm}^2} \cdot Q \sin h G_{nm} \frac{\Delta z_1}{2} \right. \\ \left. \sin \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} \right\} \quad (21.2)$$

Using Equation I

$$Q_{1q}^{33} = \left\{ 4C \left(\frac{8ab}{\pi^2} \right) \sum_{n=1}^{NT} \frac{1}{n} \sin \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} \right\}$$

$$\sum_{m=1}^{MT} \frac{\left[\left(\frac{n}{a} \right)^2 + \left(\frac{m\pi}{b} \right)^2 \right]}{m G_{nm}^2} \cdot l \cdot G_{nm} |z_q - z_1| \frac{\Delta z_1}{2} \cdot \sin \frac{m\pi y_q}{b} \cdot \sqrt{\sin \frac{m\pi y_1}{b} \cdot \sin \frac{m\pi \Delta y_1}{2b}} \quad (21.3)$$

Using Equation I

$$Q_{lq}^{12} = \left[4C(-8) \sum_{n=1}^{NT} \cos \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} \right] \checkmark$$

$$\sum_{m=1}^{MT} \frac{Q}{G_{nm}^2} |z_q - z_1| \sin h G_{nm} \frac{\Delta z_1}{2} \sin \frac{m\pi y_q}{b} \cos \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b} \quad (21.4)$$

Using Equation I

$$Q_{lq}^{21} = \left[4C(-8) \sum_{n=1}^{NT} \sin \frac{n\pi x_q}{a} \cos \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} \right] \checkmark$$

$$\sum_{m=1}^{MT} \frac{Q}{G_{nm}^2} |z_q - z_1| G_{nm} \frac{\Delta z_1}{2} \cos \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b} \quad (21.5)$$

Using Equation I

$$Q_{lq}^{23} = \left[4C \left(\pm \frac{8a}{\pi} \right) \sum_{n=1}^{NT} \frac{1}{n} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi y_1}{a} \sin \frac{n\pi \Delta y_1}{2a} \right] \checkmark$$

$$\sum_{m=1}^{MT} \frac{Q}{G_{nm}^2} |z_q - z_1| G_{nm} \frac{\Delta z_1}{2} \cos \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b} \quad (21.6)$$

Using Equation I

$$Q_{1q}^{32} = \left[4C \left(\frac{-8a}{\pi} \right) \sum_{n=1}^{NT} \frac{1}{n} \sin \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} \right] \times \frac{\sum_{m=1}^{MT} \frac{G_{nm}}{G_{nm}} \sin h \sin \frac{m\pi y_q}{b} \cos \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b}}{l} \quad (21.7)$$

Using Equation II

$$Q_{1q}^{31} = \left[4C \left(\frac{-8b}{\pi} \right) \sum_{m=1}^{MT} \frac{1}{m} \sin \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b} \right] \times \frac{\sum_{n=1}^{NT} \frac{G_{nm}}{G_{nm}} \sin h \sin \frac{n\pi x_q}{a} \cos \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a}}{l} \quad (21.8)$$

$$Q_{1q}^{13} = \left[4C \left(\frac{+8b}{\pi n} \right) \sum_{m=1}^{MT} \frac{1}{m} \sin \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b} \right] \times \frac{\sum_{n=1}^{NT} \frac{G_{nm}}{G_{nm}} \sin h \sin \frac{n\pi x_q}{a} \cos \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a}}{l} \quad (21.9)$$

In the last four expressions the upper sign is for $z_q < z_1$, the lower sign is for $z_q > z_1$

Art : 3(b) Evaluation Formula for Q_{1q}^{pk} elements with $z_q = z_1$

For $k = 11$ From Equation (21.1)

$$Q_{1q}^{11} = j \left[Q_{1q} \text{ with } \left(e^{-G_{nm}|z_q - z_1|} \cdot \sin h G_{nm} \frac{\Delta z_1}{2} \right) \text{ replaced by 1} \right]$$

$$- j \left[Q_{1q}^{11} \text{ with } \left(e^{-G_{nm}|z_q - z_1|} \cdot \sin h G_{nm} \frac{\Delta z_1}{2} \right) \text{ replaced by } e^{-G_{nm} \frac{\Delta z_1}{2}} \right]$$

The second part of Q_{1q}^{11} can be dealt with in the manner of dealing with

$$Q_{1q}^{11} \text{ with } z_q \neq z_1 \text{ outlined in Art 3(a)}$$

$$\text{1st part of } Q_{1q}^{11} = \left\{ 2C \left(\frac{j4b \Delta x_1}{4\pi} \right) \sum_{m=1}^{MT} \frac{a_0^2}{m(m^2 - a_0^2)} \left[\begin{array}{l} \sin \frac{m\pi}{b} (y_q + y_1 - \frac{\Delta y_1}{2}) \\ -\sin \frac{m\pi}{b} (y_q + y_1 + \frac{\Delta y_1}{2}) \end{array} \right] \right.$$

$$\left. \begin{array}{l} + \sin \frac{m\pi}{b} (y_q - y_1 + \frac{\Delta y_1}{2}) \\ - \sin \frac{m\pi}{b} (y_q - y_1 - \frac{\Delta y_1}{2}) \end{array} \right\} + \left\{ 4C \left(-\frac{j8ab}{4\pi^2} \right) \sum_{n=1}^{NT} \frac{1}{n} \cos \frac{n\pi x_q}{a} \right.$$

$$\left. \begin{array}{l} \cos \frac{n\pi x_1}{a} \quad \sin \frac{n\pi \Delta x_1}{2a} \quad \sum_{m=1}^{MT} \frac{a_n^2}{m(m^2 + a_n^2)} \left[\begin{array}{l} \sin \frac{m\pi}{b} (y_q + y_1 - \frac{\Delta y_1}{2}) \\ -\sin \frac{m\pi}{b} (y_q + y_1 + \frac{\Delta y_1}{2}) \end{array} \right] \\ + \sin \frac{m\pi}{b} (y_q - y_1 + \frac{\Delta y_1}{2}) \\ - \sin \frac{m\pi}{b} (y_q - y_1 - \frac{\Delta y_1}{2}) \end{array} \right\}$$

Where $a_0^2 = \frac{b^2 k_0^2}{\pi^2}$, $a_n^2 = \frac{b^2}{\pi^2} \left[\left(\frac{n\pi}{a} \right)^2 - k_0^2 \right]$ and the factor

$$\left[\sin \frac{m\pi}{b} y_q \quad \sin \frac{m\pi}{b} y_1 \quad \sin \frac{m\pi \Delta y_1}{2b} \right]$$

$$\text{Writing } \frac{a_0^2}{m(m^2 - a_0^2)} = \left[\frac{m}{m^2 - a_0^2} - \frac{1}{m} \right] \text{ and } \frac{a_n^2}{m(m^2 + a_n^2)}$$

$$= \left[\frac{1}{m} - \frac{m}{m^2 + a_n^2} \right] \text{ and using the following formulas } (7)$$

$$\sum_{m=1}^{\infty} \frac{\sin mx}{m} = \frac{\pi - x}{2} = f_1(x) \quad 0 < x < 2\pi$$

$$\sum_{m=1}^{\infty} \frac{m \sin mx}{m^2 + a_n^2} = \frac{\pi \sinh a_n (\pi - x)}{2 \sinh a_n \pi} = f_2(n, x) \begin{cases} \text{N.B.,} \\ a_n^2 > 0, \\ 0 < x < 2\pi \end{cases}$$

$$0 < x < 2\pi \quad \sum_{m=1}^{\infty} \frac{m \sin mx}{m^2 - a_0^2} = \frac{\sin a_0 (\pi - x)}{2 \sin a_0 \pi} = g_1(0, x)$$

N.B.
a₀ is noninteger, $0 < x < 2\pi$

N.B. This formula is to be used when
 $a_n^2 < 0$

$$\text{With } \theta_1^{11} = \frac{\pi}{b} (y_q + y_1 - \frac{\Delta y_1}{2}), \theta_2^{11} = \frac{\pi}{b} (y_q - y_1 + \frac{\Delta y_1}{2})$$

$$\theta_3^{11} = \frac{\pi}{b} (y_q + y_1 + \frac{\Delta y_1}{2}), \theta_4^{11} = \frac{\pi}{b} (y_q - y_1 - \frac{\Delta y_1}{2})$$

and $\theta_1^{11}, \theta_2^{11}, \theta_3^{11}, \theta_4^{11}$ reduced to within 0 to 2π range by

$$\text{adding } \pm 2\pi \text{ and with } G_{1q}^{11}(0) = \left\{ \sum_{i=1}^2 \left[g_1(0, \theta_i^{11}) - f_1(\theta_i^{11}) \right] \right\}$$

$$= \sum_{i=3}^4 \left[g_1(0, \theta_i^{11}) - f_1(\theta_i^{11}) \right]$$

$$\text{and } F_{1q}^{11}(n) = \left\{ \sum_{j=1}^2 \left[f_1(\theta_j^{11}) - f_2(n, \theta_j^{11}) \right] \right\}$$

$$- \sum_{j=3}^4 \left[f_1(\theta_j^{11}) - f_2(n, \theta_j^{11}) \right] \}. \quad \text{and First part of } Q_{1q}^{11}$$

1st part of Q_{1q}^{11}

$$= \left\{ 2C \left(\frac{j4b\Delta x_1}{4\pi} \right) G_{1q}^{11}(0) \right\} + \left\{ 4C \left(\frac{-j8ab}{4\pi^2} \right) \sum_{n=1}^{MT} \frac{1}{n} \cos \frac{n\pi x_q}{a} \right\} \cancel{\sum_{n=1}^{MT}}$$

$$\left. \cos \frac{n\pi x_q}{a} \sin \frac{n\pi \Delta x_1}{2a} \right\} \left[\begin{array}{l} \text{N.B. This is} \\ \text{with } MT \rightarrow \infty \end{array} \right]$$

Wang (7) reports that some 20×20 terms are needed to compute Q_{1q}^{11}

to a high degree of accuracy in typical cases. This is a marked improvement since by direct truncation procedure summation of even 140×140 terms does not produce convergence.

For $P_k = 22$ From Eqn. (21.2)

$$Q_{1q}^{22} = \left\{ j \left[Q_{1q}^{22} \text{ with } \left(\ell = G_{nm} \mid z_q - z_1 \mid, \sinh G_{nm} \frac{\Delta z_1}{2} \right) \right. \right. \\ \left. \left. \text{replaced by 1} \right] \right\} \\ - j \left[Q_{1q}^{22} \text{ with } \left(\ell = G_{nm} \mid z_q - z_1 \mid, \sinh \frac{\Delta z_1}{2} \right) \right. \\ \left. \left. \text{replaced by } \ell = G_{nm} \frac{\Delta z_1}{2} \right] \right\}$$

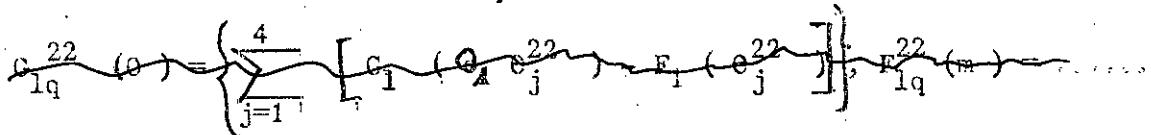
The second part of Q_{1q}^{22} can be dealt with in the manner of dealing with Q_{1q}^{22} with $z_q \neq z_1$ outlined in Art. 3 (a)

The first part of Q_{1q}^{22} can be dealt with in the manner the 1st part of Q_{1q}^{11} was dealt with.

$$\text{Thus with } e_1^{22} = \frac{\pi}{a} (x_q + x_1 - \frac{\Delta x_1}{2}), e_2^{22} = \frac{\pi}{a} (x_q - x_1 + \frac{\Delta x_1}{2}),$$

$$e_3^{22} = \frac{\pi}{a} (x_q + x_1 + \frac{\Delta x_1}{2}), e_4^{22} = \frac{\pi}{a} (x_q - x_1 - \frac{\Delta x_1}{2})$$

reduced within 0 to 2π range,



$$G_{1q}^{22}(0) = \left[4C \left(\frac{j 4a \Delta y_1}{4\pi} \right) \right] \quad \text{Ist part of } Q_{1q}^{22} = \left[2C \left(\frac{j 4a \Delta y_1}{4\pi} \right) \right]$$

$$G_{1q}^{22}(0) = \left[4C \left(-j \frac{8ab}{4\pi} \right) \sum_{m=1}^{NT} \frac{1}{m} \cos \frac{m\pi y_q}{b} \cos \frac{m\pi y_L}{b} \sin \frac{m\pi \Delta y_L}{2b} \right] \quad \times$$

$$(with NT \rightarrow \infty)$$

$$\text{where } G_{1q}^{22}(0) = \left\{ \begin{array}{l} \sum_{j=1}^2 [G_1(0, e_j^{22}) - F_1(e_j^{22})] \\ \sum_{j=3}^4 [G_1(0, e_j^{22}) - F_1(e_j^{22})] \end{array} \right\}$$

$$F_{1q}^{22}(m) = \left\{ \begin{array}{l} \sum_{j=1}^2 [F_1(e_j^{22}) - F_2(m, e_j^{22})] \\ - \sum_{j=3}^4 [F_1(e_j^{22}) - F_2(m, e_j^{22})] \end{array} \right\}$$

$$\text{and } F_1(y) = \sum_{n=1}^{\infty} \frac{\sin ny}{n} = \frac{\pi - y}{2},$$

$$F_2(m_1, y) = \sum_{n=1}^{\infty} \frac{n \sin ny}{n^2 + b_m^2} = \frac{\pi \sinh b_m (\pi - y)}{2 \sinh b_m}$$

$$\text{where } b_m^2 = \frac{a^2}{\pi^2} \left[\left(\frac{m\pi}{a} \right)^2 - k_o^2 \right]$$

$$G_1(0_1, y) = \sum_{n=1}^{\infty} \frac{n \sin ny}{n^2 - b_o^2} = \frac{\pi \sin b_o (\pi - y)}{2 \sin b_o \pi} \text{ where}$$

$$b_o^2 = \frac{a^2}{\pi^2} k_o^2 \text{ (a noninteger value)}$$

For $k = 33$ From Eqn. (21, 3)

$$Q_{1q}^{33} = \left\{ j \left[Q_{1q}^{33} \text{ with } \left(e^{-G_{33}} |z_q - z_1|, \sinh G_{33} \frac{\Delta z_1}{2} \right) \text{ replaced by 1} \right] \right. \\ \left. - j \left[Q_{1q}^{33} \text{ with } \left(e^{-G_{33}} |z_q - z_1|, \sinh G_{33} \frac{\Delta z_1}{2} \right) \text{ replaced by...} \right. \right. \\ \left. \left. e^{-G_{33}} \frac{\Delta z_1}{2} \right] \right\}$$

The Second part of Q_{1q}^{33} can be dealt with in the manner of dealing with

Q_{1q}^{33} with $z_q \neq z_1$ outlined in Art. 3 (a)

$$\text{Ist part of } Q_{1q}^{33} = \left\{ 4C \left(\frac{\pm j8ab}{4\pi^2} \right) \sum_{n=1}^{NT} \frac{1}{n} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi z_1}{a} \right.$$

$$\left. \cdot \sin \frac{n\pi \Delta z_1}{2a} \left[\sum_{m=1}^{MT} \frac{1}{m} - \frac{a_o^2}{a_n^2 m} + \frac{a_o^2}{a_m^2 (m^2 + o_n^2)} \right] \right\}$$

$$\left. , \left[\sin m\theta_1^{33} + \sin m\theta_2^{33} - \sin m\theta_3^{33} - \sin m\theta_4^{33} \right] \right\}$$

Where $\theta_1^{33} = \theta_1^{11}$, $\theta_2^{33} = \theta_2^{11}$, $\theta_3^{33} = \theta_3^{11}$, $\theta_4^{33} = \theta_4^{11}$

$$\text{with } F_{1q}^{33}(n) = \left\{ \sum_{j=1}^2 \left[f_1(\theta_j^{33}) - \frac{a_o^2}{a_n^2} f_1(\theta_j^{33}) + \frac{a_o^2}{a_n^2} f_2(n, \theta_j^{33}) \right] \right\}$$

$$= \sum_{j=3}^4 \left[f_1(\epsilon_j^{33}) - \frac{a_0^2}{a_n^2} f_2(n, \epsilon_j^{33}) + \frac{a_0^2}{a_n^2} f_2(n, \theta_j^{33}) \right] \}$$

and $f_1(x), f_2(n, x)$ are as defined on Page 58.

Ist part of $Q_{1q}^{33} = \left\{ 4C \left(\pm \frac{j8ab}{4\pi^2} \right) \sum_{n=1}^{NT} \frac{1}{n} \sin \frac{n\pi x_q}{a} \right. \quad \cancel{+}$

$$\left. \cdot \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} \cdot F_{1q}^{33}(n) \right\}$$

For $M = 12$ from Eqn. (21,4)

$$Q_{1q}^{12} = \left\{ j \left[Q_{1q}^{12} \text{ with } \left(e^{-G_{nm}} |z_q - z_1| \cdot \sinh G_{nm} \frac{\Delta z_1}{2} \right) \text{ replaced by} \right] \right. \quad \cancel{+}$$

$$\left. -j \left[Q_{1q}^{12} \text{ with } \left(e^{-G_{nm}} |z_q - z_1| \cdot \sinh G_{nm} \frac{\Delta z_1}{2} \right) \text{ replaced by} \right. \right. \\ \left. \left. \cdot e^{-G_{nm} \frac{\Delta z_1}{2}} \right] \right\}$$

The second part of Q_{1q}^{12} can be dealt with in the manner of dealing with

Q_{1q}^{12} with $z_q \neq z_1$ outlined in Art 3 (a)

Ist part of $Q_{1q}^{12} = \left\{ 4C \left(\pm \frac{j8}{4} \right) \sum_{n=1}^{NT} \cos \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \right. \quad \cancel{+}$

$$\left. \cdot \sin \frac{n\pi \Delta x_1}{2a} \sum_{m=1}^{MT \rightarrow \infty} \frac{b^2}{\frac{\pi^2}{m^2} + a_n^2} \left[\begin{array}{l} - \cos M \epsilon_1^{121} + \cos M \epsilon_2^{121} \\ + \cos M \epsilon_3^{121} - \cos M \epsilon_4^{121} \end{array} \right] \right\}$$

$$\text{Where } \epsilon_1^{12} = \epsilon_1^{11}, \epsilon_2^{12} = \epsilon_2^{11}, \epsilon_3^{12} = \epsilon_3^{11}, \epsilon_4^{12} = \epsilon_1^{11}$$

Using the relations [7] :- $\sum_{m=1}^{\infty} \frac{\cos mx}{m^2 + a_n^2} = \frac{\pi}{2a_n} \frac{\cos h(\pi/a_n)}{\sin h(a_n \pi / 2a_n)} - \frac{1}{2a_n^2}$

$$= f_3(n, x)$$

$$\text{and } F_{1q}^{12}(n) = \left\{ \frac{b^2}{\pi^2} \left[-f_3(n, \epsilon_1^{12}) + f_3(n, \epsilon_2^{12}) + f_3(n, \epsilon_3^{12}) - f_3(n, \epsilon_4^{12}) \right] \right\}$$

$$\text{Ist part of } Q_{1q}^{12} = \left\{ 4C\left(\frac{-j8}{4}\right) \sum_{n=1}^{NT} \cos \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \right. \\ \left. , \sin \frac{n\pi \Delta x_1}{2a} \cdot F_{1q}^{121}(n) \right\}$$

$$\text{E.B.} - \sum_{m=1}^{\infty} \frac{\cos mx}{m^2 - a^2} = \frac{1}{2a^2} - \frac{\pi}{2} \frac{\cos a(\pi - x)}{a \sin a\pi} \quad 0 \leq x \leq 2\pi$$

For $\pi k = 21$ From Equation (21.5)

$$Q_{1q}^{21} = \left\{ j \left[Q_{1q}^{21} \text{ with } e^{-G_{nm}} |z_q - z_1| \sinh G_{nm} \frac{\Delta z_1}{2} \text{ replaced by 1} \right] \right. \\ \left. - j \left[Q_{1q}^{21} \text{ with } e^{-G_{nm}} |z_q - z_1| \sin G_{nm} \frac{\Delta z_1}{2} \text{ replaced by } e^{-G_{nm} \frac{\Delta z_1}{2}} \right] \right\}$$

The second part of Q_{1q}^{21} can be dealt with in the manner of dealing with

Q_{1q}^{21} with $z_q \neq z_1$ outlined in Art. 3 (a)

$$\text{Ist part of } Q_{1q}^{21} = \left\{ 4C\left(\frac{-j8}{4}\right) \sum_{n=1}^{NT} \sin \frac{n\pi x_q}{a} \cos \frac{n\pi x_1}{a} \right\}$$

$$\sin \frac{n\pi \Delta x_1}{2a} \sum_{m=1}^{NT} \left[\begin{array}{l} \cos m \epsilon_1^{21} + \cos m \epsilon_2^{21} \\ - \cos m \epsilon_3^{21} - \cos m \epsilon_4^{21} \end{array} \right] \text{ where } \epsilon_1^{21} = \epsilon_1^{11}, \dots$$

$$\epsilon_2^{21} = \epsilon_2^{11}, \quad \epsilon_3^{21} = \epsilon_3^{11}, \quad \epsilon_4^{21} = \epsilon_4^{11}$$

$$\text{Using the relations [7] : } \sum_{m=1}^{\infty} \frac{\cos mx}{m^2 + a_n^2} = \frac{\pi}{2a_n} \frac{\cos h(\pi - x)}{\sin h a_n \pi} - \frac{1}{2a_n^2} \\ = f_3(n, x)$$

$$\text{and } F_{1q}^{21}(n) = \left\{ \frac{b^2}{\pi^2} \left[f_3(n_1 e_1^{21}) + \right. \right.$$

$$\left. + f_3(n_1 e_2^{21}) + f_3(n_1 e_3^{21}) + f_3(n_1 e_4^{21}) \right] \}$$

$$\text{Ist part of } Q_{1q}^{21} = \left\{ 4C \left(\frac{-j8}{4} \right) \sum_{n=1}^{NT} \sin \frac{n \prod x_q}{a} \cos \frac{n \prod x_1}{a} \right. \\ \left. \cdot \sin \frac{n \prod \Delta z_1}{2a}, F_{1q}^{21}(n) \right\}$$

For $bk = 23, 32, 31, 13$

The Q_{1q}^{pk} elements are zero because of the zero value of the factor I in these cases for $z_q = z_1$ in Eqn (5) of Art 2 of Ch. III.

Art. 4(a) A suggested Modified Method of Computing Q_{1q}^{pk} elements with $z_q = z_1$

As found in Art. 3 (b) the 2nd part of Q_{1q}^{pk} elements with $z_q = z_1$ has the factor $e^{-C_{nm} \frac{\Delta z_1}{2}}$. The rapidity of the convergence of the double infinite summation of the 2nd part of Q_{1q}^{pk} elements with $z_q = z_1$ depends largely on the cell size parameter $\frac{\Delta z_1}{2}$.

the number of cells increased for greater details and accuracy of the obstacle di-electric field quantities and with the cell size decreased for finding the field quantities in a heterogeneous obstacle di-electric the number of Q_{1q}^{pk} elements with $z_q = z_1$ will be increased and the

rapidity of Q_{lq}^{pk} element computation (for $z_q = z_1$) will be much decreased respectively.

Integral transforms have been used in a variety of ways to sum certain types of series in closed form. They are found useful in many cases in converting relatively complicated series into simpler ones which are more easily summed or in converting relatively slowly converging series into much more rapidly converging ones. A.D. Wheeler (ff) is one of the several authors who investigated the application of laplace transforms to the summation of infinite series and here we follow the method suggested by Wheeler (ff)

The laplace transform of a function $f(u)$ is

$$F(p) = \int_0^{\infty} du e^{-up} f(u)$$

If we have a series for which the function $F(n)$ represents the general term or summand then we can identify the transform variable p with the dummy index of summation n and sum both sides of this with respect to n over 0 to ∞ .

$$\text{Thus } \sum_{n=0}^{\infty} F(n) = \sum_{n=0}^{\infty} \int_0^{\infty} du e^{-un} f(u) = \int_0^{\infty} du f(u) \sum_{n=0}^{\infty} e^{-un} u^n$$

The second form follows from the interchange of the summation and the integration process based on the theory of convergence.

$$\text{Now, with } F(u) = \int_0^\infty du f(u) (e^{-u})^n$$

if we multiply both sides of this equation by $F_{1q}^{pk}(n)$ which does not spoil the convergence of the ensuing summation we obtain a more general series form :-

$$\sum_{n=0}^{\infty} F(n) F_{1q}^{pk}(n) = \int_0^\infty du f(u) \sum_{n=0}^{\infty} F_{1q}^{pk}(n) (e^{-u})^n \quad \text{III}$$

Similarly with the dummy index of summation m over 0 to ∞ we have

$$\sum_{m=0}^{\infty} F(m) F_{1q}^{pk}(m) = \int_0^\infty du f(u) \sum_{m=0}^{\infty} F_{1q}^{pk}(m) (e^{-u})^m \quad \text{IV}$$

Such conversions provide rapidly convergent integro - summation for a slowly convergent series.

From Equation (21), making $NT \rightarrow \infty$ and noting $b_{1q}^{pk}(n, 0) = 0$

for $k = 11, 33, 12, 21$, we obtain the following relations :-

$$\text{2nd part of } Q_{1q}^{11} = \left\{ 2C(C_1^{11}) \sum_{m=0}^{\infty} b_{1q}^{11}(0, m) + 4C(C_2^{11}) \right\} \quad \boxed{V}$$

$$\sum_{n=1}^{NT} a_{1q}^{11}(n) \sum_{m=0}^{\infty} b_{1q}^{11}(n, m) \quad \boxed{V}$$

$$\text{2nd part of } Q_{1q}^{pk} = \left\{ 4C(C_3^{pk}) \sum_{n=1}^{NT} a_{1q}^{pk}(n) \sum_{m=0}^{\infty} b_{1q}^{pk}(n, m) \right\}$$

for $k = 33, 12, 21$, and $C_1^{11}, C_2^{11}, C_3^{pk}$ are constants.

$$C_1^{pk}, C_2^{pk}, C_3^{pk} \text{ are constants}$$

Similarly from Equation (21) making $NT \rightarrow \infty$ and noting $a_{1q}^{pk}(0,n)=0$ for $pk = 22, 33, 12, 21$, we obtain

$$\text{2nd part of } Q_{1q}^{22} = \left\{ 2C(C_1^{22}) \sum_{n=0}^{\infty} a_{1q}^{22}(n,0) + 4C(C_2^{22}) \sum_{m=1}^{MT} b_{1q}^{22}(m) \right. \\ \left. + \sum_{n=0}^{\infty} a_{1q}^{22}(n,m) \right\} \quad VI$$

$$\text{2nd part of } Q_{1q}^{pk} = \left\{ 4C(C_4^{pk}) \sum_{m=1}^{MT} b_{1q}^{pk}(m) + \sum_{n=0}^{\infty} a_{1q}^{22}(n,m) \right\},$$

for $pk = 33, 12, 21$ and $C_1^{22}, C_2^{22}, C_4^{pk}$ are constants

Applying Equation IV to infinite series part of Q_{1q}^{pk} for

$pk = 11, 33, 12, 21$, we have, (for a fixed n)

$$S_{1q}^{pk}(n) = \sum_{m=0}^{\infty} b_{1q}^{pk}(n,m) = \sum_{m=0}^{\infty} F(m) f_{1q}^{pk}(m) \quad \cancel{\text{and}} \\ = \int_0^{\infty} du f(u) \sum_{m=0}^{\infty} f_{1q}^{pk}(m) e^{-um} = \int_0^{\infty} du f(u) S^{pk}(u) \quad VII$$

Where $F(m) = \frac{1}{m^2 + a_n^2}$ and $f(u) = \frac{\sin(a_n u)}{a_n}$ for ~~inf~~

$$a_n = \frac{b}{\pi} \sqrt{(\frac{n\pi}{a})^2 - k_o^2} \quad \text{and} \quad F(m) = \frac{1}{m^2 + a_n^2} \quad \text{and} \quad f(u) =$$

$$\frac{\sin(a_n u)}{a_n} \quad \text{for } j a_n = j \frac{b}{\pi} \sqrt{k_o^2 - (\frac{n\pi}{a})^2}$$

$$\text{and } S^{pk}(u) = \sum_{m=0}^{\infty} f_{1q}^{pk}(m) e^{-um} \approx \sum_{m=0}^{MT} f_{1q}^{pk}(m) e^{-um} \\ \text{for } pk = 11, 33, 12, 21$$

For $F_K = 11$

$$\text{With } F_{1q}^{11} (n) = \left\{ \frac{\frac{b^2}{\pi^2} \left[k_0^2 - \left(\frac{n\pi}{a} \right)^2 \right]}{m} \cdot \left(e^{-G_m} \frac{\Delta z_1}{2} \right) \right\}$$

$$, \sin \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b} \} ; S^{11} (u) = \sum_{m=0}^{MT} F_{1q}^{11} (n) e^{-um} ;$$

$$S_{1q}^{11} (n) = \int_0^u f(u) S^{11} (u) \approx \int_0^{UT} f(u) S^{11} (u)$$

Initially applying truncated trapezoidal rule, we have,

$$S_{1q}^{11} (n) = \frac{\Delta u}{2} \left[f(0) S^{11} (0) + 2f(1) S^{11}(1) + \dots \dots \right]$$

$$+ 2 \left[f(2k) S^{11} (2k) + f(2k+1) S^{11} (2k+1) \right]$$

$$\approx \Delta u \sum_{\substack{u=1 \\ \Delta u}}^{2k} f(u) S^{11} (u) \text{ for selecting suitable } \Delta u \text{ and } k.$$

Finally applying Simpson's rule, we have

$$S_{1q}^{11} (n) = \left[\frac{2\Delta u}{3} \sum_{\substack{u=0,2 \\ \Delta u}}^{2k} f(u) S^{11} (u) + \frac{2\Delta u}{3} \right]$$

$$\left. \sum_{\substack{u=1,3,5,\dots \\ \Delta u}}^{2k-1} f(u) S^{11} (u) \right\} + \left\{ \frac{\Delta u}{3} \left(f(0) S^{11} (0) + f[(2k\Delta u)] S^{11} [(2k+1)\Delta u] \right) \right\}$$

$$\text{2nd part of } Q_{1q}^{11} = \left\{ 2C \left(-j \frac{4b}{\pi} \Delta x_1 \right) S_{1q}^{11} (0) \right\} + \left\{ 4C \left(-j \frac{8ab}{\pi^2} \right) \right\}$$

$$\left. \cdot \sum_{n=1}^{NT} \frac{1}{n} \cos \frac{n\pi x_q}{a} \cos \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} \cdot S_{1q}^{11} (n) \right\}$$

For $k = 22$ Applying Equation III to infinite series part of Q_{1q}^{22} ,

we have ; (for a fixed m)

$$S_{1q}^{22}(m) = \sum_{n=0}^{\infty} a_{1q}^{22}(n, m) = \sum_{n=0}^{\infty} F(n) f_{1q}^{22}(n) = \\ = \int_0^{\infty} du f(u) \sum_{n=0}^{\infty} F_{1q}^{22}(n) e^{-un} = \int_0^{\infty} du f(u) S^{22}(u)$$

where $F(n) = \frac{1}{n^2 + b_m^2}$ and $f(u) = \frac{\sin(b_m u)}{u}$ for $b_m = \frac{a}{\pi} \sqrt{k_o^2 - (\frac{m\pi}{b})^2}$

and $F(n) = \frac{1}{n^2 + b_m^2}$ and $f(u) = \frac{\sin(b_m u)}{u}$ for $j b_m = j \frac{a}{\pi} \sqrt{k_o^2 - (\frac{m\pi}{b})^2}$

and $S^{22}(u) = \sum_{n=0}^{\infty} F_{1q}^{22}(n) e^{-un} \approx \sum_{m=0}^{NT} F_{1q}^{22}(n) e^{-un}$

With $F_{1q}^{22}(n) = \frac{-\frac{a^2}{\pi^2} \left[k_o^2 - \left(\frac{m\pi}{b} \right)^2 \right]}{n} \left(e^{-j n x_q} \frac{\Delta x_1}{2} \right) \sin \frac{n \pi x_q}{a}$

$$\cdot \sin \frac{n \pi x_1}{a} \sin \frac{n \pi \Delta x_1}{2a}$$

$$S_{1q}^{22}(m) = \int_0^{\infty} du f(u) S^{22}(u) \approx \int_0^{UT} du f(u) S^{11}(u)$$

Evaluating $S_{1q}^{22}(m)$ in the manner $S_{1q}^{11}(n)$ is evaluated, we obtain,

2nd part of $Q_{1q}^{22} = \left\{ 2C \left(-j \frac{4a}{\pi} \Delta y_1 \right) S_{1q}^{22}(0) \right\} + \left\{ 4C \left(-j \frac{8ab}{\pi^2} \right) \right\}$

$$\left. \sum_{m=1}^{MT} \frac{1}{m} \cos \frac{m \pi y_q}{b} \cos \frac{m \pi y_1}{b} \sin \frac{m \pi \Delta y_1}{2b} \cdot S_{1q}^{22}(m) \right\}$$

For PK = 33

$$\text{With } F_{1q}^{33} (m) = \left\{ \frac{b^2}{\pi^2} \frac{\left[\left(\frac{n\pi}{a} \right)^2 + \left(\frac{m\pi}{b} \right)^2 \right]}{m} \right\} \left(e^{-G_{nm} \frac{\Delta z_1}{2}} \right) \sin \frac{m\pi y_q}{b} \cdot \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b},$$

From Equation VII $S_{1q}^{33} (n) = \int_0^\infty du f(u) S^{33}(u)$

$$\approx \int_0^{UT} du f(u) S^{33}(u), \text{ Evaluating } S_{1q}^{33}(n) \text{ in the manner } S_{1q}^{11}(n)$$

is evaluated, we have,

$$\text{2nd part of } Q_{1q}^{33} = \left[4C \left(-j \frac{8ab}{\pi^2} \right) \sum_{n=1}^{NT} \frac{1}{n} \sin \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \cdot \sin \frac{n\pi \Delta x_1}{2a} \cdot S_{1q}^{33}(n) \right]$$

For PK = 12

$$\text{with } F_{1q}^{12} (m) = \left\{ \frac{b^2}{\pi^2} \right\} \left(e^{-G_{nm} \frac{\Delta z_1}{2}} \right) \sin \frac{m\pi y_q}{b} \cos \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b}$$

From Equation VII

$$S_{1q}^{12} (n) = \int_0^\infty du f(u) S^{12}(u) \approx \int_0^{UT} du f(u) S^{12}(u)$$

Evaluating $S_{1q}^{12}(n)$ in the manner $S_{1q}^{11}(n)$ is evaluated, we have,

$$\text{2nd part of } Q_{1q}^{12} = \left[4C \left(+j8 \right) \sum_{n=1}^{NT} \cos \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} S_{1q}^{12}(n) \right]$$

For PK = 21

$$\text{With } F_{1q}^{21} = \left\{ \frac{b^2}{\pi^2} \right\} \left(e^{-G_{nm} \frac{\Delta z_1}{2}} \right) \cos \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b}$$

From Equation VII

$$S_{1q}^{21}(n) = \int_0^\infty du f(u) S^{21}(u) \approx \int_0^{UT} du f(u) S^{21}(u)$$

Evaluating $S_{1q}^{21}(n)$ in the manner $S_{1q}^{11}(n)$ is evaluated, we have,

$$\text{2nd part of } Q_{1q}^{21} = \left[4C(+js) \sum_{n=1}^{NT} \sin \frac{n\pi x_q}{a} \cos \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a}, S_{1q}^{21} \right]$$

Finding the 2nd part of Q_{1q}^{pk} elements as shown above we may add to it

the respective value of the 1st part of Q_{1q}^{pk} elements with $z_q = z_1$

computed by the method outlined in Art. 3 (b) and get the whole value of

Q_{1q}^{pk} elements with $z_q = z_1$. It is to be noted that for $pk = 23, 32, 31, 13$

the Q_{1q}^{pk} elements with $z_q = z_1$ are each equal to zero. This method may

be found useful for Q_{1q}^{12} with $|z_q - z_1|$ small for $z_q \neq z_1$ cases as well.

Art. 4(b). A suggested Modified method of computing Q_{1q}^{pk} with $z_q \neq z_1$ and

$pk = 23, 32, 31, 13$.

With $\frac{1}{G_{pq}} \cdot e^{-G_{pq}|z_q - z_1|} \cdot \sinh G_{pq} \frac{\Delta z_1}{2}$ factor in Q_{1q}^{pk} element with $|z_q - z_1|$ small & $[pk = 23, 32, 31, 13]$ involving double infinite series we may apply Poisson's summation Formula (8), for evaluation of the Q_{1q}^{pk} elements with rapid convergence, utilizing Fourier transform. This may also be useful when there a large number of such elements to be computed.

According to the Poisson's summation formula (Appendix III) the summation of an infinite series is given by

$$\sum_{n=-\infty}^{\infty} g\left(\frac{2\pi n}{d}\right) = \frac{1}{2\pi} \sum_{n=-\infty}^{\infty} F\left(\frac{2\pi n}{d}\right) = \frac{1}{2\pi} \sum_{n=-\infty}^{\infty} f(d_n)$$

Where the fourier integral relation

$$f(x) = \left[\frac{1}{2\pi} \int_{-\infty}^{\infty} dw e^{jwx} \int_{-\infty}^{\infty} f(x) e^{-jwx} dx \right] \text{ defines}$$

$$f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} dw e^{jwx} F(w) = \int_{-\infty}^{\infty} dw e^{jwx} g(w)$$

$$F(w) = \int_{-\infty}^{\infty} dx e^{-jwx} f(x) \text{ and } g(w) = \frac{1}{2\pi} \int_{-\infty}^{\infty} dx e^{-jwx} f(x)$$

and the above summation formula results after performing the summation and integration in the RHS of the following relation.

$$\sum_{n=-\infty}^{\infty} f(d_n) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(w) \sum_{n=-\infty}^{\infty} e^{jwd_n} dw \text{ where } x = d_n \text{ and}$$

d is such that the series converges.

Putting $d = 2a$

$$\sum_{n=-\infty}^{\infty} g\left(\frac{n\pi}{a}\right) = \frac{a}{\pi} \sum_{n=-\infty}^{\infty} f(2na) \quad \boxed{IX}$$

$$\text{Now } f(z) = \int_{-\infty}^{\infty} dw e^{jwz} g(w) = \int_{-\infty}^{\infty} \frac{e^{jwz} - e^{jwz' - d\sqrt{w^2 + \beta^2}}}{\sqrt{w^2 + \beta^2}} dw$$

$$= 2 K_0 \left\{ \beta \sqrt{d^2 + (z + z')^2} \right\} \text{ where } K_0 \{x\} \text{ is the modified Bessel function of the second kind } [8, \text{pp } 267 - 269] \text{ of } x$$

$$\text{Putting } w = \frac{n\pi}{a}; z' = Y \cos \theta_0, d = r \sin \theta, \beta^2 = k_m^2 = \left(\frac{m\pi}{b}\right)^2 - k_0^2$$

relation IX yields

$$\sum_{n=-\infty}^{\infty} \frac{e^{j \frac{n \pi}{a} r \cos \theta}}{\sqrt{\left(\frac{n \pi}{a}\right)^2 + k_m^2}} = r \sin \theta \sqrt{\left(\frac{n \pi}{a}\right)^2 + k_m^2}$$

$$= \frac{\alpha}{\pi} \sum_{n=-\infty}^{\infty} \frac{1}{2K_0} \left\{ k_m \sqrt{r^2 + (2na)^2 + 4na \gamma \cos \theta} \right\}$$

Where LHS = $\sum_{n=-\infty}^{\infty} g\left(\frac{n \pi}{a}\right)$ and RHS = $\sum_{n=-\infty}^{\infty} f(2na)$

Hence $\sum_{n=-\infty}^{\infty} e^{j \frac{n \pi}{a} r \cos \theta} \cdot \frac{1}{G_{nm}} \cdot e^{-G_{nm} r \sin \theta}$

$$= \frac{\alpha}{\pi} \sum_{n=-\infty}^{\infty} \frac{1}{2K_0} \left\{ k_m \sqrt{r^2 + (2na)^2 + 4na r \cos \theta} \right\} \quad X$$

Analogously $\sum_{m=-\infty}^{\infty} e^{j \frac{m \pi}{b} r \cos \theta} \cdot \frac{1}{G_{nm}} \cdot e^{-G_{nm} r \sin \theta}$

$$= \frac{b}{\pi} \sum_{m=-\infty}^{\infty} \frac{1}{2K_0} \left\{ k_n \sqrt{r^2 + (2mb)^2 + 4mb \gamma \cos \theta} \right\} \quad XI$$

where $k_n = \sqrt{\left(\frac{n \pi}{a}\right)^2 - k_0^2}$

For $b=2a$ From Equation (21.6)

$$Q_{1q}^{23} = \left\{ 4C \left(+ \frac{a}{\pi} \right) \sum_{n=1}^{\infty} \frac{1}{n} \sin \frac{n \pi x_q}{a} \sin \frac{n \pi x_1}{a} \sin \frac{n \pi \Delta x_1}{2a} \right\}$$

$$\sum Q'_{om} \left[\frac{e^{j G_{nm} (z_{1q} - z_1) - \frac{\Delta z_1}{2}}}{G_{nm}} - \frac{e^{-j G_{nm} (z_{1q} - z_1) + \frac{\Delta z_1}{2}}}{G_{nm}} \right]$$

$$x \left[\begin{array}{l} \cos \frac{m \pi}{b} (y_q + y_1 - \frac{\Delta y_1}{2}) + \cos \frac{m \pi}{b} (y_q - y_1 + \frac{\Delta y_1}{2}) \\ - \cos \frac{m \pi}{b} (y_q + y_1 + \frac{\Delta y_1}{2}) - \cos \frac{m \pi}{b} (y_q - y_1 - \frac{\Delta y_1}{2}) \end{array} \right] \}$$

Let us consider the 1st term to be summed over m from 0 to ∞ .

$$\text{1st term} = \left[\sum_{m=0}^{\infty} e'_{om} \cdot \frac{e^{-G_{nm}} \left((z_q - z_1) + \frac{z_1}{2} \right)}{G_{nm}} \cdot \cos \frac{m\pi}{b} \left(y_q + y_1 - \frac{\Delta y_1}{2} \right) \right]$$

$$= \left[\sum_{m=0}^{\infty} e'_{om} \cdot \frac{e^{-G_{nm}} (Y_1 \sin \theta_1)}{G_{nm}} \cdot \cos \left(\frac{m\pi}{b} Y_1 \cos \theta_1 \right) \right]$$

N.B.

$$\left[\begin{array}{l} \text{By putting } \left((z_q - z_1) + \frac{z_1}{2} \right) = Y_1 \sin \theta_1 \\ \quad \quad \quad \left(y_q + y_1 + \frac{\Delta y_1}{2} \right) = Y_1 \cos \theta_1 \end{array} \right]$$

$$= \left[\sum_{m=-\infty}^{m=\infty} e^{j \frac{m\pi}{b} Y_1 \cos \theta_1} \frac{1}{G_{nm}} \cdot e^{-G_{nm} Y_1 \sin \theta_1} \right]$$

N.B.

$$\left[\begin{array}{l} \text{Since } \cos \frac{m\pi}{b} Y_1 \cos \theta_1 \text{ is an even function} \\ \text{over } m \text{ and} \quad e'_{om} = \begin{cases} 1 & \text{for } m = 0 \\ 2 & \text{otherwise} \end{cases} \end{array} \right]$$

$$= \left[\frac{b}{\pi} \sum_{m=-\infty}^{m=\infty} 2 K_0 \left\{ k_n \sqrt{Y_1^2 + (2mb)^2 + 4mb Y_1 \cos \theta_1} \right\} \right]^{23} (n) \text{ (by Eqn. XI)}$$

Similarly the other seven series terms to be summed over m from $0 \text{ to } \infty$ may

be dealt with. The sum of these eight terms yields the expression denoted

by $K_{1q}^{23} (n)$

$$\text{Hence } Q_{1q}^{23} = \left[4C \left(+ \frac{2}{\pi} \right) \sum_{n=1}^{\infty} \frac{1}{n} \cdot \sin \frac{n\pi x_q}{a} \cdot \sin \frac{n\pi x_1}{a} \cdot \sin \frac{n\pi \Delta x_1}{2a} \cdot K_{1q}^{23} (n) \right]$$

For $\text{Bk} = 32$ From Eqn. (21.7)

$$Q_{1q}^{32} = \left\{ 4C \left(\frac{\alpha}{+\pi} \right) \sum_{n=1}^{NT} \frac{1}{n} \sin \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} \right.$$

$$\times \sum_{nm=0}^{\infty} e'_{on} \left[\frac{e^{-G_{nm}(|z_q-z_1| - \frac{\Delta z_1}{2})}}{G_{nm}} - \frac{e^{-G_{nm}(|z_q-z_1| + \frac{\Delta z_1}{2})}}{G_{nm}} \right]$$

$$\times \left. \left[\begin{aligned} & \cos \frac{m\pi}{b}(y_q - y_1 - \frac{\Delta y_1}{2}) - \cos \frac{m\pi}{b}(y_q + y_1 - \frac{\Delta y_1}{2}) \\ & + \cos \frac{m\pi}{b}(y_q - y_1 + \frac{\Delta y_1}{2}) - \cos \frac{m\pi}{b}(y_q + y_1 - \frac{\Delta y_1}{2}) \end{aligned} \right] \right\}$$

This proceeding in the manner outlined for the case of Q_{1q}^{23}

$$Q_{1q}^{32} = \left\{ 4C \left(\frac{\alpha}{+\pi} \right) \sum_{n=1}^{NT} \frac{1}{n} \sin \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} K_{1q}^{32}(n) \right\}$$

For $\text{Bk} = 31$ From Eqn. (21.8)

$$Q_{1q}^{31} = \left\{ 4C \left(\frac{-b}{+\pi} \right) \sum_{m=1}^{MT} \frac{1}{m} \sin \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b} \right.$$

$$\times \sum_{n=0}^{\infty} e_{on} \left[\frac{e^{-G_{nm}(|z_q-z_1| - \frac{\Delta z_1}{2})}}{G_{nm}} - \frac{e^{-G_{nm}(|z_q-z_1| + \frac{\Delta z_1}{2})}}{G_{nm}} \right]$$

$$\times \left. \left[\begin{aligned} & \cos \frac{n\pi}{a}(x_q + x_1 - \frac{\Delta x_1}{2}) - \cos \frac{n\pi}{a}(x_q + x_1 + \frac{\Delta x_1}{2}) \\ & + \cos \frac{n\pi}{a}(x_q + x_1 - \frac{\Delta x_1}{2}) - \cos \frac{n\pi}{a}(x_q + x_1 + \frac{\Delta x_1}{2}) \end{aligned} \right] \right\}$$

Proceeding in the manner outlined for the case of Q_{1q}^{23} except that

Eqn. X is used instead of Eqn. XI

$$Q_{1q}^{31} = \left\{ 4C \left(\frac{+b}{-\pi} \right) \sum_{m=1}^{MT} \frac{1}{m} \sin \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b} K_{1q}^{31} (m) \right\}$$

For PK = 13 From Eqn. (21, 9)

$$Q_{1q}^{13} = \left\{ 4C \left(\frac{+b}{-\pi} \right) \sum_{m=1}^{MT} \frac{1}{m} \sin \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b} \dots \right.$$

$$\begin{aligned} & \sum_{n=0}^{\infty} e_{on} \left[\frac{-G_{nm} (|z_q - z_1| - \frac{\Delta z_1}{2})}{\frac{e}{G_{nm}}} \frac{G_{nm} (|z_q - z_1| + \frac{\Delta z_1}{2})}{e} \right. \\ & \left. \left. \left[\begin{aligned} & \cos \frac{n\pi}{a} (x_q + x_1 - \frac{\Delta x_1}{2}) + \cos \frac{n\pi}{a} (x_q - x_1 + \frac{\Delta x_1}{2}) \\ & - \cos \frac{n\pi}{a} (x_q + x_1 + \frac{\Delta x_1}{2}) - \cos \frac{n\pi}{a} (x_q - x_1 - \frac{\Delta x_1}{2}) \end{aligned} \right] \right] \right\} \end{aligned}$$

Proceeding in the manner outlined for the case of Q_{1q}^{23} except that

Equation X is used instead of Equation XI

$$Q_{1q}^{33} = \left\{ 4C \left(\frac{+b}{-\pi} \right) \sum_{m=1}^{MT} \frac{1}{m} \sin \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b} , K_{1q}^{13} (m) \right\}$$

N.B. In above expressions the upper sign is for $z_q < z_1$ and the lower sign is for $z_q > z_1$

Appendix III :- On the Poisson's summation Formula (Ref. 8)

Let us consider the following general series, $\sum_{n=0}^{\infty} f(\lambda_n)$, where $f(x)$ is of such form that its Laplace transform $F(P)$ exists.

We have by definition $F(P) = \int_0^{\infty} f(x) e^{-px} dx$

This integral determines $F(p)$ as an analytic function of the complex variable $p = u + jv$ whose singularities all lie to the left of some value of $u = c$ in the p plane. The inversion integral yields

$$f(x) = \frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} F(p) e^{px} dp$$

If we replace x by λ_n and sum over n , we get,

$$\sum_{n=0}^{\infty} f(\lambda_n) = \frac{1}{2\pi j} \sum_{n=0}^{\infty} \int_{c-j\infty}^{c+j\infty} e^{p\lambda_n} F(p) dp$$

N.B.
It is such that the
series & the integral
converges

This is permissible since the inversion integral holds identically for all values of x with the exception of certain values of x for which $f(x)$ may be discontinuous. In our case it is assumed that $f(x)$ is a continuous function of x . If now, the integral involving $F(p)$ is uniformly convergent, we may interchange the order of integration and summation to

get

$$\sum_{n=0}^{\infty} f(\lambda_n) = \frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} F(p) \sum_{n=0}^{\infty} e^{p\lambda_n} dp$$

$$\int_{C-j\infty}^{C+j\infty} \frac{F(p)}{1-e^{Pd}} dp = \left[\text{N.B. using } \sum_{n=0}^{\infty} e^{-Pd_n} \right] = \frac{1}{1-e^{Pd}}$$

provided $f(x)$ is of such form that we may take $C < 0$ in order that

$\sum_{n=0}^{\infty} e^{-Pd_n}$ should represent a convergent series. This implies that

$f(x)$ is asymptotic to $e^{-\epsilon n}$, $\epsilon > 0$, as x approaches infinity. In general, this condition is not satisfied, but in practice, we can multiply $f(d_n)$ by $e^{-\epsilon n}$, sum the resulting series and then take the limit as ϵ approaches zero. If we can evaluate the resulting integral, we have

the sum of the series in closed form. Alternatively, we may expand the integral by the residue theorem. We choose the contour, for the relevant contour integral in this case, the line $P=C$, $C < 0$, and the semicircle,

in the right half plane. Since $F(P)$ is analytic for all $U > C$, the only

poles of the integrand occur at $e^{Pd} = 1$ or $P = (j \frac{2\pi n}{d})$, $n=0$,

$\pm 1, \pm 2 \dots$. The residues at these poles of $[1 - e^{Pd}]^{-1}$ are $-\frac{1}{d}$

and the residues at these poles of the integrand of $P - \frac{1}{d} F(j \frac{2\pi n}{d})$.

Hence, provided the integral around the semicircle vanishes (for a number of standard types of functions most commonly used it does vanish) we get

$$\sum_{n=0}^{\infty} f(j \frac{2\pi n}{d}) = \frac{1}{d} \sum_{n=0}^{\infty} F(j \frac{2\pi n}{d}) \text{ for } n=0, \pm 1, \pm 2 \dots$$

$$= -\frac{1}{d} \sum_{n=0}^{\infty} F(j \frac{2\pi n}{d}) \text{ for } n=0, 1, 2 \dots$$

The change in sign is due to the fact that the contour is traversed in a clockwise sense. Sometimes it is possible to close the contour in the left half plane and the sum of the series is given in terms of the residues at the poles enclosed.

We may extend the definition of the Laplace transform so that it is valid for negative values of x as follows :-

$$L f(x) = \int_{-\infty}^0 f(x) e^{-px} dx \quad x < 0$$

The corresponding inversion formula yields

$$f(x) = \frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} e^{px} F(p) dp$$

where C now lies to the left of all singularities of $F(p)$. For positive values of x , the contour may be closed in the left half plane and since no singularities are enclosed the integral vanishes and $f(x) = 0$. For negative values of x the contour may be closed in the right half plane and the original function $f(x)$ is recovered.

Let us now consider a series such as $\sum_{n=-\infty}^{\infty} f(\ln n)$.

Imposing the condition that $f(x)$ is integrable square over $-\infty < x < \infty$
i.e. $\int_{-\infty}^{\infty} |f(x)|^2 dx$ exists, and this in turn implying that $f(x)$ has no poles on the real axis, we break up $f(x)$ into two parts as follows :-

$$f_+(x) = \begin{cases} f(x) & x \geq 0 \\ 0 & x < 0 \end{cases} \quad f_-(x) = \begin{cases} 0 & x > 0 \\ f(x) & x < 0 \end{cases}$$

The corresponding Laplace transforms are

$$F_+(p) = \int_0^\infty e^{-px} f_+(x) dx \quad F_-(p) = \int_{-\infty}^0 e^{-px} f_-(x) dx$$

The corresponding inverse transforms are

$$f_+(x) = \frac{1}{2\pi j} \int_{C_+ - j\infty}^{C_+ + j\infty} e^{px} F_+(p) dp \quad f_-(x) = \frac{1}{2\pi j} \int_{C_- - j\infty}^{C_- + j\infty} e^{px} F_-(p) dp$$

From Parseval's theorem we find that $\int_{-\infty}^\infty |F(p)|^2 dp$ exists if $f(x)$ is of integrable square type. Consequently, $F(p)$ has no poles on the imaginary axis and we may, therefore, take $C_+ < 0$ and $C_- > 0$ in the above inversion integrals. Under those conditions, we get

$$\sum_{n=0}^{\infty} f(\lambda_n) = \frac{1}{2\pi j} \int_{C_- - j\infty}^{C_+ + j\infty} \frac{F_+(p)}{1-e^{-\lambda_n p}} dp = \frac{1}{\lambda} \sum_{n=-\infty}^{\infty} F_+ \left(\frac{j2\pi n}{\lambda} \right)$$

on closing the contour in the right half plane,

$$\text{Similarly, } \sum_{n=-1}^{-\infty} f(\lambda_n) = \frac{1}{\lambda} \sum_{n=-\infty}^{\infty} F_- \left(\frac{j2\pi n}{\lambda} \right), \text{ on closing}$$

the contour in the lefthalf plane.

Combining these results, we finally have,

$$\sum_{n=-\infty}^{\infty} f(\lambda_n) = \frac{1}{\lambda} \sum_{n=-\infty}^{\infty} F \left(\frac{j2\pi n}{\lambda} \right)$$

If we make the following change in notation, $b = jw$, $dp = j dw$, then our bilateral Laplace transforms become Fourier transforms and inverse bilateral Laplace transforms become inverse Fourier transforms,

$$\text{Thus } f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(w) e^{jwx} dw = \int_{-\infty}^{\infty} g(w) e^{jwx} dw$$

$$F(w) = \int_{-\infty}^{\infty} f(x) e^{-jwx} dx \quad g(w) = \frac{1}{2\pi} \int_{-\infty}^{\infty} f(x) e^{-jwx} dx$$

Since the poles at which the residues are taken into account in the summation formula are at $b = jw = j \frac{2\pi n}{d}$ with $x = dn$, we get,

$$\sum_{n=-\infty}^{\infty} f(d_n) = \frac{1}{d} \sum_{n=-\infty}^{\infty} F\left(\frac{-2\pi n}{d}\right) = \frac{2\pi}{d} \sum_{n=-\infty}^{\infty} g\left(\frac{-2\pi n}{d}\right)$$

$$\text{Or } \sum_{n=-\infty}^{\infty} g\left(\frac{-2\pi n}{d}\right) = \frac{1}{2\pi} \sum_{n=-\infty}^{\infty} F\left(\frac{-2\pi n}{d}\right) = \frac{d}{2\pi} \sum_{n=-\infty}^{\infty} f(d_n)$$

This is the Poisson's Summation Formula.

Art. 5. Solution for field quantities inside the di-electric $[v_0, \epsilon_0]$ in volume V in waves V. With Q_{1q}^{pk} elements computed we can solve Equation (4) along with relation 4(a) for J_{1q}^{kW} elements with $C_q^P = S_q^P(Y_q)$ elements known on the basis of sinusoidal variation of unit amplitude and phase reference at the dielectric obstacle centre at $Z = Z_c$ for $b = x, y, z$ and $q = 1, 2, \dots, L$ and obtain the solution in the form

$$J_{1q}^{kW} = \frac{x_1}{-jw v_0}$$

Using the relation $E = \frac{J}{jw[\epsilon(r) - \epsilon_0]}$ we obtain

$$E_1^k = E^k(\gamma_1) \frac{j_1^k}{jw[\epsilon(\gamma_1) - \epsilon_0]} = \frac{jX_1^k}{k_1^2(\gamma_1) - k_0^2} \text{ for } k = x, y, z \in 1, L \\ L = 1, 2, \dots, L$$

Using the relation $E_s = E_i - E_j$ we obtain

$$E_s^k(\gamma_1) = E^k(\gamma_1) - E_{ij}^k(\gamma_1) = \left[\frac{X_1^k}{k_1^2(\gamma_1) - k_0^2} - C_1^k \right] \text{ for } k = x, y, z \\ \text{and } L = 1, 2, \dots, L$$

Art. 6. Solution for the Dominant TE₁₀ Mode T - Equivalent Circuit

Parameters for the di-electric obstacle discontinuity.

Since the solution for the dominant mode T - Equivalent Circuit ponaments is to be valid in the medium (μ_0, ϵ_0) we solve Equation(4) along with relation 4 (b) for $J_1^k = J(\gamma_1)$ elements with $C_q^k = E_j^k(\gamma_q)$ elements known on the basis of sinusoidal variation of unit amplitude and phase reference at the volume V at $\gamma = \gamma_q$ for $p = x, y, z$ and $q = 1, 2, \dots, L$ and get the solution in the form

$$J_1^k = \frac{x_1^k}{-j\omega\mu_0}$$

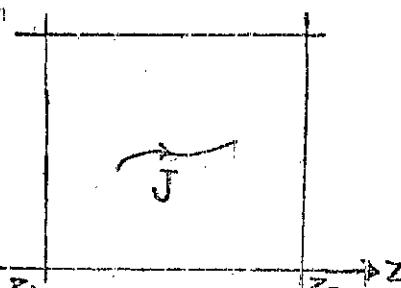


Fig. 3. Terminal planes in a waveguide containing a discontinuity current J at $z=z_1$ & $z=z_2$.

The dominant TE₁₀ mode scattered field due to J in the waveguide medium (μ_0, ϵ_0) in the region between $z=z_1$ and $z=z_2$ (Fig. 3) is given by (Ref. Appendix IV) :-

$$\left. \begin{aligned} E_s^+ &= c_{10}^+ e_{10} e^{-j\beta_{10}(z - z_2)} \\ H_s^+ &= c_{10}^+ h_{10} e^{-j\beta_{10}(z - z_2)} \end{aligned} \right\} \text{for } z \geq z_2 \quad (A)$$

$$\left. \begin{aligned} E_s^- &= c_{10}^- e_{10} e^{j\beta_{10}(z - z_1)} \\ H_s^- &= c_{10}^- h_{10} e^{j\beta_{10}(z - z_1)} \end{aligned} \right\} \text{for } z \leq z_1 \quad (B)$$

$$\text{where } E_{10} = \tilde{\rho} \tilde{y} \sin \frac{\pi x}{a}, \quad h_{10} = -Y_W \tilde{x} \sin \frac{\pi x}{a}, \quad \beta_{10} = \sqrt{k_o^2 - \left(\frac{\pi}{a}\right)^2},$$

Y_W = Wave impedance of the guide.

$$c_{10}^+ = \sum_{k=1}^3 \sum_{l=1}^L c_{10l}^{+k} \quad \text{and} \quad c_{10}^- = \sum_{k=1}^3 \sum_{l=1}^L c_{10l}^{-k}$$

$$c_{10l}^{+k} = c_{10l}^{-k} = -\frac{1}{P_{10}} \int_{\Delta V_l} E_{10} \bar{u}_k J_l^k dV \quad \text{for transverse } J_l^k$$

$$c_{10l}^{+k} = -c_{10l}^{-k} = \frac{1}{P_{10}} \int_{\Delta V_l} \bar{u}_{k1} \bar{u}_{k1}^k \cos \beta_{10} z dy \quad \text{for axial, symmetrical about } z_l, J_l^k$$

$$= 0 \quad (\text{Since } E_{z_{10}} = 0 \text{ for TE}_{10} \text{ mode})$$

$$P_{10} = 2 \int_0^a \int_0^b E_{10} \times h_{10} \cdot \bar{z} dx dy = ab Y_W$$

e.g.

Thus for the single cell case with $\bar{u}_{J_1}^1, \bar{u}_{J_1}^2, \bar{u}_{J_1}^3$, existing

$$\begin{aligned}
 c_{10}^+ &= c_{101}^{+1} + c_{101}^{+2} = 0 + c_{101}^{+2} = -\frac{1}{P_{10}} \int_{-\infty}^{\infty} \sin \frac{\pi x}{a} j_1^2 d\sqrt{x} \\
 &= -\frac{j_1^2 \Delta y_1 \Delta z_1}{\pi b Y_w} \left[\sin \frac{\pi x}{a} \left(x_1 + \frac{\Delta x_1}{2} \right) - \cos \frac{\pi x}{a} \left(x_1 - \frac{\Delta x_1}{2} \right) \right] \\
 &= -\frac{j^2 \Delta y_1 \Delta z_1}{\pi b Y_w} \sin \frac{\pi x_1}{a} \sin \frac{\pi \Delta x_1}{2a} \quad (B)
 \end{aligned}$$

$$\text{Since } j_1^2 = \frac{x_1^2}{-j\omega \mu_0} = j \frac{x_1^2 Y_w}{B_{10}}$$

Similarly we find $P_{10}^- = c_{10}^- = c_{10}$

It is to be noted that although there are other modes, mostly evanescent type, only the dominant mode survive attenuation in practical cases and the other modes are attenuated in a short distance from the discontinuity between terminal planes at z_1 and z_2 .

Considering the waveguide to be uniform and exactly of similar size and matched on the LHS and RHS of discontinuity region between z_1 and z_2 ,
 [From Equation (A)]

For $z \leq z_1$, Total field with incident field from LHS

$$E_1 = E_i^+ + E_s^+ = A_{10}^+ e_{10}^- e^{-j\beta_{10}(z-z_1)} + C_{10}^- e_{10}^+ e^{+j\beta_{10}(z-z_1)}$$

$$H_1 = H_i^+ + H_s^+ = A_{10}^+ h_{10}^- e^{-j\beta_{10}(z-z_1)} - C_{10}^- h_{10}^+ e^{+j\beta_{10}(z-z_1)}$$

For $z > z_2$ total field with incident field from RHS

$$E_2 = E_i^- + E_s^+ = A_{10}^- e^{j\beta_{10}(z-z_2)} + C_{10}^+ e^{-j\beta_{10}(z-z_2)}$$

$$H_2 = H_i^- + H_s^+ = -A_{10}^- h_{10} e^{j\beta_{10}(z-z_2)} + C_{10}^+ h_{10} e^{-j\beta_{10}(z-z_2)}$$

The following equivalent transmission line voltages and currents are now introduced :

$$V_1^+ = K_1 A_{10}^+ \quad V_1^- = K_1 C_{10}^- \quad V_2^+ = K_1 A_{10}^- \quad V_2^- = K_1 C_{10}^+$$

$$I_1^+ = K_2 A_{10}^+ \quad I_1^- = K_2 C_{10}^- \quad I_2^+ = -K_2 A_{10}^- \quad I_2^- = -K_2 C_{10}^+$$

Where $K_1 K_2 = \frac{ab Y_W}{2}$ } from power flow consideration
 $K_1/K_2 = Z_W = 1/Y_W$ } and $K_1 = \sqrt{\frac{ab}{2}}$, $K_2 = \sqrt{\frac{ab}{2}} Y_W$ [17]

With these the total voltages V_1 and V_2 and currents I_1 and I_2 are given by

For $z < z_1$

$$\left. \begin{aligned} V_1 &= V_1^+ e^{-j\beta_{10}(z-z_1)} + V_1^- e^{j\beta_{10}(z-z_1)} \\ I_1 &= I_1^+ e^{-j\beta_{10}(z-z_1)} - I_1^- e^{j\beta_{10}(z-z_1)} \end{aligned} \right\}$$

$$\left. \begin{aligned} V_2 &= V_2^+ e^{j\beta_{10}(z-z_2)} + \dots \\ I_2 &= I_2^+ e^{j\beta_{10}(z-z_2)} - \dots \\ &\quad - I_2^- e^{-j\beta_{10}(z-z_2)} \end{aligned} \right\}$$

For the terminal plane at $z = z_1$

$$V_1 = V_1^+ + V_1^-$$

$$I_1 = I_1^+ - I_1^-$$

For the terminal plane at $z = z_2$

$$V_2 = V_2^+ + V_2^-$$

$$I_2 = I_2^+ - I_2^-$$

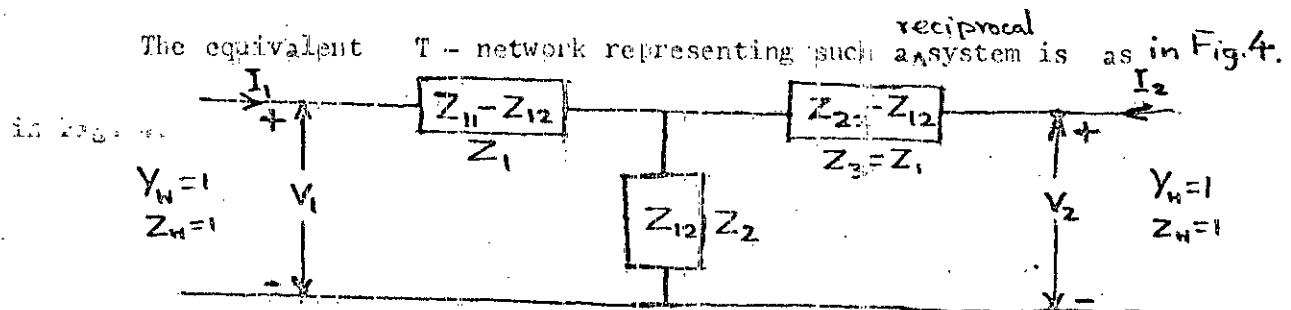


Fig. 4.

The equations relating the L.H.S. and R.H.S. voltages and currents are

$$\left. \begin{aligned} V_1 &= z_{11} I_1^+ + z_{12} I_2^+ \\ V_2 &= z_{12} I_1^+ + z_{22} I_2^+ \end{aligned} \right\} \quad \text{for a reciprocal system with } z_{12} = z_{21}$$

For a lossless discontinuity the Z-parameters become imaginary.

For a normalized voltage & current system with $Y_H = 1$ (assumed), $K_1 = K_2 = K$

and for a completely symmetrical system, $A_{10}^+ = A_{10}^- = A_{10}$, $C_{10}^+ = C_{10}^- = C_{10}$

and under these conditions we get, [N.B. For a symmetrical system $z_{11} = z_{22}$]

$$V_1^+ = V_2^+, \quad I_1^+ = I_2^+, \quad V_1^- = V_2^-, \quad I_1^- = I_2^-, \quad V_1 = V_2, \quad I_1 = I_2$$

This implies $z_{11} = z_{22}$ and the above two network equations become similar i.e. $V_1 = (z_{11} + z_{12}) I_1$ (B)

$$\text{Also from Fig. 4 with } z_{22} = z_{11} \text{ the input impedance } \frac{V_1}{I_1} = \frac{(z_{11} - z_{12}) + z_{11}}{1 + z_{22}} \quad (\text{D})$$

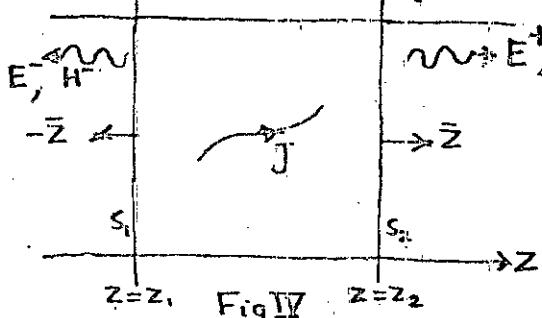
With C_{10} known from Equation (B), $A_{10} = 1$, $K = \sqrt{\frac{ab}{2}}$, V_1 & I_1 are known.

Thus $\frac{V_1}{I_1} = z_K$ (known). Now solving Equation (B) and (D), we get

$$z_{11} = \frac{z_k (1 + z_k)}{2 + z_k} \quad \text{and} \quad z_{12} = -\frac{z_k}{2 + z_k} \quad \text{where } z_k = \frac{V_i}{I_i} = \frac{V_i^+ + V_i^-}{I_i^+ - I_i^-} = \frac{K_1 A_{10} + K_1 C_{10}}{K_2 A_{10}^+ - K_2 C_{10}^-}$$

$$= \frac{K A_{10} + K C_{10}}{K A_{10} - K C_{10}} = \frac{A_{10} + C_{10}}{A_{10} - C_{10}} = \frac{1 + C_{10}}{1 - C_{10}}$$

Appendix IV Radiation from current source in a Waveguide (12)



The adjacent Figure IV illustrates an infinitely long waveguide in which a current source J is located in the region between $z=z_1$ and $z=z_2$. The wavy arrows indicate the direction of propagation

The field radiated by this source may be expressed as a combination of allowable

waveguide modes as follows :-

$$E^+ = \sum_n c_n^+ (e_n + e_{zn}) e^{-jB_n(z-z_2)} \left. \begin{array}{l} \text{for } z > z_2 \\ \text{if } z < z_1 \end{array} \right\} \text{for } z > z_2 \quad (Ia)$$

$$H^+ = \sum_n c_n^+ (h_n + h_{zn}) e^{-jB_n(z-z_2)} \left. \begin{array}{l} \text{for } z > z_2 \\ \text{if } z < z_1 \end{array} \right\} \text{for } z > z_2 \quad (Ib)$$

$$E^- = \sum_n c_n^- (e_n - e_{zn}) e^{jB_n(z-z_1)} \left. \begin{array}{l} \text{for } z < z_1 \\ \text{if } z > z_2 \end{array} \right\} \text{for } z < z_1 \quad (IIa)$$

$$H^- = \sum_n c_n^- (-h_n + h_{zn}) e^{jB_n(z-z_1)} \left. \begin{array}{l} \text{for } z < z_1 \\ \text{if } z > z_2 \end{array} \right\} \text{for } z < z_1 \quad (IIb)$$

With $e^{jB_n z_2}$ and $e^{-jB_n z_1}$ made implicit for the time being,

as they are not affecting the following derivation, we have,

$$E^+ = \sum_n c_n^+ (e_n + e_{zn}) e^{-jB_n z} \left. \begin{array}{l} \text{for } z > z_2 \\ \text{if } z < z_1 \end{array} \right\} \text{for } z > z_2 \quad (IIa)$$

$$H^+ = \sum_n c_n^+ (h_n + h_{zn}) e^{-jB_n z} \left. \begin{array}{l} \text{for } z > z_2 \\ \text{if } z < z_1 \end{array} \right\} \text{for } z > z_2 \quad (IIb)$$

$$E^- = \sum_n c_n^- (e_n - e_{zn}) e^{jB_n z} \left. \begin{array}{l} \text{for } z < z_1 \\ \text{if } z > z_2 \end{array} \right\} \text{for } z < z_1 \quad (IIa)$$

$$H^- = \sum_n c_n^- (-h_n + h_{zn}) e^{jB_n z} \left. \begin{array}{l} \text{for } z < z_1 \\ \text{if } z > z_2 \end{array} \right\} \text{for } z < z_1 \quad (IIb)$$

Where the summation index n implies a summation over all possible TE and TM modes ; e_n and h_n are the transverse mode vectors and are functions of x and y coordinates, e_{zn} & h_{zn} are the axial mode vectors and are functions of x & y coordinates ; β_n is the mode propagation constant.

Let E_1, H_1 represent the field yielded by the current source J and expressed by Equation II and let $E_2 = E_n^- = (e_n - e_{zn}) e^{j\beta_n z}$
 $H_2 = H_n^- = (-h_n + h_{zn}) e^{j\beta_n z}$ be the source free field ($J_2 = 0$) within V enclosed by S i.e. the region between $z=z_1$ and $z=z_2$

$$\text{By reciprocity relation } \int_S (E_1 \times H_n^- - E_n^- \times H_1) \cdot \bar{n} ds = \int_V E_n^- \cdot J dv.$$

The surface integral is zero over the waveguide walls by virtue of the boundary condition $\bar{n} \times E_1 = \bar{n} \times E_n^- = 0$. Since the modes are orthogonal

$$\text{i.e. } \int_{S_0} E_m^+ \times H_n^+ \cdot \bar{n} ds = 0 \quad n \neq m \quad [\text{Ref. (12) Pg 121-124}]$$

all the terms except the n th in the expansion of E_1, H_1 vanish when integrated over the arbitrary waveguide cross section S_0 . Thus we have,

$$\begin{aligned} & \int_{S_2}^+ c_n^+ [(e_n + e_{zn}) \times (-h_n + h_{zn}) - (e_n - e_{zn}) \times (h_n + h_{zn})] \bar{z} ds \\ & - \int_{S_1}^+ c_n^+ [(e_n - e_{zn}) \times (-h_n + h_{zn}) - (e_n + e_{zn}) \times (-h_n + h_{zn})] \bar{z} ds \\ & = -2 c_n^+ \int_{S_2} E_n \times h_n \cdot \bar{z} ds = \int_V E_n^- \cdot J dv; \quad \text{Since the integral over} \\ & \text{waveguide cross-section } S_1 \text{ vanishes identically. Hence } c_n^+ \text{ is given by} \end{aligned}$$

$$C_n^+ = -\frac{1}{P_n} \int_V E_n^+ J dv = -\frac{1}{P_n} \int_V (e_n - e_{zn}) \cdot J e^{jB_n z} dv$$

If E_n^+ , H_n^+ is chosen for the field E_2 , H_2 , we obtain

$$C_n^- = -\frac{1}{P_n} \int_V E_n^+ \cdot J dv = -\frac{1}{P_n} \int_V (e_n + e_{zn}) \cdot J e^{-jB_n z} dv$$

where $P_n = 2 \int_{S_2} \mathbf{E}_n \times \mathbf{h}_n \cdot \hat{\mathbf{z}} ds = 2 \int_{S_0} \mathbf{E}_n \times \mathbf{h}_n \cdot \hat{\mathbf{z}} ds$, [Since S_2 at z_2 was chosen arbitrarily.]

For transverse J at $z = z_2 \approx 0$ i.e. z_2 is near origin, we have

$$C_n^+ = C_n^- = -\frac{1}{P_n} \int_V \mathbf{e}_{zn} \cdot \mathbf{J} dv \quad \text{Since } \mathbf{e}_{zn} \cdot \mathbf{J} = 0$$

For axial J , at $z = z_2 \approx 0$ i.e. z is near origin, we have

$$C_n^+ = \frac{1}{P_n} \int_V J \cdot \mathbf{e}_{zn} \mathcal{Q}^{jB_n z} dv, \quad C_n^- = -\frac{1}{P_n} \int_V J \cdot \mathbf{e}_{zn} \bar{\mathcal{Q}}^{jB_n z} dv. \quad (\text{Since } \mathbf{e}_{zn} \cdot \mathbf{J} = 0)$$

If J is a symmetrical function of z , then, since \mathbf{e}_{zn} is not a function of z , we have

$$C_n^+ = C_n^- = -\frac{1}{P_n} \int_V J \cdot \mathbf{e}_{zn} \cos B_n z dv$$

With C_n^+ and C_n^- thus determined we can now revoke the factors

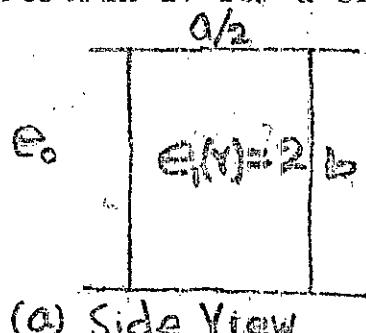
$\mathcal{Q}^{jB_n z_2}$ & $\bar{\mathcal{Q}}^{-jB_n z_1}$ and have the radiation expressions given by

Equation I.

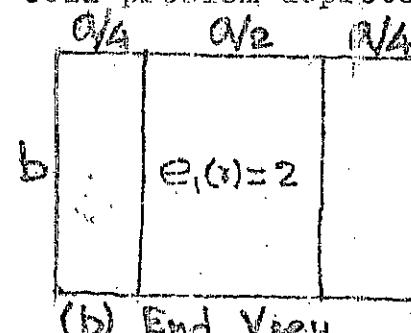
CHAPTER-IV

Determination of Equivalent Circuit Parameters For
A Three Dimensional Dielectric Obstacle in A Rectangular
Waveguide.

With the formulation and moment method of solving of the problem involving a dielectric in an arbitrary volume V inside a rectangular waveguide discussed so far we now apply the method to an illustrative example. It is to be noted that, to represent accurately the arbitrarily shaped dielectric in the volume V the cell size of volume ΔV_1 should be made small and consequently the number of cells for the given volume should be large. This implies a Computer solution on a large scale. However to illustrates the effectiveness of the method without loosing any essential feature we undertake now the digital computer programming based on Fortran IV for a single cell problem depicted in Fig.5.



(a) Side View



(b) End View

Fig.5. A rectangularly shaped dielectric in a rectangular Waveguide.

$$\begin{aligned}a &= 2.54 \text{ cm} \\b &= 1.27 \text{ cm} \\k^2 &= \frac{2\pi^2}{a^2} \\K^2(v) &= \frac{4\pi^2}{a^2}\end{aligned}$$

From Fig-5, $X_q = -\frac{a}{2}$, $X_1 = \frac{a}{2}$, $\Delta X_1 = \frac{a}{2}$, $Y_q = \frac{a}{4}$,

$Y_1 = \frac{a}{4}$, $\Delta Y_1 = \frac{a}{2}$, $Z_q = 0$, $Z_1 = 0$, $\Delta Z_1 = \frac{a}{2}$.

With above data the relevant expressions for the nine

different Q_{1q}^{Hk} elements per cell of size ($\Delta X_1 \times \Delta Y_1 \times \Delta Z_1$)

are as follows :-

Q_{1q}^H

For $Z_q \neq Z_1$ we have from Equation (21.1)

$$Q_{1q}^H = \left\{ 2C \left(\frac{4b \Delta X_1}{\pi} \right) \sum_{m=1}^{20} \frac{k_o^2 e^{-\zeta_{om}} |Z_q - Z_1|}{m \zeta_{om}^2} \sinh \zeta_{om} \frac{\Delta Z_1}{2} \right\}$$

$$+ \left\{ 4C \left(\frac{8ab}{\pi^2} \right) \sum_{n=1}^{20} \frac{1}{n} \cos \frac{n\pi x_q}{a} \cos \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta X_1}{2a} \right\}$$

$$\sum_{m=1}^{20} \left[\frac{k_o^2 - (\frac{n\pi}{a})^2}{m \zeta_{nm}^2} \right] e^{-\zeta_{nm}} (Z_q - Z_1) \sinh \zeta_{nm} \frac{\Delta Z_1}{2} \cdot \sin \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b}$$

$$= \left\{ \sum_{m=1}^{20} (B_{11})(X_1)(E_{11}L_{1q}) \right\} + \left\{ \sum_{n=1}^{20} A_{11N} \sum_{m=1}^{20} (B_{11})(X_{11})(E_{11}L_{1q}) \right\}$$

$$= \left[\sum_{m=1}^{20} B_{11} L_{1q M} + \sum_{n=1}^{20} A_{11N} \sum_{m=1}^{20} B_{11} L_{1q M} \right]$$

Where

$$B_{II} = \sin \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b}$$

$$X_{II} = 2c \left(\frac{4b \Delta x_1}{\pi Y} \right) \frac{k_o^2}{m \zeta_{nm}}$$

$$E_{ILQ} = e^{-\zeta_{nm}} \{ z_q - z_1 \} \sinh \zeta_{nm} \frac{\Delta z_1}{2}$$

$$A_{II}N = \frac{1}{n} \cos \frac{n\pi X_q}{a} \cos \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta x_1}{2a}$$

$$X_{II} = 4c \left(\frac{8ab}{\pi^2} \right) \frac{[k_o^2 - (n\pi)^2]}{m \zeta_{nm}^2}$$

$$E_{LQ} = e^{-\zeta_{nm}} \{ z_q - z_1 \} \sinh \zeta_{nm} \frac{\Delta z_1}{2}$$

$$B_{ILQM} = (B_{II})(X_{II})(E_{ILQ})$$

$$B_{IQNM} = (B_{II})(X_{II})(E_{LQ})$$

For $Z_q = Z_1$ we proceed in the manner outlined in Art 3(b)

of Ch.III.

Putting $j \left(1 - e^{-\zeta_{nm} \frac{\Delta z_1}{2}} \right)$ instead of factor $\left(e^{-\zeta_{nm}} \{ z_q - z_1 \} \right)$,

$\sinh \zeta_{nm} \frac{\Delta z_1}{2}$ and putting $j \left(1 - e^{-\zeta_{nm} \frac{\Delta z_1}{2}} \right)$ instead of factor $\left(e^{-\zeta_{nm}} \{ z_q - z_1 \} \sinh \zeta_{nm} \frac{\Delta z_1}{2} \right)$ in the Equation (21.1)

and rearranging terms, we have,

$$Q_{1q} = \left\{ j \left[2c \left(\frac{4b \Delta x_1}{\pi Y} \right) \sum_{m=1}^{20} \frac{k_o^2}{m \zeta_{nm}} \sin \frac{m\pi Y_q}{b} \right] \right.$$

$$\left. \cdot \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b} + 4c \left(\frac{8ab}{\pi^2} \right) \sum_{n=1}^{20} \frac{1}{n} \cos \frac{n\pi X_q}{a} \right.$$

$$\left. \cdot \cos \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta x_1}{2a} \sum_{m=1}^{20} \frac{[k_o^2 - (n\pi)^2]}{m \zeta_{nm}^2} \sin \frac{m\pi Y_q}{b} \right]$$

$$\left. \cdot \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b} \right\}$$

$$\text{Right } \frac{\partial^2 T}{\partial X^2} = \frac{1}{2b} \sum_{m=1}^{20} \left\{ \left[\frac{4b \Delta X_1}{\pi} \right] \sum_{n=1}^{20} \frac{k_o^2 - G_{nm} \Delta Z_1}{m k_{nm}} \right\}$$

$$= \frac{1}{2} \sin \frac{m \pi Y_q}{b} \sin \frac{m \pi Y_1}{b} \sin \frac{m \pi \Delta Y_1}{2b} + 4C \left(\frac{8ab}{\pi^2} \right).$$

$$\sum_{n=1}^{20} \frac{1}{n} \cos \frac{n \pi Ix_q}{a} \cos \frac{n \pi Ix_1}{a} \sin \frac{n \pi \Delta X_1}{2a} \sum_{m=1}^{20} \frac{[k_o^2 - (\frac{n \pi}{a})^2]}{m k_{nm}^2}$$

$$= Q^{-G_{nm} \Delta Z_1} \left[\sin \frac{m \pi Y_q}{b} \sin \frac{m \pi Y_1}{b} \sin \frac{m \pi \Delta Y_1}{2b} \right]$$

$$= \left\{ j \left[2C \left(\frac{4b \Delta X_1}{\pi} \right) G_{1111} - 4C \left(\frac{8ab}{\pi^2} \right) \right] \sum_{n=2}^{20} (A_{1111})(F_{111111}) \right.$$

$$\left. - 4C \left(\frac{8ab}{\pi^2} \right) (A_{1111})(F_{111111}) \right] - j \left[\sum_{m=1}^{20} B_{111111} + \sum_{n=1}^{20} (A_{1111}) \sum_{m=1}^{20} B_{1111111} \right]$$

where as shown in Art 3(b) of Ch.III

$$G_{1111} = G_{11}(1) + G_{11}(2) - G_{11}(3) - G_{11}(4)$$

Wherein

$$G_{11}(I) = \frac{[m \cdot T(I)]}{2} + \frac{\pi}{2} \frac{\sin a_o [m \cdot T(I)]}{\sin a_o \pi} = \frac{\pi}{2}$$

$$= \frac{\pi}{2} \frac{\sin \left[\frac{b k_o}{\pi} (m \cdot T(I)) \right]}{\sin \left(\frac{b k_o}{\pi} m \right)} - \frac{[m \cdot T(I)]}{2} \text{ for } T(1) = \frac{\pi}{b} \left(Y_q + Y_1 - \frac{\Delta Y_1}{2} \right)$$

$$T(2) = \frac{\pi}{b} \left(Y_q - Y_1 + \frac{\Delta Y_1}{2} \right), \quad T(3) = \frac{\pi}{b} \left(Y_q + Y_1 + \frac{\Delta Y_1}{2} \right),$$

$$T(4) = \frac{\pi}{b} \left(Y_q - Y_1 - \frac{\Delta Y_1}{2} \right)$$

$$F_{\text{ILLN}} = \sum_{n=1}^{20} \left(-Y_q + Y_n + \frac{Y_1}{k_o^2} \right)$$

$$F_{\text{ILLN}} = F_{\text{ff}}(1) + F_{\text{ff}}(2) + F_{\text{ff}}(3) + F_{\text{ff}}(4)$$

wherein $F_{\text{ff}}(I) = \frac{\pi I - T(I)}{2} - \frac{\pi}{2} \frac{\sinh(a_n(\pi I - T(I)))}{\sinh(a_n \pi)}$ with

$$a_n = \frac{b}{\pi I} \sqrt{\left(\frac{\pi I}{a}\right)^2 - k_o^2} \quad A_{\text{ff}} = A_{\text{ffN}} \Big]_{n=1}$$

$$F_{\text{ILLI}} = F_{\text{f}}(1) + F_{\text{f}}(2) + F_{\text{f}}(3) + F_{\text{f}}(4)$$

wherein $F_{\text{f}}(I) = \frac{\pi I - T(I)}{2} - \left(\frac{\pi}{2}\right) \cdot \frac{\sin\left[\frac{b}{a}(\pi I - T(I))\right]}{\sin\left(\frac{b}{a}\pi\right)}$ with

$$a_1 = \frac{b}{\pi I} \sqrt{\left(\frac{\pi I}{a}\right)^2 - \frac{2\pi^2}{a^2}} = j \frac{b}{a}$$

$$B_{\text{ILLM}} = (B_{\text{ff}})(X_{\text{ff}})(E_{\text{LL}}) \text{ wherein } E_{\text{LL}} = Q^{-\epsilon_{\text{om}} \frac{\Delta z_1}{2}}$$

$$B_{\text{ILLNM}} = (B_{\text{ff}})(X_{\text{ff}})(E_{\text{LL}}) \text{ wherein } E_{\text{LL}} = Q^{-\epsilon_{\text{om}} \frac{\Delta z_1}{2}}$$

$$\frac{22}{Q_{1q}}$$

For $Z_q \neq Z_1$ we have from Equation (21.2)

$$Q_{1q}^{22} = \left[2 c \left(\frac{4a \Delta Y_1}{\pi I} \right) \sum_{n=1}^{20} \frac{k_o^2 e^{-\epsilon_{\text{no}} |Z_q - Z_1|}}{n \epsilon_{\text{no}}^2} \right]$$

$$\cdot \sinh \epsilon_{\text{no}} \frac{\Delta z_1}{2} \cdot \sin \frac{n\pi I x_q}{a} \sin \frac{n\pi I x_1}{q} \sin \frac{n\pi \Delta x_1}{2a} \Bigg\}$$

$$+ \left\{ 4c \left(\frac{8ab}{\pi I^2} \right) \sum_{m=1}^{20} \frac{1}{m} \cos \frac{m\pi I y_q}{b} \cos \frac{m\pi I y_1}{b} \sin \frac{m\pi \Delta y_1}{2b} \right\}$$

$$\sum_{n=1}^{20} \frac{\left[k_o^2 - \left(\frac{m\pi I}{b} \right)^2 \right]}{n \epsilon_{\text{nm}}^2} Q^{-\epsilon_{\text{nm}} |Z_q - Z_1|} \sinh \epsilon_{\text{nm}} \frac{\Delta z_1}{2} \cdot \sin \frac{n\pi I x_q}{a} \sin \frac{n\pi I x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} \Bigg]$$

$$= \left[B_{2LQ1} + \sum_{n=2}^{20} B_{2LQN} + \sum_{m=1}^{20} A_{22M} \sum_{n=1}^{20} B_{22QNM} \right]$$

where $B_{2LQN} = (B_{22})(X_2)(E_{2LQ})$

$$\text{wherein } B_{22} = \sin \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta y_1}{2a}$$

$$X_2 = 2c \left(\frac{4a \Delta y_1}{\pi} \right) \left(\frac{k_o^2}{n \epsilon_{no}^2} \right)$$

$$E_{2LQ} = Q^{-G_{np}} | z_q - z_1 | \cdot \sinh \frac{G_{np} \Delta z_1}{2}$$

$$B_{2LQ1} = B_{2LQN} \Big|_{n=1} \quad \text{with } G_{10} = j \frac{\pi}{a}$$

$$A_{22M} = \frac{1}{m} \cos \frac{m\pi y_q}{b} \cos \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b}$$

$$B_{22QNM} = (B_{22})(X_2)(E_{LQ})$$

$$\text{wherein } X_{22} = 4c \left(\frac{8ab}{\pi^2} \right) \left[\frac{k_o^2 - \left(\frac{m\pi}{b} \right)^2}{n \epsilon_{nm}^2} \right]$$

For $z_q = z_1$ we proceed in the manner outlined in Art 3(b) of

Ch.III. Putting $j(1-e^{-G_{np} \frac{\Delta z_1}{2}})$ instead of factor

$Q^{-G_{np}} |z_q - z_1| \cdot \sinh \frac{G_{np} \Delta z_1}{2}$ and putting $j(1-e^{-G_{nm} \frac{\Delta z_1}{2}})$

instead of factor $Q^{-G_{nm}} |z_q - z_1| \cdot \sinh \frac{G_{nm} \Delta z_1}{2}$ in the

equation (21.2) and rearranging terms, we have,

$$Q_{\text{eq}}^{22} = \left\{ j \left[2c \left(\frac{4a \Delta Y_1}{\pi} \right) \sum_{n=1}^{20} \frac{k_o^2}{n G_{no}^2} \sin \frac{n\pi X_q}{a} \right] + \right.$$

$$\left. \cdot \sin \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a} + 4c \left(\frac{8ab}{\pi^2} \right) \sum_{m=1}^{20} \frac{1}{m} \cos \frac{m\pi Y_q}{b} \right.$$

$$\left. \cos \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{b} \sum_{n=1}^{20} \frac{\left[k_o^2 - \left(\frac{m\pi}{b} \right)^2 \right]}{n G_{nm}^2} \sin \frac{n\pi X_q}{a} \right]$$

$$\left. \cdot \sin \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a} \right] - j \left[2c \left(\frac{4a \Delta Y_1}{\pi} \right) \sum_{n=1}^{20} \frac{k_o^2}{n G_{no}^2} \right]$$

$$\left. - Q_{\text{eq}} \frac{4Z_p Z_1}{\pi^2} \cdot \sin \frac{n\pi X_q}{a} \sin \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a} \right]$$

$$+ 4c \left(\frac{8ab}{\pi^2} \right) \sum_{m=1}^{20} \frac{1}{m} \cos \frac{m\pi Y_q}{b} \cos \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b},$$

$$\left. \sum_{n=1}^{20} \frac{\left[k_o^2 - \left(\frac{m\pi}{b} \right)^2 \right]}{n G_{nm}^2} \sin \frac{n\pi X_q}{a} \sin \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a} \right\}$$

$$= j \left[2c \left(\frac{4a \Delta Y_1}{\pi} \right) G_{22LL} - 4c \left(\frac{8ab}{\pi^2} \right) \sum_{m=1}^{20} (\Lambda_{22M}) \sum_{n=1}^{20} (F_{22LM}) \right]$$

$$- j \left[B_{2LL1} + \sum_{m=2}^{20} B_{2LLN} + \sum_{m=1}^{20} (\Lambda_{22M}) \sum_{n=1}^{20} B_{22LNM} \right]$$

whereas shown in Art 3(b) of Ch. III.

$$G_{22LL} = G_{22}(5) + G_{22}(6) - G_{22}(7) - G_{22}(8)$$

$$\text{wherein } G_{22}(I) = \frac{\pi}{2} \frac{\sin b_o (\pi - T(I))}{\sin b_o \pi} \cdot \frac{[T_I - T(I)]}{2} \text{ with } b_o = \frac{ak_o}{\pi}$$

$$T_I = \frac{a K_C}{2 \pi}$$

$$\text{for } T(5) = \frac{\pi}{a} \left(x_q + x_1 - \frac{\Delta x_1}{2} \right), \quad T(6) = \frac{-\pi}{a} \left(x_q - x_1 + \frac{\Delta x_1}{2} \right),$$

$$T(7) = \frac{\pi}{a} \left(x_q + x_1 + \frac{\Delta x_1}{2} \right), \quad T(8) = \frac{\pi}{a} \left(x_q - x_1 - \frac{\Delta x_1}{2} \right)$$

$$F22LLM = F22(5) + F22(6) - F22(7) - F22(8)$$

$$\text{wherein } F22(I) = \frac{[\pi - T(I)]}{2} - \left(\frac{\pi}{2} \right) \cdot \frac{\sinh b_m [\pi - T(I)]}{\sinh(b_m \pi)} \text{ with}$$

$$b_m = \frac{a}{\pi} \sqrt{\left(\frac{m\pi}{b}\right)^2 - k_o^2}$$

$$B2LLN = (B22)(X2)(E2LL) \text{ wherein } E2LL = Q^{-\frac{6}{2}} \sinh \frac{\Delta x_1}{2}$$

$$B2LLI = [B2LLN]_{n=1}$$

$$B22LNM = (B22)(X22)(ELL) \text{ wherein } ELL = Q^{-\frac{6}{2}} \sinh \frac{\Delta x_1}{2}$$

$$\underline{Q^{33}_{1q}}$$

For $z_q \neq z_1$ we have from Equation (21.5)

$$Q^{33}_{1q} = \left[4C \left(\frac{8ab}{\pi^2} \right) \sum_{n=1}^{20} \frac{1}{G_{nm}} \sin \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a} \right]$$

$$\sum_{m=1}^{20} \frac{\left[\left(\frac{n\pi}{a} \right)^2 + \left(\frac{m\pi}{b} \right)^2 \right]}{G_{nm}^2} \cdot Q^{-\frac{6}{2}} \sinh \frac{\Delta x_1}{2} \sinh \frac{\Delta z_1}{2},$$

$$\left. \times \sin \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi y_1}{2b} \right] \Rightarrow A33N \sum_{n=1}^{20} B33QNM$$

$$\text{where } A33N = \frac{1}{n} \sin \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a}$$

$$B33QNM = (B33)(X33)(ELQ)$$

$$\text{Wherein } B33 = \sin \frac{m\pi y_q}{b} \sin \frac{m\pi y_1}{b} \sin \frac{m\pi \Delta y_1}{2b}$$

$$X_{33} = 4C \left(\frac{8ab}{\pi^2} \right) \cdot \frac{\left[\left(\frac{n\pi}{a} \right)^2 + \left(\frac{m\pi}{b} \right)^2 \right]}{m^2 n^2}$$

$$ELQ = e^{-G_{nm}|Z_q - Z_1|} \cdot \sinh G_{nm} \frac{\Delta Z_1}{2}$$

For $Z_q = Z_1$ we proceed in the manner outlined in Art 3(b)

of Ch.III. Putting $j(1-e^{-G_{nm}\frac{\Delta Z_1}{2}})$ instead of factor

$\left(e^{-G_{nm}|Z_q - Z_1|} \cdot \sinh G_{nm} \frac{\Delta Z_1}{2} \right)$ in the Equation (21.3) and re-arranging terms,

we have,

$$\begin{aligned}
 Q_{1q}^{33} &= j \left[4C \left(\frac{8ab}{\pi^2} \right) \sum_{n=1}^{20} \frac{1}{n} \sin \frac{n\pi X_q}{a} \sin \frac{n\pi X_1}{a} \right. \\
 &\quad \cdot \sin \frac{n\pi \Delta X_1}{2a} \cdot \sum_{m=1}^{20} \frac{\left[\left(\frac{n\pi}{a} \right)^2 + \left(\frac{m\pi}{b} \right)^2 \right]}{m^2 n^2} \sin \frac{m\pi Y_q}{b} \\
 &\quad \left. \cdot \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b} \right] - j \left[4C \left(\frac{8ab}{\pi^2} \right) \sum_{n=1}^{20} \frac{1}{n} \sin \frac{n\pi X_q}{a} \right. \\
 &\quad \cdot \sin \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a} \cdot \sum_{m=1}^{20} \frac{\left[\left(\frac{n\pi}{a} \right)^2 + \left(\frac{m\pi}{b} \right)^2 \right]}{m^2 n^2} \underbrace{G_{nm} \frac{\Delta Z_1}{2}}_{m^2 n^2} \\
 &\quad \left. \cdot \sin \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b} \right] \} = j \left[4C \left(\frac{8ab}{4\pi^2} \right) (A331) \right. \\
 &\quad \left. + (F33LL1) + 4C \left(\frac{8ab}{4\pi^2} \right) \sum_{n=2}^{20} (A33N)(F33LLN) - \left[\sum_{n=1}^{20} \frac{1}{n} A33N \right] \right]
 \end{aligned}$$

$$\begin{aligned}
 &\sum_{m=1}^{20} B33 \text{ LNM} \quad \boxed{B33 \text{ LNM}}
 \end{aligned}$$

where as shown in Art. 3(b) of Ch. XIII

$$A_{33N} = \frac{1}{n} \sin \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a}$$

$$F_{33LLN} = F_{33}(1) + F_{33}(2) - F_{33}(3) - F_{33}(4)$$

$$\text{wherein } F_{33}(1) = \left[\frac{(\pi - T(1))}{2} - \left(\frac{a_o^2}{a^2} \right) \cdot \frac{\left[\pi - T(1) \right]}{2} \cdot \frac{\sinh_n [\pi - T(1)]}{2 \sinh(a_n \pi)} \right]$$

$$\text{with } a_o = \frac{bk_o}{\pi}, \quad a_n = -\frac{b}{\pi} \sqrt{\left(\frac{n\pi}{a} \right)^2 - k_o^2}$$

$$A_{331} = A_{33N} \prod_{n=1}^{20}$$

$$F_{33LL1} = F_{331}(1) + F_{331}(2) - F_{331}(3) - F_{331}(4)$$

$$\text{wherein } F_{331}(1) = \left[\frac{[\pi - T(1)]}{2} - \left(a_o^2 \right) \cdot \left(-\frac{a^2}{b^2} \right) \cdot \frac{[\pi - T(1)]}{2} \right]$$

$$+ \left(a_o^2 \right) \cdot \left(-\frac{a^2}{b^2} \right) \cdot \left(\frac{\pi}{2} \right) \cdot \frac{\sin \frac{b}{a} [\pi - T(1)]}{\sin \left(\frac{b}{a} \pi \right) T(1)}$$

$$B_{33LNM} = (B_{33})(X_{33}) \text{ (ELL)}$$

$$\text{wherein } X_{33} = 4C \left(\frac{8ab}{\pi^2} \right) \cdot \frac{\left[\left(\frac{n\pi}{a} \right)^2 + \left(\frac{m\pi}{b} \right)^2 \right]}{G_{nm}^2}$$

$$\text{ELL} = Q^{-\frac{G_{nm} \Delta z_1}{\pi^2}}.$$

$$\underline{\underline{Q}}_{1q}^{12}$$

For $Z_q \neq Z_1$ we have from Equation 21.4

$$\underline{\underline{Q}}_{1q}^{12} = 4C (-8) \sum_{n=1}^{20} \cos \frac{n\pi x_q}{a} \sin \frac{n\pi x_1}{a} \sin \frac{n\pi \Delta x_1}{2a},$$

$$\underline{\underline{Q}}_{1q}^{12} = \sum_{m=1}^{20} \frac{Q^{-G_{nm} |Z_q - Z_1|}}{G_{nm}^2} \cdot \sinh G_{nm} \frac{\Delta z_1}{2},$$

$$x \cdot \sin \frac{n\pi x_q}{b} \cos \frac{n\pi x_1}{b} \sin \frac{n\pi \Delta x_1}{2b}$$

$$= \sum_{n=1}^{20} A_{12N} \sum_{m=1}^{20} B_{12QNM}$$

where $A_{12N} = \cos \frac{n\pi X_q}{a} \sin \frac{m\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a}$

$$B_{12QNM} = (B_{12}) (X_{12}) (ELQ)$$

wherein $B_{12} = \sin \frac{m\pi Y_q}{b} \cos \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b}$

$$X_{12} = 4c \left(-8 \right) \left(\frac{1}{\epsilon_{nm}^2} \right)$$

$$ELQ = Q^{-\frac{\epsilon_{nm}}{nm}} \left(Z_q - Z_1 \right), \sinh \frac{\epsilon_{nm} \Delta Z_1}{2}$$

For $Z_q = Z_1$ we proceed in the manner outlined in Art 5(b) of Ch.III.

Putting $j (1 - Q^{-\frac{\epsilon_{nm}}{nm}} \frac{\Delta Z_1}{2} \frac{Z_1}{2})$ instead of factor $Q^{-\frac{\epsilon_{nm}}{nm}} (Z_q - Z_1)$.

$\sinh \frac{\epsilon_{nm} \Delta Z_1}{2}$ in the Equation (21.4) and re-arranging terms,

we have,

$$Q_{12}^{12} = j \left[4c \left(-8 \right) \sum_{n=1}^{20} \cos \frac{n\pi X_q}{a} \sin \frac{m\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a} \right]$$

$$\sum_{m=1}^{20} \frac{1}{\epsilon_{nm}^2} \sin \frac{m\pi Y_q}{b} \cos \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b}]$$

$$-j \left[4c \left(-8 \right) \sum_{n=1}^{20} \cos \frac{n\pi X_q}{a} \sin \frac{m\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a} \sum_{m=1}^{20} \frac{-\epsilon_{nm} \Delta Z_1}{\epsilon_{nm}^2} \sin \frac{m\pi Y_q}{b} \right]$$

$$4c \left(-8 \right) \sum_{n=2}^{20} (A_{12N}) (F_{12LLN}) - j \left[\sum_{n=1}^{20} A_{12N} \sum_{m=1}^{20} B_{12LNM} \right]$$

whereas shown in Art 3(b) of Ch. III.

$$A_{12N} = \cos \frac{n\pi X_2}{a} \sin \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a}$$

$$F_{12LLN} = -FLL(1) + FLL(2) + FLL(3) - FLL(4)$$

$$\text{wherein } FLL(I) = \left[\left(\frac{b^2}{\pi^2} \right) \cdot \left(\frac{\pi}{2a_n} \right) \cdot \left(\frac{\cosh(\pi - T(I))}{\sinh(a_n T(I))} \right) \right] \\ = \frac{b^2}{2\pi^2 a_n^2} \quad \text{with } a_n = \frac{b}{\pi} \sqrt{\left(\frac{n\pi}{a} \right)^2 - k_o^2} \text{ and } I=1, 2, 3, 4 \\ A_{121} = A_{12N} \Big|_{n=1}$$

$$F_{12LL1} = -FLL1(1) + FLL1(2) + FLL1(3) - FLL1(4)$$

$$\text{wherein } FLL1(I) = \left[\frac{a^2}{2\pi^2} - \left(\frac{ab}{2\pi} \right) \cdot \frac{\cos \frac{b}{a} [\pi - T(I)]}{\sin \left(\frac{b}{a} \pi \right)} \right]$$

$$B_{12LNN} = (B_{12}) (X_{12}) (\text{ELL}) \text{ wherein ELL} = \frac{G_{nm} \Delta z_2}{G_{nm}} \frac{z_1}{2}$$

$$Q_{1q}^{21}$$

For $Z_q \neq Z_1$ we have from Equation (21.5)

$$Q_{1q}^{21} = \left[4C \left(-8 \right) \sum_{n=1}^{20} \sin \frac{n\pi X_q}{a} \cos \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a} \right]$$

$$\sum_{m=1}^{20} \frac{G_{nm} |Z_q - Z_1|}{G_{nm}^2} \cdot \sinh \frac{G_{nm} \Delta Z_1}{2} \cdot \times \cos \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b}$$

$$\cdot \sin \frac{m\pi \Delta Y_1}{2b} \Bigg] = \sum_{n=1}^{20} A_{21N} \sum_{m=1}^{20} B_{21QNM}$$

$$\text{where } A_{21N} = \sin \frac{n\pi X_q}{a} \cos \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a}$$

$$B_{21QNM} = (B_{21}) (X_{21}) (\text{ELQ})$$

$$\text{wherein } B_{21} = \cos \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b}$$

$$X_{21} = X_{12} = 4C (-8) \left(\frac{1}{G_{nm}^2} \right)$$

$$ELQ = Q^{-\frac{G_{nm}}{2}} \left| z_q - z_1 \right| \sinh \frac{G_{nm} \Delta z_1}{2}$$

For $z_q = z_1$ we proceed in the manner outlined in Art 3(b) of

Ch.III. Putting $j (1 - Q^{-\frac{G_{nm} \Delta z_1}{2}})$ instead of factor $e^{-\frac{G_{nm}}{2}}$

$Q^{-\frac{G_{nm}|z_q - z_1|}{2}} \sinh \frac{G_{nm} \Delta z_1}{2}$ in the Equation (21.5) and re-arranging

$$\text{terms, we have, } Q_{1q}^{21} = j \left[4C (-8) \sum_{m=1}^{20} \sin \frac{m\pi Y_q}{a} \cos \frac{m\pi Y_1}{a} \right]$$

$$\sin \frac{n\pi \Delta x_1}{2a} \sum_{m=1}^{20} \frac{1}{G_{nm}^2} \cos \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b}$$

$$-j \left[4C (-8) \sum_{n=1}^{20} \sin \frac{n\pi X_q}{a} \cos \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a} \sum_{m=1}^{20} \frac{-G_{nm} \Delta z_1}{G_{nm}^2} \right]$$

$$\cos \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b} \}$$

$$= \left\{ j \left[4C \left(-\frac{8}{4} \right) (A_{211}) (F_{21LLN}) + 4C \left(-\frac{8}{4} \right) \sum_{n=2}^{20} (A_{21N}) (F_{21LLN}) \right] \right\}$$

$$-j \left[\sum_{n=1}^{20} A_{21N} \sum_{m=1}^{20} B_{21LNM} \right] \}$$

$$\text{where } F_{21LLN} = FLL(1) + FLL(2) - FLL(3) - FLL(4)$$

$$\text{wherein } FLL(1) \text{ is already defined in the expression for } F12LLN ;$$

$$F12LLN \quad A_{211} = A_{21N} \Big|_{n=1} ;$$

$$F_{21LL4} = F_{LL1}(1) + F_{LL2}(2) - F_{LL3}(3) - F_{LL4}(4)$$

wherein $F_{LL1}(1)$ is already defined in the expression for F_{12LL4}

$$B_{21LNM} = (B_{21})(X_{21})(ELL) \text{ wherein } ELL = Q^{\frac{\sin \Delta Z_1}{\pi n^2}}.$$

In the following expressions for $Q_{1q}^{23}, Q_{1q}^{32}, Q_{1q}^{51}, Q_{1q}^{13}$, the

upper sign is for $Z_q < Z_1$ and the lower sign is for $Z_q > Z_1$

$$\underline{Q_{1q}^{23}}$$

For $Z_q \neq Z_1$ we have from Equation (21.6)

$$Q_{1q}^{23} = 4c \left(\pm \frac{8a}{\pi n} \right) \sum_{n=1}^{20} \frac{1}{n} \sin \frac{n\pi X_q}{a} \sin \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a}$$

$$\sum_{m=1}^{20} \frac{\sin \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b}}{G_{nm}} \sinh G_{nm} \frac{\Delta Z_1}{2} \pm \cos \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b}.$$

$$= 4c \left(\pm \frac{8a}{\pi n} \right) \sum_{n=1}^{20} A_{23N} \sum_{m=1}^{20} B_{23QNM}$$

$$\text{Where } A_{23N} = \frac{1}{n} \sin \frac{n\pi X_q}{a} \sin \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a}$$

$$B_{23QNM} = (p_{23})(x_{23})(ELQ)$$

$$\text{Wherein } B_{23} = B_{21} = \cos \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b}$$

$$x_{23} = 4c \left(\frac{8a}{\pi n} \right) \left(\frac{1}{G_{nm}} \right)$$

$$ELQ = Q^{\frac{\sin \Delta Z_1}{\pi n^2}} \sinh G_{nm} \frac{\Delta Z_1}{2}$$

$$\text{For } Z_q = Z_1, Q_{1q}^{32} = 0$$

For $Z_q \neq Z_1$ we have from Equation (21.7)

$$Q_{1q}^{32} = \left[4C \left(\frac{-8a}{\pi^2} \right) \sum_{n=1}^{20} \frac{1}{n} \sin \frac{n\pi X_q}{a} \sin \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta Y_1}{2a} \right. \\ \left. + \sum_{m=1}^{20} \frac{\epsilon_{nm} (Z_q - Z_1)}{\epsilon_{nm}} \cdot \sinh \epsilon_{nm} \frac{\Delta Z_1}{2} \cdot \sin \frac{m\pi Y_q}{b} \cos \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b} \right]$$

$$= (+) \sum_{n=1}^{20} A_{32N} \sum_{m=1}^{20} B_{32QNM}$$

$$\text{where } A_{32N} = \frac{1}{n} \sin \frac{n\pi X_q}{a} \sin \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta Y_1}{2a}$$

$$B_{32QNM} = (B_{32}) (X_{32}) (ELQ)$$

$$\text{wherein } B_{32} = \sin \frac{m\pi Y_q}{b} \cos \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b}$$

$$X_{32} = 4C \left(\frac{8a}{\pi^2} \right) \left(\frac{1}{\epsilon_{nm}} \right) = X_{23}$$

$$ELQ = \frac{\epsilon_{nm} (Z_q - Z_1)}{\epsilon_{nm}} \cdot \sinh \epsilon_{nm} \frac{\Delta Z_1}{2}$$

$$\text{For } Z_q = Z_1, Q_{1q}^{32} = 0$$

$$\underline{Q_{1q}^{31}}$$

For $Z_q \neq Z_1$ we have from Equation (21.8)

$$Q_{1q}^{31} = \left[4C \left(\frac{-8b}{\pi^2} \right) \sum_{m=1}^{20} \frac{1}{m} \sin \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b} \right]$$

$$\sum_{n=1}^{20} \frac{\epsilon_{nm} (Z_q - Z_1)}{\epsilon_{nm}} \cdot \sinh \epsilon_{nm} \frac{\Delta Z_1}{2} \cdot X \sin \frac{n\pi X_q}{a} \epsilon_{\phi_B} \frac{n\pi Y_1}{a} \sin \frac{n\pi \Delta Y_1}{2a}$$

$$= (+) \sum_{m=1}^{20} A_{31M} \sum_{n=1}^{20} B_{31QNM}$$

$$\text{where } A_{31M} = \frac{1}{m} \sin \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b}$$

$$B_{31QNM} = (B_{31}) (X_{31}) (\text{ELQ})$$

$$\text{wherein } B_{31} = \sin \frac{n\pi X_q}{a} \cos \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a}$$

$$X_{31} = 4C \left(\frac{8b}{\pi} \right) \left(\frac{1}{E_{nm}} \right)$$

$$\text{ELQ} = Q^{-E_{nm}} [z_q - z_1] \cdot \sinh E_{nm} \frac{\Delta z_1}{2}$$

$$\text{For } z_q = z_1, \quad Q_{1q}^{13} = 0$$

$$Q_{1q}^{13} = 0$$

For $z_q \neq z_1$ we have from Equation (21.9)

$$Q_{1q}^{13} = \left[4C \left(\pm \frac{8b}{\pi} \right) \sum_{m=1}^{20} \frac{1}{m} \sin \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b} \right]$$

$$\begin{aligned} & \sum_{n=1}^{20} Q^{-E_{nm}} [z_q - z_1] \cdot \sinh E_{nm} \frac{\Delta z_1}{2} \cdot \cos \frac{n\pi X_q}{a} \sin \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a} \\ & = \left(\pm \right) \sum_{m=1}^{20} A_{13M} \sum_{n=1}^{20} B_{13QNM} \end{aligned}$$

$$\text{where } A_{13M} = \left[\frac{1}{m} \sin \frac{m\pi Y_q}{b} \sin \frac{m\pi Y_1}{b} \sin \frac{m\pi \Delta Y_1}{2b} \right]$$

$$B_{13QNM} = (B_{13}) (X_{13}) (\text{ELQ})$$

$$\text{wherein } B_{13} = \left[\cos \frac{n\pi X_q}{a} \sin \frac{n\pi X_1}{a} \sin \frac{n\pi \Delta X_1}{2a} \right]$$

$$X_{13} = \left[4C \left(\frac{8b}{\pi} \right) \left(\frac{1}{E_{nm}} \right) \right] = X_{31}$$

$$\text{ELQ} = Q^{-E_{nm}} [z_q - z_1] \cdot \sinh E_{nm} \frac{\Delta z_1}{2}$$

$$\text{For } z_q = z_1, \quad Q_{1q}^{13} = 0$$

With Q_{1q}^{pk} elements expressions presented as above the relevant

computer program is as shown in Appendix V.

The digital Computer program consists of the main program, the sub-routine QPKLQ and the subroutine SOLVE. The main program, with the given data, utilizes the subroutine QPKLQ to find the matrix elements Q_{1q}^k and then it utilizes the subroutine SOLVE to find the J_1^k elements by Gauss-Jordan elimination method [14] and, with J_1^k elements determined, it itself computes Z_{11}, Z_{12}, Z_1 and Z_2 as normalized values.

For the illustrative problem with the given dielectric volume considered as a single cell the results obtained were as follows:-

$$Z_{11} = Z_{12} = 0.138711 - j0.326588$$

$$Z_{12} = Z_{21} = 0.176307 - j0.182039$$

$$Z_1 = Z_{11} - Z_{12} = -0.037596 - j0.134549$$

$$Z_2 = Z_{12} = 0.176307 - j0.182039$$

Subsequently the volume of the dielectric in the given illustrative problem was subdivided into three equal cells along X-direction and the results obtained thus were as follows:-

$$Z_{11} = Z_{22} = 0.130448 - j0.269111$$

$$Z_{12} = Z_{21} = 0.154171 - j0.158204$$

$$Z_1 = Z_{11} - Z_{12} = -0.023723 - j0.110907$$

$$Z_2 = Z_{12} = 0.154171 - j0.158204$$

The most outstanding feature of these results is that Z_1 parameter has a negative real part. A comment on this point has been presented in the concluding Chapter.

APPENDIX V: COMPUTER PROGRAM

Page -107-

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C MAIN PROGRAM
C NO. OF. CELL=1JKLMN
01      COMPLEXAA,BB,PIVOT,C10,A10,Z1,Z2,Z11,Z12,ZK,Q
02      1 = 510,DET
03      DIMENSION AA(36,36),BB(36,1),IPVUT(36),INDEX(36,2),PIVUT(36),Q(3
     1,3)
04      1 ,X(12),Y(12),Z(12)
05      COMMON DABSZIPVUT,INDOLX,PIVUT,AA,BB,MM,NN,DET,BQ/XQ,XL,DXL,
     1 YQ,YL,DYL,ZQ,ZL,DZL,SK1,L,IQ, A,B,C,SKD,Q
06      IJKLMN=1
07      D=0.000001
08      DD=0.000001
09      PI=3.141592654
10      READ(1,261)XL,YL,ZL,SK1
11      261 FORMAT(3F10.8,F10.4)
12      DU 262 IQ=1,IJKLMN
13      263 FORMAT(3F10.8)
14      262 READ(1,263)X(I),Y(I),Z(I)
15      DU 290 IQ=1,IJKLMN
16      DU 290 L=1,IJKLMN
17      XL=X(L)
18      YL=Y(L)
19      ZL=Z(L)
20      XQ=X(IQ)
21      YQ=Y(IQ)
22      ZQ=Z(IQ)
23      CALL QPKLQ
24      DO 202 I=1,3
25      DO 202 J=1,3
26      202 AA(((IQ-1)*3+I),((I-1)*3+J))=Q(I,J)
27      290 CONTINUE
28      NN=3*IJKLMN
29      MM=1
30      DET=CMPLX(0.,0.)
31      DO 270 I=1,NN
32      DO 270 J=1,NN
33      CCCC=CAB(S(AA(I,J))
34      E=(CCCC*LL-DD)AA(I,J)=CMPLX(0.,0.)
35      270 CONTINUE
36      DO 285 IQ=1,IJKLMN
37      BB(((IQ-1)*3+1),1)=CMPLX(0.,0.)
38      E=SIN((PI/2.54)*X(IQ))
39      THETA=(PI/2.54)*Z(IQ)
40      BB(((IQ-1)*3+2),1)=CMPLX(4.6*COS(THETA)),(-E*SIN(THETA)))
41      DU (((IQ-1)*3+3),1)=CMPLX(0.,0.)
42      285 CONTINUE
43      WRITE(3,206)
44      206 FORMAT(10X,*MATRIX BB*)
45      DU 280 I=1,NN
46      207 FORMAT(2F10.6)
47      280 WRITE(3,207)(BB(I,1))
48      CALL SOLVE
49      WRITE(3,208)
50      208 FORMAT(10X,*SOLUTION XKL*)

```

```
49      DO 240 I=1,NN -108-
50 209 FORMAT(2E10.6)
51 240 WRITE(3,209)(UB(I,1))
52      C10=CMPLX(0.,0.)
53      DO 265 L=1,IJKLMN
54      CC=(-16.)*(DYL/P1)*(DZL/P1)*SIN((P1/2.54)*X(L))*SIN((P1/2.54)*DXL)
55      S10=CMPLX(0.,CC)+BB((L-1)*3+2),1)
56 265 C10=C10+S10
57      A10=CMPLX(1.,0.)
58      ZK=(A10+C10)/(A10-C10)
59      Z11=(CMPLX(1.,0.)+ZK)*(ZK/(CMPLX(2.,0.)+ZK))
60      Z12=ZK/(CMPLX(2.,0.)+ZK)
61      Z1=Z11-Z12
62      Z2=Z12
63      WRITE(3,211)
64 211 FORMAT(10X,Z11,Z12,Z1,Z2,SERIALLY*)
65      WRITE(3,212) Z11,Z12,Z1,Z2
66 212 FORMAT(4(4X,2F10.6))
67 280 CONTINUE
```

-109-

```
01 SUBROUTINE GPKLQ
02 COMPLEX Q ,V
03 DIMENSION Q(3,3),V(3,3),
04      T(8),F11(4),G11(4),F22(4),G22(4),F33(4),FLL(4),
05      1F1(4),S11LL5(20),S11LQ3(20),S22LL5(20),S22LQ3(20),F331(4),
06      2S33LL4(20),S33LQ2(20),FLL1(4),S12LL4(20),S12LQ2(20),S21LL4(20),
07      3S21LQ2(20),S23LQ2(20),S32LQ2(20),S31LQ2(20),S13LQ2(20)
08      COMMON D/BQ/XQ,XL,DXL,YQ,YL,DYL,ZQ,ZL,DZL,SK1,L,IQ ,A,B,C,SKD,Q
09      A=2.54
10      B=1.27
11      PI=3.141592654
12      SKU=(2.*PI*PI)/(A*A)
13      C=1/(2.*PI*PI)
14      T(1)=(PI/B)*(YQ+YL-DYL)
15      T(2)=(PI/B)*(YQ-YL+DYL)
16      T(3)=(PI/B)*(YQ+YL+DYL)
17      T(4)=(PI/B)*(YQ-YL-DYL)
18      T(5)=(PI/A)*(XQ+XL-DXL)
19      T(6)=(PI/A)*(XQ-XL+DXL)
20      T(7)=(PI/A)*(XQ+XL+DXL)
21      T(8)=(PI/A)*(XQ-XL-DXL)
22      DO 10 I=1,8
23      IF(T(I)-0.0)3,10,4
24      3 T(I)=T(I)+2.*PI
25      GO TO 6
26      4 IF(T(I)-2*PI)10,10,5
27      5 T(I)=T(I)-2*PI
28      GO TO 4
29      10 CONTINUE
30      AU=(B/PI)*SQRT(SKU)
31      BU=(A/PI)*SQRT(SKD)
32      NNN=3
33      MMM=3
34      NNN1=NNN+1
35      MMM1=MMM+1
36      NN=NNN
37      MM=MMM
38      IF(ZQ-ZL)12,11,12
39      11 S11LL2=0
40      DO 9 I=1,4
41      9 G11(1)=(PI/2.)*(SIN(AU*(PI-T(I)))/SIN(AU*PI))-(PI-T(I))*(0.5),
42      G11LL=G11(1)+G11(2)+G11(3)+G11(4)
43      DO 60 I=1,4
44      60 F1(1)=(PI-T(I))*(0.5)-(PI/2.)*(SIN((B/A)*(PI-T(I)))/SIN(B*PI/A))
45      F11LL1=F1(1)+F1(2)+F1(3)+F1(4)
46      A111=COS((PI*XQ)/A)*COS((PI*XL)/A)*SIN((PI*DXL)/A)
47      S11LL1=((2.*C*8.*B*DXL)/(4.*PI))*G11LL-4.*C*6.*A*B*A111*F11LL1*(1.
48      1/(4.*PI*PI))
49      DO 13 N=2,NN
50      AN=N
51      AAN=(B/PI)*SQRT((AN*PI)/A)*2-SKU
52      DO 8 I=1,4
53      8 F11(1)=(PI-T(I))*(0.5)-(PI/2.)*(SINH(AAN*(PI-T(I)))/SINH(AAN*PI))
54      F11LLN=F11(1)+F11(2)+F11(3)+F11(4)
```

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50 13 S11LL2=S11LL2+((4.*C*(A*B)/(4.*PI*PI))*A11N*F11LLN
51 S11LL3=0
52 DO 14 M=1,MM
53 BM=M
54 B11=SIN(BM*PI*YQ/B)*SIN(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
55 GM=SQRT((BM*PI/B)**2-SKU)
56 X1=2.*C*(2.*B*DXL)*SKU*(1.//(PI*BM*GM*GM))
57 E1LL=EXP(-GM*DZL)
58 B1LLM=B11*X1*E1LL
59 14 S11LL3=S11LL3+B1LLM
60 S11LL4=0
61 DO 16 N=1,NN
62 S11LL5(N)=0
63 AN=N
64 A11N=(1./AN)*COS(AN*PI*XQ/A)*COS(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
65 DO 15 M=1,MM
66 BM=M
67 B11=SIN(BM*PI*YQ/B)*SIN(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
68 GM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SKU)
69 X1=(4./BM)*C*(8.*A*B)*(SKU-(AN*PI/A)**2)*(1.//((PI*GNM)**2))
70 ELL=EXP(-GM*DZL)
71 B11LN=M=B11*X1*ELL
72 15 S11LL5(N)=S11LL5(N)+A11N*B11LN
73 16 S11LL4=S11LL4+S11LL5(N)
74 XQ11LL=0
75 YQ11LL=S11LL1-S11LL2-S11LL3-S11LL4
76 21 B2=(SIN((PI/A)**XQ)*SIN((PI/A)*XL)*SIN((PI/A)*DXL))*(2*C*8.*A*DYL*
77 1SKU)*(1./PI)*((-PI*PI)/(A*A)))
78 XB2LL1=B2*COS((PI/A)*DZL)
79 YB2LL1=B2*(-1)*SIN((PI/A)*DZL)
80 XB2LQ1=B2*COS((PI/A)+ABS(ZQ-ZL))*SIN((PI/A)*DZL)
81 YB2LQ1=B2*(-1)*SIN((PI/A)+ABS(ZQ-ZL))*SIN((PI/A)*DZL)
82 DO 30 T=5.8
83 30 G22(1)=(P1/2.)*(SIN(80*(P1-T(1)))/SIN(80*PI)-(P1-T(1))*(0.5)
84 G22LL=G22(5)+G22(6)-G22(7)-G22(8)
85 S22LL1=((2.*C*8.*A*DYL)/(4.*PI))*G22LL-XB2LL1
86 S22LL2=0
87 DO 23 M=1,MM
88 BM=M
89 BBM=(A/PI)*SQRT((BM*PI/B)**2-SKU)
90 DO 20 I=5,8
91 20 F22(I)=(PI-T(I))*(0.5)-(P1/2.)*(SINH(BBM*(PI-T(I)))/SINH(BBM*PI))
92 F22LLM=F22(5)+F22(6)-F22(7)-F22(8)
93 A22M=(1./LM)*COS(BM*PI*YQ/B)*COS(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
94 23 S22LL2=S22LL2+((4.*C*8.*A*B)/(4.*PI*PI))*A22M*F22LLM
95 S22LL3=0
96 DO 24 N=2,NN
97 AN=N
98 GN=SQRT((AN*PI/A)**2-SKU)
99 B22=SIN(AN*PI*XQ/A)*SIN(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
100 X2=2.*C*(8.*A*DYL)*SKU*(1.//(PI*AN*GN*GN))
101 E2LL=EXP(-GN*DZL)
102 B2LLN=B22*X2*E2LL
103 24 S22LL3=S22LL3+B2LLN
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3 S22LL4=0
4 DO 26 M=1,MM
5 BM=M
6 S22LL5(M)=0
7 A22M=(1./BM)*COS(BM*PI*YG/B)*COS(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
8 DO 25 N=1,NN
9 AN=N
0 GNM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SK0)
1 B22=SIN(AN*PI*XG/A)*SIN(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
2 X22=(4./AN)*C*(8.*A*B)*(SK0-(BM*PI/B)**2)*(1./(PI*GNM)**2))
3 ELL=EXP(-GNM*DZL)
4 B22LN=M22*X22*LLL
5 S22LL5(M)=S22LL5(M)+A22N*B22LN
6 S22LL4=S22LL4+S22LL5(M)
7 XQ22LL=YB2LL1
8 YQ22LL=S22LL1-S22LL2-S22LL3-S22LL4
9 A331=SIN((PI*XQ)/A)*SIN((PI*XL)/A)*SIN((PI*DXL)/A)
0 DO 70 I=1,4
1 F331(I)=(PI-T(I))*(0.5)-(AO*AO)*(-(A*A)/(B*B))*(PI-T(I))*(0.5)
2 + (AO*AO)*(-(A*A)/(B*B))*(PI/2.)*SIN((B/A)*(PI-T(I)))*(1./SIN((2*B*PI)/A))
3 F33LL1=F331(1)+F331(2)-F331(3)-F331(4)
4 S33LL1=4.*C*(8.*A*B)*(1./(4.*PI*PI))*A331*F33LL1
5 S33LL2=0
6 DO 33 N=2,NN
7 AN=N
8 AAN=(B/PI)*SQRT((AN*PI/A)**2-SK0)
9 GNM=SQRT((AN*PI/A)**2-SK0)
0 DO 40 I=1,4
1 F33(I)=(PI-T(I))*(0.5)-((AO**2)/(AAN**2))*(PI-T(I))*(0.5)+((AO**2)
2 1/AAN**2)*(PI/2.)*(SINH(AAN*(PI-T(I)))/SINH(AAN*PI))
3 F33LN=F33(1)+F33(2)-F33(3)-F33(4)
4 B22=SIN(AN*PI*XQ/A)*SIN(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
5 A33N=(1./AN)*B22
6 S33LL2=S33LL2+4.*C*((8.*A*B)/(4.*PI*PI))*A33N*F33LN
7 S33LL3=0
8 DO 35 N=1,NN
9 S33LL4(N)=0
0 AN=N
1 B22=SIN(AN*PI*XQ/A)*SIN(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
2 A33N=(1./AN)*B22
3 DO 34 M=1,MM
4 BM=M
5 B11=SIN(BM*PI*YG/B)*SIN(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
6 B33=B11
7 GNM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SK0)
8 X33=(4./BM)*C*(8.*A*B)*((AN*PI/A)**2+(BM*PI/B)**2)*(1./(PI*GNM)
9 1**2))
0 ELL=EXP(-GNM*DZL)
1 B33LN=M33*X33*ELL
2 S33LL4(N)=S33LL4(N)+A33N*B33LN
3 S33LL3=S33LL3+S33LL4(N)
4 XQ33LL=0
5 YQ33LL=S33LL1+S33LL2-S33LL3

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41 A121=COS((P1*XQ)/A)*SIN((P1*XL)/A)*SIN((P1*DXL)/A)
DO 80 I=1,4
80 FLL1(1)=((A*A)/(2.*PI*P1))-((A*B)/(2.*P1))*COS((B/A)*(P1-T(1)))*
1*(1./SIN((B*P1)/A))
F12LL1=-FLL1(1)+FLL1(2)+FLL1(3)-FLL1(4)
S12LL1=4.*C*(-B.)*(1./4.)*A121*F12LL1
S12LL2=0
DO 43 N=2,NN
AN=N
AAN=(B/P1)*SQR((AN*P1/A)**2-SKU)
DO 50 I=1,4
50 FLL1(1)=((B*B)/(P1*P1))*(P1/(2.*AAN*SINH(AAN*P1)))*COSH(P1-T(1))
1-((B/(P1*AAN))*2)*0.5
F12LLN=-FLL1(1)+FLL1(2)+FLL1(3)-FLL1(4)
A12N=COS(AN*P1*XQ/A)*SIN(AN*P1*XL/A)*SIN(AN*P1*DXL/A)
43 S12LL2=S12LL2+4.*C*(-B.)*(1./4.)*A12N*F12LLN
S12LL3=0
DO 45 N=1,NN
S12LL4(N)=0
AN=N
A12N=COS(AN*P1*XQ/A)*SIN(AN*P1*XL/A)*SIN(AN*P1*DXL/A)
DO 44 M=1,MM
BM=M
GNM=SQR((AN*P1/A)**2+(BM*P1/B)**2-SKU)
B12=SIN(3M*P1*YC/B)*COS(BM*P1*YL/B)*SIN(BM*P1*DYL/B)
X12=4.*C*(-B.)*(1./GAM**2)
ELL=EXP(-GNM*DZL)
B12NM=B12*X12*ELL
44 S12LL4(N)=S12LL4(N)+A12N*B12NM
45 S12LL3=S12LL3+S12LL4(N)
XQ12LL=0
YQ12LL=S12LL1+S12LL2+S12LL3
51 A211=SIN((P1*XQ)/A)*COS((P1*XL)/A)*SIN((P1*DXL)/A)
DO 380 I=1,4
380 FLL1(1)=((A*A)/(2.*PI*P1))-((A*B)/(2.*P1))*COS((B/A)*(P1-T(1)))*
1*(1./SIN((B*P1)/A))
F21LL1=FLL1(1)+FLL1(2)+FLL1(3)-FLL1(4)
S21LL1=4.*C*(-B.)*(1./4.)*A211*F21LL1
S21LL2=0
DO 53 N=2,NN
AN=N
AAN=(B/P1)*SQR((AN*P1/A)**2-SKU)
A21N=SIN(AN*P1*XQ/A)*COS(AN*P1*XL/A)*SIN(AN*P1*DXL/A)
DO 350 I=1,4
350 FLL1(1)=((B*B)/(P1*P1))*(P1/(2.*AAN*SINH(AAN*P1)))*COSH(P1-T(1))
1-((B/(P1*AAN))*2)*0.5
F21LLN=FLL1(1)+FLL1(2)+FLL1(3)-FLL1(4)
53 S21LL2=S21LL2+4.*C*(-B.)*(1./4.)*A21N*F21LLN
S21LL3=0
DO 55 N=1,NN
S21LL4(N)=0
AN=N
A21N=SIN(AN*P1*XQ/A)*COS(AN*P1*XL/A)*SIN(AN*P1*DXL/A)
DO 54 M=1,MM
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3 BM=M
4 GNM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SKD)
5 B21=COS(BM*PI*YQ/B)*SIN(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
6 X12=4.*C*(-8.)*(1./(GNM**2))
7 X21=X12
8 ELL=EXP(-GNM*DZL)
9 B21LN=M=B21*X21*ELL
10 S21LL4(N)=S21LL4(N)+A21N*B21LN
11 S21LL3=S21LL3+S21LL4(N)
12 XQ21LL=0
13 YQ21LL=S21LL1+S21LL2-S21LL3
14 XQ23LL=0
15 YQ23LL=0
16 XQ32LL=0
17 YQ32LL=0
18 XQ31LL=0
19 YQ31LL=0
20 XQ13LL=0
21 YQ13LL=0
22 IF(L-IQ)90,89,90
23 Q(1,1)=CMPLX((XQ11LL-1./(SKI-SKO)),YQ11LL)
24 Q(1,2)=CMPLX(XQ12LL,YQ12LL)
25 Q(1,3)=CMPLX(XQ13LL,YQ13LL)
26 Q(2,1)=CMPLX(XQ21LL,YQ21LL)
27 Q(2,2)=CMPLX((XQ22LL-1./(SKI-SKO)),YQ22LL)
28 Q(2,3)=CMPLX(XQ23LL,YQ23LL)
29 Q(3,1)=CMPLX(XQ31LL,YQ31LL)
30 Q(3,2)=CMPLX(XQ32LL,YQ32LL)
31 Q(3,3)=CMPLX((XQ33LL-1./(SKI-SKO)-1./SKO),YQ33LL)
32 GO TO 100
33 Q(1,1)=CMPLX(XQ11LL,YQ11LL)
34 Q(1,2)=CMPLX(XQ12LL,YQ12LL)
35 Q(1,3)=CMPLX(XQ13LL,YQ13LL)
36 Q(2,1)=CMPLX(XQ21LL,YQ21LL)
37 Q(2,2)=CMPLX(XQ22LL,YQ22LL)
38 Q(2,3)=CMPLX(XQ23LL,YQ23LL)
39 Q(3,1)=CMPLX(XQ31LL,YQ31LL)
40 Q(3,2)=CMPLX(XQ32LL,YQ32LL)
41 Q(3,3)=CMPLX(XQ33LL,YQ33LL)
42 GO TO 100
43 S11LQ1=0
44 DO 17 M=1,MM
45 BM=M
46 B11=SIN(BM*PI*YQ/B)*SIN(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
47 GM=SQRT((BM*PI/B)**2-SKD)
48 X1=2.*C*(2.*B*DYL)*SKD*(1./(PI*BM*GM*GM))
49 E1LQ=EXP(-GM*ABS(ZQ-ZL))*SINH(GM*DZL)
50 B1LQM=B11*X1*E1LQ
51 S11LQ1=S11LQ1+B1LQM
52 S11LQ2=0
53 DO 19 N=1,NN
54 AN=N
55 A11N=(1./AN)*COS(AN*PI*XQ/A)*COS(AN*PI*XL/A)*SIN(AN*PI*DYL/A)
56 S11LQ3(N)=0
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DO 18 M=1,MM
BM=M
B11=SIN(BM*PI*YQ/B)*SIN(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
GNM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SK0)
X11=(4./BM)*C*(B.*A*B)*(SK0-(AN*PI/A)**2)*(1./*((PI*GNM)**2))
ELQ=EXP(-GNM*ABS(ZQ-ZL))*SINH(GNM*DZL)
B11QNM=B11*X11*ELQ
18 S11LQ3(N)=S11LQ3(N)+A11N*B11QNM
19 S11LQ2=S11LQ2+S11LQ3(N)
XQ11LQ=S11LQ1+S11LQ2
YQ11LQ=0
22 S22LQ1=0
DO 27 N=2,NN
C
70 AN=N
71 GN=SQRT((AN*PI/A)**2-SK0)
72 B22=SIN(AN*PI*XQ/A)*SIN(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
73 X2=2.*C*(B.*A*DYL)*SK0*(1./*(PI*AN*GN*GN))
74 E2LQ=EXP(-GN*ABS(ZQ-ZL))*SINH(GN*DZL)
75 B2LQN=B22*X2*E2LQ
76 27 S22LQ1=S22LQ1+B2LQN
77 S22LQ2=0
78 DO 29 M=1,MM
79 S22LQ3(M)=0
80 BM=M
81 A22M=(1./BM)*COS(BM*PI*YQ/B)*COS(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
DO 28 N=1,NN
AN=N
GNM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SK0)
B22=SIN(AN*PI*XQ/A)*SIN(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
X22=(4./AN)*C*(B.*A*B)*(SK0-(BM*PI/B)**2)*(1./*((PI*GNM)**2))
EL0=EXP(-GNM*ABS(ZQ-ZL))*SINH(GNM*DZL)
B22QNM=B22*X22*EL0
28 S22LQ3(M)=S22LQ3(M)+A22M*B22QNM
29 S22LQ2=S22LQ2+S22LQ3(M)
XQ22LQ=YB2LQ1
YQ22LQ=S22LQ1+S22LQ2
32 S33LQ1=0
DO 37 N=1,NN
AN=N
B22=SIN(AN*PI*XQ/A)*SIN(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
A33N=(1./AN)*B22
S33LQ2(N)=0
DO 36 M=1,MM
BM=M
B11=SIN(BM*PI*YQ/B)*SIN(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
B33=B11
GNM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SK0)
X33=(4./BM)*C*(B.*A*B)*(AN*PI/A)**2+(BM*PI/B)**2)*(1./*((PI*GNM)**2))
ELQ=EXP(-GNM*ABS(ZQ-ZL))*SINH(GNM*DZL)
B33QNM=J33*X33*ELQ
36 S33LQ2(N)=S33LQ2(N)+433N*B33QNM
37 S33LQ1=S33LQ1+S33LQ2(N)
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309 XQ33LQ=S33LQ1
310 YQ33LQ=0
311 42 S12L01=0
312 DO 47 N=1,NN
313 S12LQ2(N)=0
314 AN=N
315 A12N=COS(AN*PI*XQ/A)*SIN(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
316 DO 46 M=1,MM
317 BM=M
318 GNM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SKU)
319 B12=SIN(BM*PI*YQ/B)*COS(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
320 X12=4.*C*(-8.)*(1.//(GNM**2))
321 ELQ=EXP(-GNM*ABS(ZQ-ZL))*SINH(GNM*DZL)
322 B12QNM=B12*X12*ELQ
323 46 S12LQ2(N)=S12LQ1+A12N*B12QNM
324 47 S12LQ1=S12LQ1+S12LQ2(N)
325 XQ12LQ=S12LQ1
326 YQ12LQ=0
327 52 S21LQ1=0
328 DO 57 N=1,NN
329 S21LQ2(N)=0
330 AN=N
331 A21N=SIN(AN*PI*XQ/A)*COS(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
332 DO 56 M=1,MM
333 BM=M
334 GNM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SKU)
335 B21=COS(BM*PI*YQ/B)*SIN(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
336 X12=4.*C*(-8.)*(1.//(GNM**2))
337 X21=X12
338 ELQ=EXP(-GNM*ABS(ZQ-ZL))*SINH(GNM*DZL)
339 B21QNM=B21*X21*ELQ
40 56 S21LQ2(N)=S21LQ1+A21N*B21QNM
41 57 S21LQ1=S21LQ1+S21LQ2(N)
42 XQ21LQ=S21LQ1
43 YQ21LQ=0
44 62 S23LQ1=0.
45 DO 64 N=1,NN
46 S23LQ2(N)=0
47 AN=N
48 B22=SIN(AN*PI*XQ/A)*SIN(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
49 A23N=(1./AN)*B22
50 A23N=A23N
51 DO 63 M=1,MM
52 BM=M
53 GNM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SKU)
54 B21=COS(BM*PI*YQ/B)*SIN(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
55 B23=B21
56 X23=4.*C*(B.*A)*(1.//(PI*GNM))
57 ELQ=EXP(-GNM*ABS(ZQ-ZL))*SINH(GNM*DZL)
58 B23QNM=B23*X23*ELQ
59 63 S23LQ2(N)=S23LQ1+A23N*B23QNM
60 64 S23LQ1=S23LQ1+S23LQ2(N)
61 IF(ZQ-ZL)65,72,66
62 65 XQ23LQ=S23LQ1

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YQ23LQ=0
GO TO 72
66 XQ23LQ=-S23LQ1
YQ23LQ=0
72 S32LQ1=0
DO 74 N=1,NN
S32LQ2(N)=0
AN=N
B22=SIN(AN*PI*XQ/A)*SIN(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
A33N=(1./AN)*B22
A32N=A33N
DO 73 M=1,MM
BM=M
GNM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SKU)
B12=SIN(BM*PI*YQ/B)*COS(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
B32=B12
X23=4.*C*(8.*A)*(1./(PI*GNM))
X32=-X23
ELQ=EXP(-GNM*ABS(ZQ-ZL))*SINH(GNM*DZL)
B32QNM=B32*X32*ELQ
73 S32LQ2(N)=S32LQ2(N)+A32N*B32QNM
74 S32LQ1=S32LQ1+S32LQ2(N)
IF(ZQ-ZL>75,82,76
75 XQ32LQ=S32LQ1
YQ32LQ=0
GO TO 82
76 XQ32LQ=-S32LQ1
YQ32LQ=0
82 S31LQ1=0
DO 84 M=1,MM
S31LQ2(M)=0
BM=M
B11=SIN(BM*PI*YQ/B)*SIN(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
A31M=(1./BM)*B11
DO 83 N=1,NN
AN=N
GNM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SKD)
B31=SIN(AN*PI*XQ/A)*COS(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
X31=4.*C*(-8.*B)*(1./(PI*GNM))
ELQ=EXP(-GNM*ABS(ZQ-ZL))*SINH(GNM*DZL)
B31QNM=B31*X31*ELQ
83 S31LQ2(M)=S31LQ2(M)+A31M*B31QNM
84 S31LQ1=S31LQ1+S31LQ2(M)
IF(ZQ-ZL>85,92,86
85 XQ31LQ=S31LQ1
YQ31LQ=0
GO TO 92
86 XQ31LQ=-S31LQ1
YQ31LQ=0
92 S13LQ1=0
DO 94 M=1,MM
S13LQ2(M)=0
BM=M
B11=SIN(BM*PI*YQ/B)*SIN(BM*PI*YL/B)*SIN(BM*PI*DYL/B)
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-117-

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A31M=(1./BM)*B11
A13M=A31M
DO 93 N=1,NN
AN=N
GNM=SQRT((AN*PI/A)**2+(BM*PI/B)**2-SK0)
B13=COS(AN*PI*XQ/A)*SIN(AN*PI*XL/A)*SIN(AN*PI*DXL/A)
X31=4.*C*(-8.*B)*(1./(PI*GNM))
X13=-X31
B13QNM=B13*X13*ELQ
93 S13LQ2(M)=S13LQ2(M)+A13M*B13QNM
94 S13LQ1=S13LQ1+S13LQ2(M)
IF(ZQ-ZL)95,98,96
95 XQ13LQ=S13LQ1
YQ13LQ=0
GO TO 98
96 XQ13LQ=-S13LQ1
YQ13LQ=0
98 Q(1,1)=CMPLX(XQ11LQ,YQ11LQ)
Q(1,2)=CMPLX(XQ12LQ,YQ12LQ)
Q(1,3)=CMPLX(XQ13LQ,YQ13LQ)
Q(2,1)=CMPLX(XQ21LQ,YQ21LQ)
Q(2,2)=CMPLX(XQ22LQ,YQ22LQ)
Q(2,3)=CMPLX(XQ23LQ,YQ23LQ)
Q(3,1)=CMPLX(XQ31LQ,YQ31LQ)
Q(3,2)=CMPLX(XQ32LQ,YQ32LQ)
Q(3,3)=CMPLX(XQ33LQ,YQ33LQ)
100 IF((NN.EQ.NNN1).AND.(MM.EQ.MMM1))GO TO 312
315 DO 316 I=1,3
DO 316 J=1,3
316 V(I,J)=Q(I,J)
WRITE(3,311)NN,MM,IQ,L
311 FORMAT(1X,12.5X,12,10X,12.5X,12)
DO 317 I=1,3
321 FORMAT(3(4X,2E19.8))
317 WRITE(3,321)(V(I,J),J=1,3)
NN=NNN1
MM=MMM1
GO TO 11
312 *RITE(3,313)NN,MM,IQ,L
313 FORMAT(1X,12.5X,12,10X,12.5X,12)
DO 320 I=1,3
305 FORMAT(3(4X,2E19.8))
320 *RITE(3,305)(Q(I,J),J=1,3)
KKK=0
DO 323 I=1,3
DO 323 J=1,3
CCC=CAbs(Q(I,J)-V(I,J))
IF(CCC.LE.D)KKK=KKK+1
323 CONTINUE
IF(KKK.EQ.9)GO TO 3200
IF((NN.GT.20).OR.(MM.GT.20))GO TO 3200
NNN=NNN+1
MM=MMM+1
GO TO 314

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-118-

3200 RETURN
END

- 119 -

SUBROUTINE SOLVE
COMPLEX AA,BB,PIVOT,TT,DET
DIMENSION AA(36,36),BB(36,1),PIVOT(36),INDEX(36,2),PIVOT(36)
COMMON D/BS/PIVOT, INDEX, PIVOT,AA,BB,MM,NN,DET
EQUIVALENCE (IRW,JRW),(ICOL,JCOL)

C
157 DET=CMPLX(1.,0.)
DO 117 J=1,NN

117 PIVOT(J)=0
DO 135 I=1,NN

C
TT=CMPLX(0.,0.)
DO 108 J=1,NN

IF(PIVOT(J).EQ.1)GO TO 108
113 DO 123 K=1,NN

IF(PIVOT(K)-1)145,123,181

143 IF(CABS(TT).GE.CABS(AA(J,K))) GO TO 123

183 IRW=J

ICOL=K

TT=AA(J,K)

123 CONTINUE

108 CONTINUE

PIVOT(ICOL)=PIVOT(ICOL)+1

C
IF(IRW.EQ.ICOL)GO TO 109
173 DET=DET

DO 112 LL=1,NN

TT=AA(IRW,LL)

AA(ICOL,LL)=AA(ICOL,LL)+

112 AA(ICOL,LL)=TT

IF (MM.LE.0)GO TO 109

133 DO 102 LL=1,MM

TT=BB(IRW,LL)

BB(IRW,LL)=BB(ICOL,LL)

102 BB(ICOL,LL)=TT

109 INDEX(1,1)=IRW

INDEX(1,2)=ICOL

PIVOT(1)=AA(ICOL,ICOL)

DET=DET*PIVOT(1)

C
AA(ICOL,ICOL)=CMPLX(1.,0.)
DO 105 LL=1,NN

105 AA(ICOL,LL)=AA(ICOL,LL)/PIVOT(1)

IF(MM.LE.0)GO TO 147

166 DO 152 LL=1,MM

152 BB(ICOL,LL)=BB(ICOL,LL)/PIVOT(1)

C
147 DO 135 LI=1,NN

IF(LI.EQ.ICOL)GO TO 135

121 TT=AA(LI,ICOL)

AA(LI,ICOL)=CMPLX(0.,0.)

DO 184 LL=1,NN

189 AA(LI,LL)=AA(LI,LL)-AA(ICOL,LL)*TT

IF(MM.LE.0)GO TO 135

0050 118 DO 168 LL=1,NN
0051 168 BB(L1,LL)=BB(L1,LL)-BB(JCOL,LL)*TT
0052 135 CONTINUE
C
0053 122 DO 103 I=1,NN
0054 LL=NN+I+1
0055 IF(INDEX(LL,1).EQ.INDEX(LL,2))GO TO 108
0056 119 JRW=INOCX(LL,1)
0057 JCOL=INDEX(LL,2)
0058 DO 149 K=1,NN
0059 TT=AA(K,JRW)
0060 AA(K,JRW)=AA(K,JCOL)
0061 AA(K,JCOL)=TT
0062 149 CONTINUE
0063 103 CONTINUE
0064 181 RETURN
0065 END

Chapter-V

A Suggested Modified Moment Method

Of the different types of moment methods introduced in Art-1. of Ch.III the evaluation of l_{mn} matrix elements become laborious even on a high speed computer since at least two integrations may have to be performed numerically incase if the operator L is an integral operator. In the point-matching method the use of dirac delta functions as testing functions at discrete points reduces the laborious process of integration in finding l_{mn} matrix elements. However the accuracy of the solution depends not only on the number of points of the physical problem at which solution values are desired but also on their location. In the entire domain basis method use of a basis spanning the whole domain may result in rapid convergence, but the derivation of the l_{mn} elements is usually not efficient in terms of computer time. On the other hand in the sub-sectional/basis method the use of subspace basis functions usually afford efficient derivation of the l_{mn} elements but the number of matrix elements becomes large for representing the whole problem especially when the whole problem involves a considerably odd-shaped curved boundary requiring many cell segments to approximate the problem geometry. One might conclude, then, that it

Contd....

would be desirable to have an alternative approach that would have the advantages of both the entire domain and sub-domain approaches. One such method applied to a wire antenna has been discussed by R. Mittra et al [16]. This approach may be applied to the three-dimensional dielectric obstacle problem Equation (4) in Art 2 of Ch.III written below in matrix form:

$$-j\omega u_0 \begin{bmatrix} Q_{1y}^{1-k} \\ Q_{2y}^{1-k} \end{bmatrix} \begin{bmatrix} J_1^k \\ J_2^k \end{bmatrix} = - \begin{bmatrix} C_y^p \\ C_y^p \end{bmatrix} \quad (1*)$$

we consider firstly the one-dimensional Case and then extend it to three-dimensional case.

From Art-1 of Ch.III we rewrite Equation (5)

$$[l_{mn}] [\lambda_n] = [g_m] \quad \dots \quad (1) \quad \text{wherein}$$

$$[l_{mn}] = \begin{bmatrix} l_{11} & l_{12} & \dots \\ l_{21} & l_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}, \quad [\lambda_n] = \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \end{bmatrix}, \quad [g_m] = \begin{bmatrix} g_1 \\ g_2 \\ \vdots \end{bmatrix}$$

Now Column vector $[\lambda_n] = \lambda_1 \begin{bmatrix} 1 \\ 0 \\ 0 \\ \vdots \end{bmatrix} + \lambda_2 \begin{bmatrix} 0 \\ 1 \\ 0 \\ \vdots \end{bmatrix} + \dots$

$$= \begin{bmatrix} 1 & 0 & 0 & \dots \\ 0 & 1 & 0 & \dots \\ 0 & 0 & 1 & \dots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \end{bmatrix} = \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \end{bmatrix} \quad (1a)$$

Thus the basis vectors are subsectional pulse functions,

$$[\{_1\}] = \begin{bmatrix} 1 \\ 0 \\ 0 \\ \vdots \end{bmatrix}, \quad [\{_2\}] = \begin{bmatrix} 0 \\ 1 \\ 0 \\ \vdots \end{bmatrix}, \quad \dots$$

If we change to a new set of basis vector which are nonsubsectional sinusoidal function vectors

$$[\{'_1\}] = \begin{bmatrix} \cos \frac{\pi l_1}{L} \\ \cos \frac{\pi l_2}{L} \\ \vdots \end{bmatrix}, \quad [\{'_2\}] = \begin{bmatrix} \cos \frac{2\pi l_1}{L} \\ \cos \frac{2\pi l_2}{L} \\ \vdots \end{bmatrix} \quad \text{where } l_1 = 1, l_2 = 2, \dots, l_L = L.$$

$$\text{then } [\lambda_n] = \lambda'_1 [\{'_1\}] + \lambda'_2 [\{'_2\}] + \dots = [T_{mn}] [\lambda'_m] \quad (2)$$

$$\text{where } [T_{mn}] = \begin{bmatrix} \cos \frac{\pi l_1}{L} & \cos \frac{2\pi l_1}{L} & \dots \\ \cos \frac{\pi l_2}{L} & \cos \frac{2\pi l_2}{L} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \quad (2a) \quad \text{and } [\lambda'_m] = \begin{bmatrix} \lambda'_1 \\ \lambda'_2 \\ \vdots \end{bmatrix} \quad (2b)$$

where $[T_{mn}]$ is the transformation matrix

Substituting Equation (2) in Equation (1) we have

$$[l'_{mn}] [d_n] = [g_m] \quad (3)$$

where $[l'_{mn}] = [l_{mn}] [T_{mn}]$

Now in the expansion of Equation (2)

$$[d_n] = d_1[f'_1] + d_2[f'_2] + \dots + d_K[f'_K] + \dots + d_L[f'_L]$$

Often one usually finds that $[d_n]$ is quite well approximated by retaining only the first K terms (assuming proper ordering of the $[d_n]$ matrix elements) and in fact it is not unusual to obtain sufficient accuracy with $K < \frac{L}{10}$.

When this approximation is done Equation (3) becomes

$$[l'_{mn}]_a [d_n]_a = [g_m] \quad (4)$$

where $[l'_{mn}]_a$, $[d_n]_a$, $[g_m]$ are of orders $L \times K$, $K \times 1$, $L \times 1$

respectively. Multiplying both sides by the conjugate transpose of matrix $[l'_{mn}]_a$, $[l'_{mn}]_a^T$, we get the reduced matrix Equation

$$[l''_{mn}] [d_n] = [g''_m] \quad (5)$$

where $[l''_{mn}]$, $[d_n]$, $[g''_m]$ are of orders $K \times K$, $K \times 1$, $K \times 1$ respectively.

It is reasonable to expect that going in for a suitably changed basis vectors and solving equation (3) instead of equation (1) will improve the accuracy of the solution or computer time saving.

For extending this one dimensional approach to 3-dimensional cases we proceed as follows:-

of

Instead/using a scalar element in the one-dimensional case we use a scalar submatrix. Thus instead of Equations (1), (1a) we write:

$$[(I_{mn})] [(A_n)] = [(G_m)]$$

where submatrices $(I_{mn}), (A_n), (G_m)$ are of orders $3 \times 3, 3 \times 1, 3 \times 1$ respectively.

$$[(A_n)] = \begin{bmatrix} (I) \\ (0) \\ (0) \end{bmatrix} (\lambda_1) + \begin{bmatrix} (0) \\ (I) \\ (0) \end{bmatrix} (\lambda_2) + \dots = [f_1](\lambda_1) + [f_2](\lambda_2) + \dots \quad (1a)$$

wherein $(I) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$, $(0) = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$, $(\lambda_1) = \begin{pmatrix} \lambda_1^1 \\ \lambda_1^2 \\ \lambda_1^3 \end{pmatrix}$, $(\lambda_2) = \begin{pmatrix} \lambda_2^1 \\ \lambda_2^2 \\ \lambda_2^3 \end{pmatrix}$
and superscripts 1, 2, 3 imply $\bar{x}, \bar{y}, \bar{z}$ direction components respectively.

Similarly Equations (2), and (2-a) may be written as:-

$$\begin{aligned} [(A_n)] &= [f'_1](\lambda'_1) + [f'_2](\lambda'_2) + \dots \\ &= \begin{bmatrix} \cos \frac{\pi l_1}{L} (I) \\ \cos \frac{\pi l_2}{L} (I) \end{bmatrix} (\lambda'_1) + \begin{bmatrix} \cos \frac{2\pi l_1}{L} (I) \\ \cos \frac{2\pi l_2}{L} (I) \end{bmatrix} (\lambda'_2) \end{aligned} \quad (2')$$

wherein also

wherein $\cos \frac{\pi l_1}{L} (I) = \begin{pmatrix} \cos \frac{\pi l_1}{L} & 0 & 0 \\ 0 & \cos \frac{\pi l_1}{L} & 0 \\ 0 & 0 & \cos \frac{\pi l_1}{L} \end{pmatrix}$, $\cos \frac{\pi l_2}{L} (I) = \begin{pmatrix} \cos \frac{\pi l_2}{L} & 0 & 0 \\ 0 & \cos \frac{\pi l_2}{L} & 0 \\ 0 & 0 & \cos \frac{\pi l_2}{L} \end{pmatrix}$,
and $(\lambda'_1) = \begin{pmatrix} \lambda'_1^1 \\ \lambda'_1^2 \\ \lambda'_1^3 \end{pmatrix}$, $(\lambda'_2) = \begin{pmatrix} \lambda'_2^1 \\ \lambda'_2^2 \\ \lambda'_2^3 \end{pmatrix}$, and $[(T_{mn})] = \begin{bmatrix} \cos \frac{\pi l_1}{L} (I) & \cos \frac{2\pi l_1}{L} (I) & \dots \\ \cos \frac{\pi l_2}{L} (I) & \cos \frac{2\pi l_2}{L} (I) & \dots \end{bmatrix} \quad (2'a)$
where (λ'_n) , (T_{mn}) are of orders $3 \times 1, 3 \times 3$ respectively.

Thus this three-dimensional approach may be usefully applied to Equation (1a) and may result in either computer time saving or improving the accuracy of the pulse function basis solution in a manner outlined for the 1-dimensional case.

Chapter - VI.

C o n c l u s i o n

The development of the dominant mode equivalent circuit parameters for a three-dimensional dielectric obstacle inside a rectangular waveguide involves solution of an integral equation containing suitable dyadic Green's function. The point-matching moment method has been used for finding the secondary volume current density produced at the centres of small rectangularly shaped cells formed by subdividing the dielectric obstacle. Subsequently these secondary volume current density values are used to obtain the dominant mode equivalent circuit parameters.

The various steps of this investigation, the difficulties encountered and the ways they were dealt with are discussed below.

The first step is the formulation of the problem (Chap.I). The formulation was done starting from Maxwell's curl equation and utilizing dyadic Green's function developed by Y.R.Sami[6]. The main task in formulating the problem was conversion of the two-region scattering problem into two one-region scattering problems, by utilizing the linearity property of Maxwell's curl equations. Y.R.Sami's derivation of the relevant dyadic Green's function has been analyzed in details and following the suggestion of R.E.Collin [12] a modified way of deriving the relevant dyadic Green's function has been presented.

The second step is the solution of the formulated equation to find the secondary volume current density values in the dielectric obstacle(Ch.II). In this ^{the} work/point-matching

moment method. Using a set of pulse function type subsectional basis vectors spanning the domain of the integral operator over the subsections of the obstacle region has been used. These subsections were chosen to be rectangularly sided parallel to pipe and have been termed "Cells" by J.J.H.Wang [7]. This was done in order to reduce the computational difficulty especially the numerical integration process involved in the moment method. The procedure of solution as outlined by J.J.H.Wang [7] has been followed and computational formulas have been derived for the matrix elements resulting from the application of the point-matching moment method. These elements involve double infinite series.

An alternative method

of dealing with such double infinite series utilizing Laplace transforms as suggested by A.D.Wheelon [11] and ~~utilizing Fourier transforms as suggested by R.E.Collin [8]~~ has been presented.

The third step is the derivation of the formulas for the TE_{10} mode equivalent circuit parameters (Ch.III). Following the procedure of R.E.Collin [12 & 8] expressions for TE_{10} scattered field radiated by the secondary current in the obstacle were derived these expressions along with the incident field expression were used in deriving the two-part equivalent circuit parameter expressions.

An illustrative example showing the various steps of solution has been presented (Ch.IV). A digital Computer program in Fortran-IV Language has been developed using the techniques suggested by S.S.Kuo [14] and Organik [15]. The results of the program indicate quite rapid convergence in the double infinite series summation with some 20x20 terms per series and also

indicate that an equivalent current parameter for the problem in this illustrative example has negative resistive part. The physical interpretation of this is that the fundamental mode contribute power to other modes. In this context the following remark made by R.E.Collin [8] in connection with explaining the thick iris discontinuity problem in a waveguide is noteworthy:- "A single evanscent mode cannot propagate real power but the combination of nonpropagating modes which decay in opposite directions does lead to a transfer of power. Thus the occurrence of the negative resistance may be attributed to the presence of a number of evanenscent modes decaying in opposite directions out of the infinite number of evanescent medes existent with the propagating mode.

Following the approach discussed by R.Mittma et al [16] a modified moment method has been developed for the three-dimensional di-electric obstacle problem. The method involves a transformation matrix manipulation in the process of solving for the secondary current values by the application of point matching method. The method has the possibility of either reducing the computer time or improving the accuracy of the solution. Further investigation with this method is worth consideration.

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